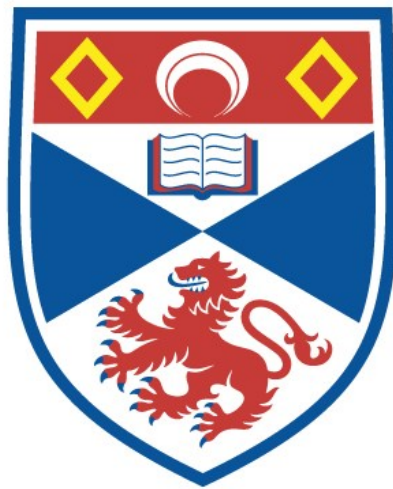


# University of St Andrews



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A DETERMINATION OF THE ORBIT OF THE

ASTEROID 522 HELGA

by

DIMITRIOS N. PAPADAKOS

A Thesis presented for the Degree of Master of Science  
in the University of St Andrews

May 1977



TO MY PARENTS

ΝΙΚΟΛΑΟΣ - ΕΤΤΧΙΑ

TO MY SUPERVISOR

TADEUSZ

Εἰ πρῶτον μή εὐτυχῆσω, αὖθις αὖ πάλιν πειρᾶσαι.  
PLATO

#### DECLARATION

I hereby declare that the following Thesis is the result of work carried out by me, that the Thesis is my own composition, and that it has not previously been presented for a Higher Degree. The research was carried out at the University Observatory, St Andrews.

D. N. Papadakos



CERTIFICATE

I hereby certify that Dimitrios N. Papadakos has spent seven terms at research work in the University Observatory, St Andrews, that he has fulfilled the conditions of Ordinance No. 51 (St Andrews) and that he is qualified to submit the accompanying Thesis in application for the Degree of Master of Science.

T. B. Slebarski

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## C O N T E N T S

	<u>Page</u>
Chapter 1 .. .. .	1
Chapter 2 .. .. .	14
Chapter 3 .. .. .	30
Chapter 4 .. .. .	78
Appendix A-1 .. .. .	127
Appendix A-2 .. .. .	131

## INTRODUCTION

There are two principal themes of this work.

Firstly, the application of the Gaussian and Laplacian methods to determine the preliminary orbit of the minor planet 522 Helga.

Secondly, the application of the power series method to find:

(i) The velocity vectors of the planets of the Solar System at a given time.

(ii) The determination of the real paths of these planets and hence the path of the minor planet 522 Helga.

By applying the latter method we are able to determine the mass of the minor planet ( $1.10^{-13}$  solar masses) and to construct its ephemeris.

The calculations were carried out by using computer and all programs are available.

The photographic plates used in this work were taken with the James Gregory Telescope at the University Observatory (St Andrews) during the observing season of 1971-72.

Chapter 1  
Gaussian Method

The solution of the problem of the relative motion of two bodies, which can be regarded as particles, contains six arbitrary constants of integration. They are:

$h_x, h_y, h_z$  - components of angular momentum in a given rectangular system of reference.

$C$  - energy constant.

$\omega$  - orientation of the major axis of the orbit

$T$  - time when the bodies are at the least distance from each other.

In problems related to planets and comets it is more convenient to use six elements, which are independent functions of the constants of integration. They are:

$e$  - eccentricity of the orbit.

$\alpha$  - semi-major axis of the orbit.

$M_0$  - mean anomaly of a planet at a chosen epoch  $t_0$ .

$\omega$  - argument of perihelion (orientation of the major axis).

$i$  - inclination of the orbit.

$Q$  - longitude of ascensional node.

Of course, the choice of the above orbital elements is not unique. It is possible to replace this set by another.

The reduction of a set of observed topocentric co-ordinates  $\alpha_i, \delta_i$  ( $i=1, 2, 3$ ) of a minor planet to obtain its orbital elements consists the problem of the initial determination of the orbit of the minor planet. Such a solution gives a satisfactory representation of the real motion during a relatively short interval of time, as long as it is possible to neglect the action of the other planets. Therefore, the

observations must be separated by short intervals of time.

Let  $\underline{r}_i \equiv (r_{xi}, r_{yi}, r_{zi})$  ( $i=1,2,3$ ) be the heliocentric radius vectors of the minor planet at three instants  $t_i$  ( $i=1,2,3$ ). Similarly, let  $\underline{R}_i \equiv (R_{xi}, R_{yi}, R_{zi})$  and  $\underline{\rho}_i \equiv (\rho_{xi}, \rho_{yi}, \rho_{zi})$  be the topocentric radius vectors of the Sun and the minor planet respectively at the same instants. Since the orbit in Keplerian mechanics, neglecting the action of the other planets, is a plane passing through the origin of the heliocentric co-ordinates we can write:

$$\underline{r}_2 = C_1 \underline{r}_1 + C_3 \underline{r}_3, \quad (1.1)$$

which states that the three position vectors  $\underline{r}_1, \underline{r}_2, \underline{r}_3$  are dependent, so the position vector  $\underline{r}_2$  at any time  $t_2$ , is some linear combination of the radius vectors at  $t_1$  and  $t_3$ . The equation (1.1) gives

$$(\underline{r}_2 \times \underline{r}_3) = C_1 (\underline{r}_1 \times \underline{r}_3), \quad (\underline{r}_1 \times \underline{r}_2) = C_3 (\underline{r}_1 \times \underline{r}_3). \quad (1.2)$$

Hence

$$C_1 = \frac{[\underline{r}_2, \underline{r}_3]}{[\underline{r}_1, \underline{r}_3]}, \quad C_3 = \frac{[\underline{r}_1, \underline{r}_2]}{[\underline{r}_1, \underline{r}_3]},$$

where, in general,  $[\underline{r}_i, \underline{r}_j]$  ( $i, j=1, 2, 3$   $i \neq j$ ) stands for the area of the triangle formed by  $\underline{r}_i$  and  $\underline{r}_j$ . C's are known as the "triangle ratios".

The vectors  $\underline{r}_i, \underline{R}_i, \underline{\rho}_i$  defined above, are related by

$$\underline{r}_i = \underline{\rho}_i - \underline{R}_i \quad (i=1,2,3). \quad (1.3)$$

Combining the expressions (1.1) and (1.3) we obtain

$$C_1 \underline{\rho}_1 - \underline{\rho}_2 + C_3 \underline{\rho}_3 = C_1 \underline{R}_1 - \underline{R}_2 + C_3 \underline{R}_3, \quad (1.4)$$

which is one of the fundamental equations of the Gaussian method.

Operating upon both sides of the equation (1.4) by  $(\hat{\rho}_1 \times \hat{\rho}_3)$ ,

where  $\hat{\rho}_i = \underline{\rho}_i / |\underline{\rho}_i|$  ( $i=1,2,3$ ), we get

$$-\rho_2 \hat{\rho}_2 \cdot (\hat{\rho}_1 \times \hat{\rho}_3) = C_1 \underline{R}_1 \cdot (\hat{\rho}_1 \times \hat{\rho}_3) - \underline{R}_2 \cdot (\hat{\rho}_1 \times \hat{\rho}_3) + C_3 \underline{R}_3 \cdot (\hat{\rho}_1 \times \hat{\rho}_3). \quad (1.5)$$

Since the  $\hat{\rho}_i = (\cos \delta_i \cos \alpha_i, \cos \delta_i \sin \alpha_i, \sin \delta_i)$  and  $\underline{R}_i$  ( $i=1,2,3$ ) are known, the

equation (1.5) reduces to an equation of the form

$$W_1 \rho = W_2 C_1 + W_3 + W_4 C_3 \quad (1.6)$$

Consider now the triangle formed by the Sun, the observer and the planet at  $t_2$ . This has sides of length  $r_2$ ,  $R_2$  and  $\rho_2$  and thus, we can write

$$r_2^2 = \rho_2^2 - 2 \rho_2 \hat{\rho}_2 \cdot R_2 + R_2^2, \quad (1.7)$$

which, since  $\hat{\rho}_2$  and  $R_2$  are known, is an equation of the form

$$r_2^2 = \rho_2^2 + W_{11} \rho_2 + W_{12} \quad (1.8)$$

The first step in the computation is to calculate the coefficients  $W_1, W_2, W_3, W_4, W_{11}$  and  $W_{12}$  using the topocentric direction cosines of the planet, obtained from its observed topocentric co-ordinates  $\alpha_i, \delta_i$  ( $i=1,2,3$ ), and the topocentric rectangular co-ordinates, obtained from the geocentric tables, corrected for parallax and reduced to the place of observations by introduction of appropriate corrections.

We can now proceed to obtain first approximations to the  $\tilde{r}_i$  ( $i=1,2,3$ ). In order to do this we require to know  $C_1$  and  $C_3$ . From the expansions of the co-ordinates of the body in convergent Taylor's series we get

$$C_1 = \frac{\tau_1}{\tau_2} \left[ 1 + \frac{(\tau_2^2 - \tau_1^2)}{6 \tau_2^3} + \frac{\tau_3 (\tau_2 \tau_3 - \tau_1^2)}{4 \tau_2^4} \left( \frac{d\tau}{d\tau} \right)_{t=t_2} + \dots \right], \quad (1.9)$$

and

$$C_3 = \frac{\tau_3}{\tau_2} \left[ 1 + \frac{(\tau_2^2 - \tau_3^2)}{6 \tau_2^3} + \frac{\tau_1 (\tau_2 \tau_1 - \tau_3^2)}{4 \tau_2^4} \left( \frac{d\tau}{d\tau} \right)_{t=t_2} + \dots \right],$$

where  $\tau_1 = k \cdot (t_3 - t_2)$ ,  $\tau_2 = k \cdot (t_3 - t_1)$ ,  $\tau_3 = k \cdot (t_2 - t_1)$  are the modified times, and  $k$  is the Gaussian constant. Since terms with  $\left( \frac{d\tau}{d\tau} \right)_{t=t_2}$

are unknown, in the first approximation we have to neglect them. Thus we shall set

$$C_1 = \frac{\tau_1}{\tau_2} \left[ 1 + \frac{\tau_2^2 - \tau_1^2}{6 \tau_2^3} \right], \quad C_3 = \frac{\tau_3}{\tau_2} \left[ 1 + \frac{\tau_2^2 - \tau_3^2}{6 \tau_2^3} \right] \quad (1.10)$$

Clearly, since  $\tau_1, \tau_2$  and  $\tau_3$  are known, the elimination of  $C_1$  and  $C_3$  in equation (1.6) by substitution of the above expressions (1.10) will result in an equation of the form

$$\rho_2 = w_9 + w_{10} r_2^{-3} \quad (1.11)$$

It is obvious that we can obtain values for  $\rho_2$  and  $r_2$  by simultaneous solution of the equations (1.11) and (1.8). This is accomplished by means of successive approximations. We can take  $r_2 = 2.8$  A.U. as first approximation since this is the mean distance of the minor planets from the Sun. This value is used in equation (1.11) to obtain a value of  $\rho_2$  which is then inserted into equation (1.8) to obtain a second approximation of  $r_2$ . The obtained value of  $r_2$  is substituted into equation (1.11) and the process is continued until successive approximations of  $\rho_2$  and  $r_2$  are identical to the required accuracy.

Since equations (1.10) are nothing more than preliminary estimates of the triangle ratios  $C_1$  and  $C_3$ , the  $r_2$  and  $\rho_2$  obtained by the solution of the equations (1.8) and (1.11) are only approximate. It should be noted that the coefficients  $w_{11}$  and  $w_{12}$  in equation (1.8) are exact and they do not change in the subsequent computation of  $r_i$  ( $i=1,2,3$ ).

The next step in the reduction is to use the value of  $r_2$  to obtain first approximations for  $C_1$  and  $C_3$  by means of the expressions (1.10). After these unknowns are determined, we may return to the fundamental equation (1.4) to obtain  $\rho_1$  and  $\rho_3$ . The equation is used in the form

$$\begin{aligned} C_1 \left| \hat{\rho}_{x1} \right| \rho_1 + C_3 \left| \hat{\rho}_{x3} \right| \rho_3 &= C_1 R_{x1} - R_{x2} + C_3 R_{x3} + \left| \hat{\rho}_{x2} \right| \rho_2 \\ C_1 \left| \hat{\rho}_{y1} \right| \rho_1 + C_3 \left| \hat{\rho}_{y3} \right| \rho_3 &= C_1 R_{y1} - R_{y2} + C_3 R_{y3} + \left| \hat{\rho}_{y2} \right| \rho_2 \\ C_1 \left| \hat{\rho}_{z1} \right| \rho_1 + C_3 \left| \hat{\rho}_{z3} \right| \rho_3 &= C_1 R_{z1} - R_{z2} + C_3 R_{z3} + \left| \hat{\rho}_{z2} \right| \rho_2 \end{aligned} \quad (1.12)$$

where  $\left| \hat{\rho}_{xi} \right| = \cos \delta_i \cos \alpha_i$ ,  $\left| \hat{\rho}_{yi} \right| = \cos \delta_i \sin \alpha_i$  and  $\left| \hat{\rho}_{zi} \right| = \sin \delta_i$  ( $i=1,2,3$ ).

The expressions (1.12) contain two unknowns,  $\rho_1$  and  $\rho_3$ , therefore we require two of these component equations to obtain a solution. The third equation is used to provide a numerical check on the values of  $\rho_1$  and  $\rho_3$ .



This is generally unnecessary when a computer is used for the reduction.

Our observations are all exactly satisfied since our values of the  $\rho_1$ ,  $\rho_2$  and  $\rho_3$  have been derived directly from the equations which express the geometrical conditions. Our  $C$ 's however, were obtained from approximate formulas and therefore there is no guarantee that the motion of the minor planet is in strict accordance with the law of gravitation.

With the  $\rho$ 's we now have, we may obtain the corresponding  $\gamma$ 's by means of the equation

$$\gamma_i = \rho_i \hat{\rho}_i - R_i \quad (i=1,2,3). \quad (1.13)$$

In the second approximation, knowing  $\rho_1$ ,  $\rho_2$  and  $\rho_3$ , we are able to take into consideration the neglected influence of planetary aberration on the moments of observations. The corrected moments will be

$$t_i^o = t_i^* - A \rho_i \quad (i=1,2,3). \quad (1.14)$$

It is necessary to substitute them in place of the initial  $t_i$  in the calculation of the formulas.  $t_i^o$  is the moment when the light ray observed by us left the celestial body,  $t_i^*$  is the ephemeris time of observation and  $A$  is the light time for unit distance (time during which light travels one astronomical unit). To evaluate  $t_i^*$  we use the formula

$$t_i^* = t_i + \Delta T \quad (i=1,2,3), \quad (1.15)$$

where  $t_i$  is the moment of observation indicated in U.T. and  $\Delta T$  the correction to U.T. to obtain the ephemeris time. The equation (1.14) by introduction of the equation (1.15) becomes

$$t_i^o = t_i + \Delta T - A \rho_i \quad (i=1,2,3). \quad (1.16)$$

More accurate expressions for  $C_1$  and  $C_3$  was given by Gibbs.

They are

$$C_1 = \frac{r_1}{r_2} \cdot \frac{1 + B_1 r_1^{-3}}{1 - B_2 r_2^{-3}}, \quad C_3 = \frac{r_3}{r_2} \cdot \frac{1 + B_3 r_3^{-3}}{1 - B_2 r_2^{-3}}, \quad (1.17)$$

where  $B_1 = (\tau_3^2 + \tau_1 \tau_3 - \tau_1^2)/12$ ,  $B_2 = (\tau_1^2 + 3\tau_1 \tau_3 + \tau_3^2)/12$ ,  $B_3 = (\tau_1^2 + \tau_1 \tau_3 - \tau_3^2)/12$

$$\text{and } \tau_1 = k(t_3^\circ - t_2^\circ), \quad \tau_2 = k(t_3^\circ - t_1^\circ), \quad \tau_3 = k(t_2^\circ - t_1^\circ).$$

Taking into account only the first two terms of the series expansions (1.9) for  $C^j_s$ , we have

$$C_1 = \frac{\tau_1}{\tau_2} + \frac{\nu_1}{\tau_2^3}, \quad C_3 = \frac{\tau_3}{\tau_2} + \frac{\nu_3}{\tau_2^3}, \quad (1.18)$$

where

$$\nu_1 = \frac{\tau_1}{\tau_2} \frac{\tau_2^2 - \tau_1^2}{6}, \quad \nu_3 = \frac{\tau_3}{\tau_2} \frac{\tau_2^2 - \tau_3^2}{6}.$$

The equations (1.18) give

$$\nu_1 = \left(C_1 - \frac{\tau_1}{\tau_2}\right) \tau_2^3, \quad \nu_3 = \left(C_3 - \frac{\tau_3}{\tau_2}\right) \tau_2^3. \quad (1.19)$$

Using the found value of  $\tau_2$  from the previous approximation and the values of  $C_1$  and  $C_3$  evaluated from the Gibbs formulae (1.17), we compute the values of  $\nu^j_s$ . Substitution of these equations into equations (1.18) gives

$$C_1 = W_5 + W_6 \tau_2^{-3}, \quad C_3 = W_7 + W_8 \tau_2^{-3}, \quad (1.20)$$

where  $W_5 = \tau_1 / \tau_2$ ,  $W_6 = \nu_1$ ,  $W_7 = \tau_3 / \tau_2$ ,  $W_8 = \nu_3$  are known. The equation (1.6) by introduction of the equations (1.20) takes the form

$$\rho_2 = W_9 + W_{10} \tau_2^{-3}. \quad (1.21)$$

The equations (1.8) and (1.21) are now solved for  $\tau_2$  and  $\rho_2$ .

The value of  $\tau_2$  obtained in the previous approximation, is taken as the initial value of the iteration. The values of  $C_1$  and  $C_3$  are determined using (1.20), and the new values of  $\rho_1$  and  $\rho_3$  are obtained from the equations (1.12). Then the vectors  $\underline{f}_i$  ( $i=1,2,3$ ) are determined by means

of

$$\tilde{r}_i = \rho_i \hat{\rho}_i - R_i \quad (i=1,2,3) .$$

This process must be repeated by exactly the same method until the values of  $C$ 's and  $\tilde{r}$ 's no longer change. The convergence is, in general, very rapid. This is due to the fact that  $C$ 's are relatively insensitive to the  $\tilde{r}$ 's. The large change in  $\tilde{r}$ 's, in going from one approximation to the next, will not produce a correspondingly large change in  $C$ 's. Hence the next solution for the  $\rho$ 's will not differ greatly from the preceding one. As a rule, no more than four approximations lead to the final values of  $\tilde{r}_i$  ( $i=1,2,3$ ) .

The next stage in the computation is the determination of the ratio of the area of the sector to that of the triangle in the orbit. This important concept is fundamental to the Gaussian method and its determination forms an intermediate stage between the calculation of the  $\tilde{r}_i$  ( $i=1,2,3$ ) and the evaluation of the orbital elements. It is possible to obtain the ratio of the area of the sector to the area of the triangle from two heliocentric positions of the body and the interval of time during which the body passed from the first position to the second.

Let  $\tilde{r}_i, \tilde{r}_j$  be the heliocentric distances of the planet at two instants  $t_i, t_j$  respectively, and  $E_i, E_j$  the corresponding eccentric anomalies. Also let  $t_j > t_i$  .

The "sector-triangle ratio",  $\tilde{y}_k$ , satisfies the Gauss equations

$$\tilde{y}_k^2 = \frac{m_k^2}{l_k + \sin^2(g_k/2)} , \quad \tilde{y}_k^3 - \tilde{y}_k^2 = \frac{m_k^2(2g_k - \sin 2g_k)}{\sin^3 g_k} , \quad (1.22)$$

where

$$m_k^2 = \frac{\tau_k^2}{2\sqrt{2}K_k^3} , \quad l_k = \frac{\tilde{r}_i + \tilde{r}_j}{2\sqrt{2}K_k} - \frac{1}{2} ,$$

$$K_k^2 = \tilde{r}_i \tilde{r}_j + \tilde{r}_i \cdot \tilde{r}_j , \quad 2g_k = E_j - E_i , \quad \tau_k = k(t_j - t_i) .$$

The equations (1.22) contain two unknowns  $\tilde{y}_k$  and  $g_k$ . Since it is not possible to eliminate the later, one has to use a method of successive approximations to obtain  $\tilde{y}_k$ . In the determination of a preliminary orbit, the difference in eccentric anomalies is usually a small quantity. Then, using expansion in series, Gauss derived the equation

$$\tilde{y}_k^3 - \tilde{y}_k^2 - h_k \tilde{y}_k - \frac{1}{9} h_k = 0, \quad (1.23)$$

where

$$h_k = \frac{m_k^2}{5/6 + l_k + \xi_k}, \quad \xi_k = \frac{2}{35} \chi_k^2 + \frac{52}{1575} \chi_k^3 + \dots, \quad (1.24)$$

$$\chi_k = \frac{m_k^2}{y_k^2} - l_k = \sin^2(g_k/2).$$

The cubic equation (1.23) has only one positive root, which, for small values of  $h_k$ , can be obtained using Hansen's approximate formula

$$\tilde{y}_k = 1 + \frac{\frac{10}{9} h_k}{1 + \frac{\frac{11}{9} h_k}{1 + \frac{\frac{11}{9} h_k}{1 + \dots}}} = 1 + \frac{\frac{10}{11} \frac{\frac{11}{9} h_k}{1 + \frac{\frac{11}{9} h_k}{1 + \frac{\frac{11}{9} h_k}{1 + \dots}}}}{\frac{11}{9} h_k} \quad (1.25)$$

The procedure for determining  $\tilde{y}_i$  ( $i=1,2,3$ ) for the three observations is as follows: firstly, using the final values of the  $\tilde{r}_i$  ( $i=1,2,3$ ) obtained in the previous section of the work, we calculate the  $K_i$  ( $i=1,2,3$ )

$$\begin{aligned} K_1^2 &= \tilde{r}_2 \tilde{r}_3 + \tilde{r}_2 \cdot \tilde{r}_3, \\ K_2^2 &= \tilde{r}_1 \tilde{r}_3 + \tilde{r}_1 \cdot \tilde{r}_3, \\ K_3^2 &= \tilde{r}_2 \tilde{r}_1 + \tilde{r}_2 \cdot \tilde{r}_1. \end{aligned} \quad (1.26)$$

We next compute the  $m_i^2$  and  $l_i$  ( $i=1,2,3$ ) using the equations (1.22).

That is

$$m_i^2 = \frac{\tau_i^2}{2\sqrt{2} k_i^3} \quad , \quad l_i = \frac{r_k + r_j}{2\sqrt{2} k_i} - \frac{1}{2} \quad (i,j,k=1,2,3 \quad i \neq j \neq k),$$

where  $\tau_i$  ( $i=1,2,3$ ) are the final values, corrected for light time, obtained in the previous section.

The first approximations for the  $h_i$  ( $i=1,2,3$ ) are obtained by neglecting the  $\xi_i$  ( $i=1,2,3$ )

$$h_i = \frac{m_i^2}{5/6 + l_i} \quad (i=1,2,3).$$

These values are substituted in the equation (1.25) to obtain the first approximations to the  $\tilde{y}_i$  ( $i=1,2,3$ ). These are then used to compute  $x_i$  and  $\xi_i$  from (1.24).

Now, the second approximation to  $h_i$  ( $i=1,2,3$ ) is determined with the help of the first of the equations (1.24). Second approximation to  $\tilde{y}_i$  ( $i=1,2,3$ ) is then derived, and the process is repeated until the successive values of the  $h_i$  and  $\tilde{y}_i$  ( $i=1,2,3$ ) agree sufficiently well.

By definition

$$\tilde{y}_k = \frac{(r_i, r_j)}{[r_i, r_j]} \quad i,j,k=1,2,3 \quad i \neq j \neq k, \quad (1.27)$$

where  $(r_i, r_j)$  represents the area of the sector of the ellipse contained between the two radius vectors  $\underline{r}_i$  and  $\underline{r}_j$ . With the help of the equations (1.27) and (1.2) we easily obtain

$$C_1 = \frac{(r_2, r_3) \tilde{y}_2}{(r_1, r_3) \tilde{y}_1} \quad , \quad C_3 = \frac{(r_1, r_2) \tilde{y}_2}{(r_1, r_3) \tilde{y}_3}.$$

From the Kepler's laws it follows that the areas of the sectors are proportional to the intervals of time between observations. Hence

$$C_1 = \frac{\tau_1 \tilde{y}_2}{\tau_2 \tilde{y}_1} \quad , \quad C_3 = \frac{\tau_3 \tilde{y}_2}{\tau_2 \tilde{y}_3}.$$

We use these equations as a check on the values obtained for  $\tilde{y}_i$  ( $i=1,2,3$ ). The values of  $C$ 's obtained from these expressions are compared with the values obtained in the final approximation to the  $\tilde{r}_i$  ( $i=1,2,3$ ). There should be good agreement between the two sets of values if the accuracy has been maintained.

We now have values of  $\tilde{r}_i$ ,  $\tau_i$  and  $y_i$  ( $i=1,2,3$ ) and can thus proceed to the computation of the orbital elements.

We notice that, in the numerical applications, we shall use dimensionless quantities. Therefore, the following units of time, mass and distance will be employed. The mass of the Sun will be taken as the unit of mass, the astronomical unit as the unit of distance, and  $1/k$  mean solar days as the unit of time.

Considering the mass of the asteroid negligible in comparison with the mass of the Sun, the "sector-triangle ratios"  $\tilde{y}_1, \tilde{y}_2$  and  $\tilde{y}_3$  are given by

$$\tilde{y}_1 = \frac{\tau_1 \sqrt{P}}{r_2 r_3 \sin(U_3 - U_2)}, \quad \tilde{y}_2 = \frac{\tau_2 \sqrt{P}}{r_1 r_3 \sin(U_3 - U_1)}, \quad \tilde{y}_3 = \frac{\tau_3 \sqrt{P}}{r_2 r_1 \sin(U_2 - U_1)},$$

where  $U_1, U_2$  and  $U_3$  are the true anomalies of the minor planet at the instants  $t_1, t_2$  and  $t_3$  respectively. From these equations we obtain the parameter of the orbit  $P$  as

$$P = \frac{(r_1 r_3)^2 \sin^2(U_3 - U_1) \tilde{y}_2^2}{\tau_2^2} = \frac{(r_2 r_3)^2 \sin^2(U_3 - U_2) \tilde{y}_1^2}{\tau_1^2} = \frac{(r_1 r_2)^2 \sin^2(U_2 - U_1) \tilde{y}_3^2}{\tau_3^2}.$$

In order to determine  $P$ , it is sufficient to make use of the first of these equations, which gives the greatest accuracy, because its numerator and denominator are larger than those in the two following equations. In

practice we proceed as follows: Let us set

$$\sigma = \frac{\tilde{r}_1 \cdot \tilde{r}_3}{\tilde{r}_1^2} = \frac{\tilde{r}_{x1} \tilde{r}_{x3} + \tilde{r}_{y1} \tilde{r}_{y3} + \tilde{r}_{z1} \tilde{r}_{z3}}{\tilde{r}_1^2} = \frac{\tilde{r}_3 \cos(\nu_3 - \nu_1)}{\tilde{r}_1} ,$$

and let us introduce the notation

$$\tilde{r}_0 = \tilde{r}_3 - \sigma \tilde{r}_1 .$$

It follows that

$$\tilde{r}_0^2 = \tilde{r}_3^2 - \sigma^2 \tilde{r}_1^2 = \tilde{r}_3^2 \sin^2(\nu_3 - \nu_1) ,$$

and

$$\tilde{r}_1 \tilde{r}_3 \sin(\nu_3 - \nu_1) = \tilde{r}_1 \tilde{r}_0 .$$

Hence

$$P = \frac{(\tilde{r}_1 \tilde{r}_0)^2}{\tilde{r}_2^2} \tilde{y}_2^2 . \quad (1.28)$$

For the determination of the true anomalies we use the relations

$$\tilde{r}_1 = \frac{P}{1 + e \cos \nu_1} , \quad \tilde{r}_3 = \frac{P}{1 + e \cos \nu_3} ,$$

which give

$$e \cos \nu_1 = \frac{P}{\tilde{r}_1} - 1 , \quad e \cos \nu_3 = \frac{P}{\tilde{r}_3} - 1 . \quad (1.29)$$

The last equation can be represented in the form

$$e \cos \nu_3 = e \cos(\nu_1 + (\nu_3 - \nu_1)) = e \cos \nu_1 \cos(\nu_3 - \nu_1) - e \sin \nu_1 \sin(\nu_3 - \nu_1) = \frac{P}{\tilde{r}_3} - 1 .$$

Whence

$$e \sin \nu_1 = \frac{\left(\frac{P}{\tilde{r}_1} - 1\right) \cos(\nu_3 - \nu_1) - \left(\frac{P}{\tilde{r}_3} - 1\right)}{\sin(\nu_3 - \nu_1)} . \quad (1.30)$$

Evaluating

$$\cos(\nu_3 - \nu_1) = \frac{\tilde{r}_1 \cdot \tilde{r}_3}{\tilde{r}_1 \tilde{r}_3} ,$$

$$\sin(\nu_3 - \nu_1) = \left(1 - \cos^2(\nu_3 - \nu_1)\right)^{\frac{1}{2}} , \quad (1.31)$$

the equations (1.29) and (1.30) permit us to find  $U_1$  and  $e$ .

With the help of the relations (1.31)

$$U_3 = U_1 + (U_3 - U_1)$$

is also obtained.

The semi-major axis  $\alpha$  and the mean daily motion  $n$  are directly obtained from

$$\alpha = P (1 - e^2)^{-1}, \quad n = k \alpha^{-3/2}.$$

For elliptical orbits we find the eccentric anomalies by the formulas

$$t \alpha n \frac{E_1}{2} = \sqrt{\frac{1-e}{1+e}} t \alpha n \frac{U_1}{2}, \quad t \alpha n \frac{E_3}{2} = \sqrt{\frac{1-e}{1+e}} t \alpha n \frac{U_3}{2},$$

and then we apply Kepler's equation giving the mean anomaly

$$M_i = E_i - e \sin E_i \quad (i=1,3).$$

The time of perihelion passage is computed by use of the formula

$$T = t_i^\circ - \frac{M_i}{n} \quad (i=1,3),$$

where  $t_i^\circ$  ( $i=1,3$ ) is the E.T. corrected for planetary aberration.

The element which normally replaces  $T$  in elliptical orbits is the mean anomaly  $M_0$  at some specific epoch  $t_0$ .  $M_0$  can be calculated from

$$M_0 = n(t_0 - T) \quad \text{or} \quad M_0 = M_i + n(t_0 - t_i) \quad (i=1,3),$$

where, again,  $t_i$  ( $i=1,3$ ) is the E.T. corrected for planetary aberration.

To find the remaining three elements  $\omega, i$  and  $\varrho$  we require a knowledge of the vectorial equatorial constants  $P_x, P_y, P_z, Q_x, Q_y, Q_z$  which are components, in the equatorial system, of the unit vectors  $\hat{P}$  and  $\hat{Q}$  directed along the major and minor axis of the orbit respectively.



The equations

$$\begin{aligned}\tilde{r}_1 &= \hat{P} \tilde{r}_1 \cos U_1 + \hat{Q} \tilde{r}_1 \sin U_1, \\ \tilde{r}_3 &= \hat{P} \tilde{r}_3 \cos U_3 + \hat{Q} \tilde{r}_3 \sin U_3,\end{aligned}$$

give us

$$\hat{P} = \frac{\tilde{r}_1 \tilde{r}_3 \sin U_3 - \tilde{r}_3 \tilde{r}_1 \sin U_1}{\tilde{r}_1 \tilde{r}_3 \sin (U_3 - U_1)},$$

$$\hat{Q} = \frac{\tilde{r}_3 \tilde{r}_1 \cos U_1 - \tilde{r}_1 \tilde{r}_3 \cos U_3}{\tilde{r}_1 \tilde{r}_3 \sin (U_3 - U_1)},$$

from which  $\hat{P}$  and  $\hat{Q}$  could be evaluated directly, but it is more convenient to proceed using the already defined vector  $\tilde{r}_0$ . Whence

$$\hat{P} = \frac{\cos U_1}{\tilde{r}_1} \tilde{r}_1 - \frac{\sin U_1}{\tilde{r}_0} \tilde{r}_0,$$

$$\hat{Q} = \frac{\sin U_1}{\tilde{r}_1} \tilde{r}_1 - \frac{\cos U_1}{\tilde{r}_0} \tilde{r}_0.$$

The elements  $i$ ,  $\mathcal{Q}$  and  $\omega$  are referred to the ecliptic, therefore we have to rotate the co-ordinate system about  $X$ -axis through an angle  $\mathcal{E}$  equal to the mean obliquity of 1950.0. If the ecliptic vectorial constants are  $P'_x, P'_y, P'_z, Q'_x, Q'_y, Q'_z, R'_x, R'_y, R'_z$ , then

$$\begin{bmatrix} P'_x & P'_y & P'_z \\ Q'_x & Q'_y & Q'_z \\ R'_x & R'_y & R'_z \end{bmatrix} \begin{bmatrix} P_x & P_y & P_z \\ Q_x & Q_y & Q_z \\ R_x & R_y & R_z \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \mathcal{E} & -\sin \mathcal{E} \\ 0 & \sin \mathcal{E} & \cos \mathcal{E} \end{bmatrix}.$$

Alternatively,

$$\begin{aligned}\sin \omega \sin i &= P_z \cos \mathcal{E} - P_y \sin \mathcal{E}, \\ \cos \omega \sin i &= Q_z \cos \mathcal{E} - Q_y \sin \mathcal{E}, \\ \sin \mathcal{Q} &= (P_y \cos \omega - Q_y \sin \omega) \sec \mathcal{E}, \\ \cos \mathcal{Q} &= P_x \cos \omega - Q_x \sin \omega, \\ \cos i &= -(P_x \sin \omega + Q_x \cos \omega) \operatorname{cosec} \mathcal{Q}.\end{aligned}$$

From these equations we obtain  $\omega$ ,  $i$  and  $\mathcal{Q}$ . In the numerical applications we must take care that the found values of the angles are the values of the corresponding orbital elements, since the same value of trigonometric function corresponds to more than one angle.

Chapter 2  
Laplacian method

The problem of the determination of elements by Laplace's method can, briefly, be described as follows: From the known topocentric position vectors of the Sun  $\underline{R}_i$  ( $i=1,2,3$ ) at the instants  $t_1, t_2, t_3$  and the unit vectors  $\hat{\underline{p}}_i$  ( $i=1,2,3$ ) along the topocentric position vectors of the planet, we determine its heliocentric position and velocity vectors at the instant  $t = t_2$  in the rectangular ecliptic system of co-ordinates, and from these we find the elements of orbit.

Before we continue with the method we shall explain how we can determine the velocity vector of a planet at the instant  $t_0$ , given its two position vectors at  $t_1$  and  $t_2$  and the position vector at  $t_0$ , where  $t_1 < t_0 < t_2$ .

If the attraction of the other bodies are neglected, the acceleration of the planet relative to the Sun is given by

$$\ddot{\underline{r}} = -k^2(1+m)\frac{\underline{r}}{r^3}, \quad (2.1)$$

where  $k$  is the Gaussian constant and  $m$  the mass of the planet expressed in terms of the solar mass.

We define  $\tau$  by

$$\tau = k(t - t_0),$$

and introduce the following notation

$$\underline{r}' = \frac{d\underline{r}}{d\tau}, \quad \underline{r}'' = \frac{d^2\underline{r}}{d\tau^2}, \quad \underline{r}^{(\nu)} = \frac{d^\nu \underline{r}}{d\tau^\nu}, \quad \nu = 3, 4, \dots$$

The equation (2.1) becomes

$$\underline{r}'' = -(1+m)\frac{\underline{r}}{r^3}. \quad (2.2)$$

We write the solution of (2.2) in a Taylor's series

$$\underline{r} = \underline{r}_0 + \underline{r}_0' \tau + \underline{r}_0'' \frac{\tau^2}{2!} + \sum_{v=3}^{\infty} \underline{r}_0^{(v)} \frac{\tau^v}{v!} \quad (2.3)$$

where  $\underline{r}_0$  is the position vector at  $t=t_0$ , and the subscript 0 refers to the values for this position.

The differential equation (2.2) permits us to eliminate  $\underline{r}_0''$  in terms of  $\underline{r}_0$  and  $\underline{r}_0 = |\underline{r}_0|$ . Similarly, the higher derivatives in the equation (2.3) can be eliminated by successive differentiation of the equation (2.2). This process leads to an expression

$$\underline{r} = f \underline{r}_0 + g \underline{r}_0' \quad (2.4)$$

$$\text{where } f = \sum_{n=0}^{\infty} f_n \frac{\tau^n}{n!} \quad \text{and} \quad g = \sum_{n=0}^{\infty} g_n \frac{\tau^n}{n!}.$$

These power series in  $\tau$  are known as "f and g series".

The coefficients  $f_n$  and  $g_n$  are polynomials in  $\mu_0$ ,  $G_0$  and  $\xi_0$ , defined by

$$\mu_0 = \frac{(1+m)}{r_0^3}, \quad G_0 = \frac{r_0'}{r_0}, \quad \xi_0 = \frac{r_0'^2}{r_0^2} - \mu_0. \quad (2.5)$$

Lagrange was first to give explicit expressions for  $f_n$  and  $g_n$  up to  $n=5$ . The direct derivations for  $n > 5$  becomes very laborious. Cipoletti (1872) discovered two recursive formulae

$$\begin{aligned} f_n &= f_{n-1}' - (1/r_0^3) g_{n-1}, \\ g_n &= f_{n-1} - g_{n-1}' \end{aligned} \quad (2.6)$$

with initial values  $f_0 = 1$  and  $g_0 = 0$ . The tedious algebra involved in the evaluation of the formula (2.6) can be carried out by a computer. Sconzo (1965) obtained  $f_n$  and  $g_n$  on an IBM 7094 computer, up to  $n = 27$ .

In the present work the coefficients  $f_n$  and  $g_n$  up to  $12^{\text{th}}$  order will be used. The expressions for these are given in the table I.

Consider now two position vectors  $\underline{r}_1, \underline{r}_2$  at the instants  $\tau_1, \tau_2$ , respectively. Using the power series expansion (2.3) about the same epoch, approximately halfway between  $\tau_1$  and  $\tau_2$ , we obtain

$$\begin{aligned}\underline{r}_1 &= \underline{r}_0 + \underline{r}_0' \tau_1 + \underline{r}_0'' \frac{\tau_1^2}{2!} + \underline{r}_0^{(3)} \frac{\tau_1^3}{3!} + \dots \\ \underline{r}_2 &= \underline{r}_0 + \underline{r}_0' \tau_2 + \underline{r}_0'' \frac{\tau_2^2}{2!} + \underline{r}_0^{(3)} \frac{\tau_2^3}{3!} + \dots\end{aligned}$$

We eliminate  $\underline{r}_0''$  using the equation (2.2). Then

$$\begin{aligned}\underline{r}_1 &= Q_1 \underline{r}_0 + \underline{r}_0' \tau_1 + \underline{r}_0^{(3)} \frac{\tau_1^3}{3!} + \dots \\ \underline{r}_2 &= Q_2 \underline{r}_0 + \underline{r}_0' \tau_2 + \underline{r}_0^{(3)} \frac{\tau_2^3}{3!} + \dots\end{aligned}\tag{2.7}$$

where  $Q_1 = 1 - \frac{(1+m)\tau_1^2}{2\tau_0^3}$  and  $Q_2 = 1 - \frac{(1+m)\tau_2^2}{2\tau_0^3}$ .

Neglecting higher terms in the expansions (2.7), we obtain

$$\underline{r}_0' = \left[ (\underline{r}_1 - Q_1 \underline{r}_0) \tau_2^3 - (\underline{r}_2 - Q_2 \underline{r}_0) \tau_1^3 \right] / \tau_1 \tau_2 (\tau_2^2 - \tau_1^2).\tag{2.8}$$

Now, using the velocity vector  $\underline{r}_0'$  and the known position vector  $\underline{r}_0$  we evaluate a first approximation of  $\mu_0, \delta_0$  and  $\epsilon_0$ . Then, with the help of the table I, we calculate approximate values of the  $f$  and  $g$

series at the point  $T = T_1$ , say  $f_1$  and  $g_1$ . Since we have these values, we solve the equation (2.4) to obtain a better approximation of the velocity vector  $\underline{r}_0'$

$$\underline{r}_0' = \frac{1}{g_1} \underline{r}_1 - \frac{f_1}{g_1} \underline{r}_0 .$$

Repeating the same process, we can obtain the desirable accuracy for  $\underline{r}_0'$  which, of course, is confined because we truncated the  $f$  and  $g$  series.

We return now to the Laplacian method.

The geometrical conditions of the problem are expressed by the equation

$$\underline{r} = \rho \hat{\underline{p}} - \underline{R} , \quad (2.9)$$

where  $\underline{r} \equiv (x, y, z)$  is the heliocentric radius vector of the planet,  $\underline{R} \equiv (X, Y, Z)$  and  $\underline{p} \equiv (\xi, \eta, \zeta)$  are the topocentric position vectors of the Sun and the planet respectively with reference to the observer. The co-ordinates  $x, y, z, X, Y, Z, \xi, \eta, \zeta$  are the equatorial rectangular co-ordinates of the bodies.

We differentiate the equation (2.9) twice with respect to  $T$

$$\underline{r}' = \rho' \hat{\underline{p}} + \rho \hat{\underline{p}}' - \underline{R}' , \quad (2.10)$$

$$\underline{r}'' = \rho'' \hat{\underline{p}} + 2\rho' \hat{\underline{p}}' + \rho \hat{\underline{p}}'' - \underline{R}'' . \quad (2.11)$$

We now impose the dynamical condition that the Earth and the minor planet move around the Sun in accordance with the law of gravitation.

Neglecting the attraction of other planets, we have

$$\underline{R}'' = - \frac{1+m_e}{R^3} \underline{R} , \quad \underline{r}'' = - \frac{1+m}{r^3} \underline{r} ,$$

where  $m_e$  and  $m$  are the masses of the Earth and the minor planet. The quantities are expressed in astronomical units, solar masses and  $1/k$  mean solar days.

Neglecting the mass of minor planet, as very small compared with the mass of the Sun, the second equation becomes

$$\ddot{r} = -\frac{1}{r^3}(\rho \hat{r} - R).$$

We substitute the expressions for  $\ddot{R}$  and  $\ddot{r}$  into (2.11).

Then

$$-\frac{\rho}{r^3}\hat{r} + \left(\frac{1}{r^3} - \frac{1+m_e}{R^3}\right)R = \rho''\hat{r} + 2\rho'\hat{r}' + \rho\hat{r}''.$$

Multiplying both sides by  $\cdot(\hat{r} \times \hat{r}')$  and  $\cdot(\hat{r} \times \hat{r}'')$

we obtain

$$\left(\frac{1+m_e}{R^3} - \frac{1}{r^3}\right)D_1 = \rho D, \quad (2.12)$$

$$\left(\frac{1+m_e}{R^3} - \frac{1}{r^3}\right)D_2 = 2\rho'D, \quad (2.13)$$

where  $D = [\hat{r}, \hat{r}', \hat{r}'']$ ,  $D_1 = [\hat{r}, R, \hat{r}']$ ,  $D_2 = [\hat{r}, \hat{r}'', R]$ .

It is necessary to have one more equation involving  $r$  and  $\rho$ . Such an equation may be obtained by squaring the equation (2.9). Then

$$r^2 = \rho^2 + R^2 - 2(\hat{r} \cdot R)\rho. \quad (2.14)$$

We have now to evaluate the determinants  $D$ ,  $D_1$  and  $D_2$ . Suppose that the topocentric equatorial co-ordinates,  $\alpha_i, \delta_i$  ( $i=1,2,3$ ) have been obtained from three observations made at the instants  $t_1, t_2$  and  $t_3$ . The direction cosines of the line from the Earth to the Sun at  $t = t_i$  ( $i=1,2,3$ ) are given by

$$\lambda_i = \cos \delta_i \cos \alpha_i, \quad \mu_i = \cos \delta_i \sin \alpha_i, \quad \nu_i = \sin \delta_i \quad (i=1,2,3). \quad (2.15)$$

The quantities  $\lambda_i, \mu_i, \nu_i$  are the components of the unit vector  $\hat{p}_i$ . Thus the vector  $\hat{p}_i$  is known.

The position vectors of the Sun  $\underline{R}_i$  ( $i=1,2,3$ ) are obtained by interpolation from the equatorial rectangular co-ordinates of the Sun, tabulated in the Astronomical Ephemeris.

The next step in the evaluation of the determinants consists of the determination of the first and second derivatives of the vector  $\hat{p}$  at an instant  $t_0$  such that  $t_1 < t_0 < t_3$ . The vector  $\hat{p}$  can be expanded as power series in  $\tau$ , that is

$$\hat{p} = \hat{p}_0 + \hat{p}'_0 \tau + \hat{p}''_0 \frac{\tau^2}{2!} + \dots \quad (2.16)$$

In the case of the minor planets the series converges rapidly for small values of  $\tau$ .

The series (2.16) can be written in terms of  $\lambda, \mu$  and  $\nu$  as

$$\begin{aligned} \lambda &= \lambda_0 + \lambda'_0 \tau + \lambda''_0 \frac{\tau^2}{2!} + \dots, \\ \mu &= \mu_0 + \mu'_0 \tau + \mu''_0 \frac{\tau^2}{2!} + \dots, \\ \nu &= \nu_0 + \nu'_0 \tau + \nu''_0 \frac{\tau^2}{2!} + \dots. \end{aligned} \quad (2.17)$$

If the observations are equally (or nearly equally) spaced, one takes, in practice, the time of the second observation as the epoch  $t_0$ . Then  $\tau_2=0$  and  $\lambda_0=\lambda_2$ ,  $\mu_0=\mu_2$ ,  $\nu_0=\nu_2$ .

If only three observations are given, the series (2.17) have to be truncated. To obtain the components of the vectors  $\hat{\rho}'$  and  $\hat{\rho}''$  we obtain the following systems of equations

$$\left. \begin{aligned} \lambda_1 &= \lambda_0 + \lambda'_0 \tau_1 + \lambda''_0 \frac{\tau_1^2}{2!} \\ \lambda_3 &= \lambda_0 + \lambda'_0 \tau_3 + \lambda''_0 \frac{\tau_3^2}{2!} \end{aligned} \right\}, \quad (2.18)$$

$$\left. \begin{aligned} \mu_1 &= \mu_0 + \mu'_0 \tau_1 + \mu''_0 \frac{\tau_1^2}{2!} \\ \mu_3 &= \mu_0 + \mu'_0 \tau_3 + \mu''_0 \frac{\tau_3^2}{2!} \end{aligned} \right\}, \quad (2.19)$$

$$\left. \begin{aligned} \nu_1 &= \nu_0 + \nu'_0 \tau_1 + \nu''_0 \frac{\tau_1^2}{2!} \\ \nu_3 &= \nu_0 + \nu'_0 \tau_3 + \nu''_0 \frac{\tau_3^2}{2!} \end{aligned} \right\}, \quad (2.20)$$

Since  $(\lambda_1, \mu_1, \nu_1)$ ,  $(\lambda_3, \mu_3, \nu_3)$ ,  $(\lambda_0=\lambda_2, \mu_0=\mu_2, \nu_0=\nu_2)$ ,  $\tau_1$  and  $\tau_3$  are given we derive  $(\lambda'_0, \mu'_0, \nu'_0)$  and

$(\lambda''_0, \mu''_0, \nu''_0)$  by solving the equations (2.18), (2.19)

and (2.20).



The values so obtained are approximate due to the truncation of the series (2.17). If more than three observations are available we can obtain more accurate values, writing more equations containing more terms. Of course, the number of equations, which we can use, is limited by the fact that the instants of the observations must be included in the interval of convergence of the series (2.16), and we can no longer neglect the action of the other planets on the motion of the Earth and the minor planet, since more observations require a longer interval of time. This must be small, especially, when the perturbations from Jupiter on the minor planet are large.

The choice of the time of the second observation as the initial epoch has been made with the assumption that the second observation is halfway (or nearly halfway) between those of the other two. The question now arises, what should be taken as the initial epoch, when this assumption is not valid, and why we make such an assumption.

Let us consider the power series expansions (2.17) about some epoch point  $t_0 \neq t_2$ . Then the errors, resulting from neglecting the higher terms in the right members, are given by the relations

$$\Delta \lambda_0 = -\frac{1}{3!} \lambda_0''' \tau_1 \tau_2 \tau_3 - \frac{1}{4!} \lambda_0^{(4)} \tau_1 \tau_2 \tau_3 (\tau_1 + \tau_2 + \tau_3) + \dots,$$

$$\Delta \lambda_0' = \frac{1}{3!} \lambda_0''' (\tau_1 \tau_2 + \tau_2 \tau_3 + \tau_3 \tau_1) + \frac{1}{4!} \lambda_0^{(4)} (\tau_1 + \tau_2)(\tau_2 + \tau_3)(\tau_3 + \tau_1) + \dots, \quad (2.21)$$

$$\Delta \lambda_0'' = -\frac{1}{3!} \lambda_0''' (\tau_1 + \tau_2 + \tau_3) - \frac{1}{4!} \lambda_0^{(4)} (\tau_1^2 + \tau_2^2 + \tau_3^2 + \tau_1 \tau_2 + \tau_2 \tau_3 + \tau_3 \tau_1) + \dots,$$

and similar expressions for  $\Delta \mu_0, \Delta \mu_0', \Delta \mu_0'', \Delta \nu_0, \Delta \nu_0', \Delta \nu_0''$ .

Clearly,  $\lambda_0, \mu_0, \nu_0$  are subjected to errors of the third order,  $\lambda_0', \mu_0', \nu_0'$  are subjected to errors of the second order,

while the errors in  $\lambda_0''$ ,  $\mu_0''$ ,  $\nu_0''$  are of the first order. Since, in general, an error of the first order is more serious than one of the second order, the origin of the time should be chosen as to make the first order errors in  $\lambda_0''$ ,  $\mu_0''$ ,  $\nu_0''$  equal to zero. This will be valid if

$$\begin{aligned} & \tau_1 + \tau_2 + \tau_3 = 0, \\ \text{or} \quad & t_0 = \frac{1}{3} (t_1 + t_2 + t_3). \end{aligned} \quad (2.22)$$

Hence the instant of the second observation is taken to be the origin of the time when the successive observations are equally or about equally distant from one another.

The determinants  $D$ ,  $D_1$  and  $D_2$  are easily computed at the point  $\tau = 0$  from the evaluated derivatives  $\hat{\rho}'_0$ ,  $\hat{\rho}''_0$  and the known vectors  $\underline{R}_0$  and  $\hat{\rho}_0$ . Then, the equations (2.12) and (2.14) take the form

$$\rho_0 = C + \frac{F}{r_0^3}, \quad (2.23)$$

$$r_0^2 = \hat{\rho}_0^2 + A \cdot \rho_0 + B, \quad (2.24)$$

where  $C \equiv \left( \frac{1+m_e}{R_0^3} \right) \left( \frac{D_1}{D} \right)_{\tau=0}$ ,  $F \equiv \left( \frac{-D_1}{D} \right)_{\tau=0}$ ,  $A \equiv -2(\underline{R}_0 \cdot \hat{\rho}_0)$  and  $B \equiv R_0^2$ .

The index zero refers to the initial epoch  $t_0$ .

In order to find the values of  $r_0$  and  $\rho_0$  we have to solve the system of the equations (2.23), (2.24). Rather than attempting to solve this system by algebraic calculations, calculations which lead us to an equation of the eighth degree in  $\rho_0$ , it is easier to obtain values

for  $\rho_0$  and  $r_0$  by simultaneous solution of the equations of the system. This is accomplished by means of successive approximations. A value of  $r_0$  about 2,8 a.u., which is the mean heliocentric distance of the minor planets, is inserted in the equation (2.23) to obtain a value of  $\rho_0$ . Then with the help of the equation (2.24) we evaluate a second approximation of  $r_0$ . This is substituted into (2.23) and the process is continued until successive approximations are identical to the required accuracy.

After  $r_0$  and  $\rho_0$  are known we can evaluate  $\rho'_0$  making use of the equation (2.13), which at the point  $\tau = 0$  becomes

$$\rho'_0 = \left( \frac{1+m_e}{R_0^3} - \frac{1}{r_0^3} \right) \left( \frac{D_2}{2D} \right)_{\tau=0} . \quad (2.25)$$

The planetary aberration should now be taken into account. This is done subtracting from the E.T. the light time for the distance between the planet and the observer, that is

$$\text{corrected } t_i \equiv t_i^c = t_i - A^* \rho_i \quad (i=1,2,3), \quad (2.26)$$

where  $A^* = 0.00577560$  m.s.d., is the time, in mean solar days, during which the light travels one a.u.

For the modified variable time  $\tau$  we have,

$$\text{corrected } \tau_i \equiv \tau_i^c = k(t_i^c - t_0^c) \quad (i=1,2,3),$$

which by the introduction of the equation (2.26) becomes

$$\tau_i^c = k(t_i - A^* \rho_i - t_0 + A^* \rho_0) \quad \text{or} \quad \tau_i^c = \tau_i - k A^* (\rho_i - \rho_0) \quad (i=1,2,3). \quad (2.27)$$

In order to make these corrections to the instants of observations, it is necessary to know the values of  $\rho_i$  ( $i=1,2,3$ ). These are given

with sufficient approximation by

$$\rho_i = \rho_0 + \rho'_0 \tau_i^c \quad (i=1,2,3) .$$

Substitution of this equation in equation (2.27) gives

$$\tau_i^c = \tau_i - k A^* (\rho_0 + \rho'_0 \tau_i^c - \rho_0) \quad \text{or} \quad \tau_i^c = \frac{\tau_i}{1 + A^* k \rho'_0} \quad (i=1,2,3). \quad (2.28)$$

With these new corrected values of  $\tau_i^c$  ( $i=1,2,3$ ) we repeat the evaluation of  $\rho_0$  and  $\rho'_0$  until successive approximations of these are identical to the required accuracy.

We can now find the velocity vector  $\underline{r}_0'$ . In order to do this we need the velocity vector  $\underline{R}_0'$ . This is obtained by using the process which is described at the beginning of this chapter. From the known position vectors  $\underline{R}_1, \underline{R}_0, \underline{R}_3$  and the corresponding times  $\tau_1, \tau_2 \equiv 0, \tau_3$  we calculate the values of the f and g series, and then making use of the equation (2.4) we obtain the velocity vector  $\underline{R}_0'$ . Since  $\rho'_0, \hat{\rho}'_0$  and  $\underline{R}_0'$  are already known, the equation (2.10), at the point  $t = t_0$  gives the desired velocity vector  $\underline{r}_0'$ .

The vectors  $\underline{r}_0$  and  $\underline{r}_0'$  are already known, and as a matter of fact, their components comprise an alternative set of the six constants of integration of the two body problem, so we can proceed in the determination of the orbital elements of the minor planet.

Since the elements  $\Omega, i$  and  $\omega$  are referred to the ecliptic, we rotate the co-ordinate system about x-axis through an angle  $\epsilon$ , equal to the obliquity of the ecliptic. Then the components of the vectors  $\underline{r}_0$  and  $\underline{r}_0'$  in the new system are given by

$$\begin{aligned} [x_e, y_e, z_e] &= [x, y, z] M(\epsilon) \\ [x'_e, y'_e, z'_e] &= [x', y', z'] M(\epsilon) \end{aligned} \quad (2.29)$$

where  $M(\varepsilon)$  is the matrix

$$M(\varepsilon) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \varepsilon & -\sin \varepsilon \\ 0 & \sin \varepsilon & \cos \varepsilon \end{bmatrix} .$$

The angular momentum per unit mass

$$\underline{h} = \underline{r} \times \frac{d\underline{r}}{dt} = k \left( \underline{r} \times \frac{d\underline{r}}{d\tau} \right) = k(\underline{r} \times \underline{r}') , \quad (2.30)$$

is constant and can be found at once. Its components in the ecliptic co-ordinate system are evaluated by

$$h_{x_e} = (y_e z'_e - y'_e z_e), \quad h_{y_e} = (z_e x'_e - z'_e x_e), \quad h_{z_e} = (x_e y'_e - x'_e y_e). \quad (2.31)$$

On the other hand, the direction cosines of the unit vector  $\hat{h}$  as is evident from the geometry of the orbit, are

$$\sin \varrho \sin i, -\cos \varrho \sin i, \cos i .$$

Since  $\hat{h} = (h_{x_e}/h, h_{y_e}/h, h_{z_e}/h)$  it follows that

$$\frac{h_{x_e}}{h} = \sin \varrho \sin i, \quad -\frac{h_{y_e}}{h} = \cos \varrho \sin i, \quad \frac{h_{z_e}}{h} = \cos i . \quad (2.31)$$

From the formulae (2.31), since  $h_{x_e}$ ,  $h_{y_e}$ ,  $h_{z_e}$  and  $h$  are known, we obtain  $\varrho$  and  $i$ .

The semi-latus rectum of the orbit is found as a result of the relation

$$P = \frac{h^2}{G(m+m_\odot)} ,$$

where  $h^2 = (h_{x_e}^2 + h_{y_e}^2 + h_{z_e}^2)$  ,  $m_\odot$  is the mass of the Sun and  $m$  the mass of the asteroid. Since  $m$  is much less than  $m_\odot$  and, in general, unknown, it is usually neglected.

In order to find the eccentricity  $e$  let us consider the equation

$$r = P / (1 + e \cos U) \quad \text{or} \quad e \cos U = \frac{P}{r} - 1 , \quad (2.32)$$

which describes, in first approximation, the relative motion of the asteroid. Differentiating this equation once with respect to  $t$  we obtain

$$-e \sin U \dot{U} = -\frac{P}{r^2} \dot{r} . \quad (2.33)$$

Since the tangential component of the velocity in a motion is  $v = r \cdot \dot{U}$  and  $h = r \cdot v$  the equation (2.33) becomes

$$e \sin U = \frac{P}{h} \dot{r} . \quad (2.34)$$

Squaring and adding the equations (2.32) and (2.34) we obtain

$$e^2 = \left( \frac{P}{h} \dot{r} \right)^2 + \left( \frac{P}{r} - 1 \right)^2 , \quad (2.35)$$

which gives the value of the eccentricity. Using this value, with the help of the equations (2.32) and (2.34), we can find the true anomaly.

We notice that  $\dot{r}$  is given by

$$\dot{r} = \frac{d(x^2 + y^2 + z^2)^{1/2}}{dt} = \frac{1}{2}(x^2 + y^2 + z^2)^{-1/2} \cdot 2(x\dot{x} + y\dot{y} + z\dot{z}),$$

or

$$\dot{r} = \frac{\underline{r} \cdot \dot{\underline{r}}}{r}.$$

The semi-major axis  $\alpha$  is obtained directly from

$$\alpha = \frac{P}{(1 - e^2)}.$$

Next step is to find  $\omega$ . The heliocentric ecliptic rectangular co-ordinates are given by

$$x_e = r(\cos \varrho \cos(\omega + u) - \sin \varrho \sin(\omega + u) \cos i),$$

$$y_e = r(\sin \varrho \cos(\omega + u) + \cos \varrho \sin(\omega + u) \cos i),$$

$$z_e = r(\sin(\omega + u) \sin i).$$

Multiplying the first equation by  $\cos \varrho$ , the second by  $\sin \varrho$  and adding we obtain

$$x_e \cos \varrho + y_e \sin \varrho = r \cos(\omega + u).$$

Similarly, multiplying the first equation by  $-\sin \varrho \cos i$ , the second by  $\cos \varrho \cos i$ , the third by  $\sin i$  and adding we get

$$-x_e \sin \varrho \cos i + y_e \cos \varrho \cos i + z_e \sin i = r \sin(\omega + u).$$

The combination of these two equations gives

$$\tan(\omega + u) = \frac{-x_e \sin \varrho \cos i + y_e \cos \varrho \cos i + z_e \sin i}{x_e \cos \varrho + y_e \sin \varrho}.$$

Since  $U, Q, i$  are already known, we obtain  $\omega$ .

The mean daily motion  $n$  is obtained without difficulty from the relation

$$n^2 = k^2 / \alpha^3 .$$

The already known true anomaly and the eccentric anomaly are connected by the relation

$$t \alpha n \frac{E}{2} = \left( \frac{1-e}{1+e} \right)^{1/2} t \alpha n \frac{U}{2} .$$

Consequently we can easily find the value of  $E$ .

Using Kepler's equation

$$M = E - e \sin E ,$$

we obtain the mean anomaly  $M$  and hence the time of perihelion passage, since

$$M = n(t - T) \quad \text{or} \quad T = t - \frac{M}{n} .$$



TABLE I. Coefficients  $f_n, g_n$  to 12th order.

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$f_0 = 1$
$f_1 = 0$
$f_2 = -\mu$
$f_3 = 3\sigma\mu$
$f_4 = -15\sigma^2\mu + 3\epsilon\mu + \mu^2$
$f_5 = 105\sigma^3\mu - \sigma(45\epsilon\mu + 15\mu^2)$
$f_6 = -945\sigma^4\mu + \sigma^2(630\epsilon\mu + 210\mu^2) - 24\epsilon\mu^2 - 45\epsilon^2\mu - \mu^3$
$f_7 = 10395\sigma^5\mu - \sigma^3(9450\epsilon\mu + 3150\mu^2) + \sigma(882\epsilon\mu^2 + 1575\epsilon^2\mu + 63\mu^3)$
$f_8 = -135135\sigma^6\mu + \sigma^4(155925\epsilon\mu + 51975\mu^2)$ $- \sigma^2(24570\epsilon\mu^2 + 42525\epsilon^2\mu + 2205\mu^3) + 117\epsilon\mu^3 + 1575\epsilon^3\mu$ $+ 1107\epsilon^2\mu^2 + \mu^4$
$f_9 = 2027025\sigma^7\mu - \sigma^5(2837835\epsilon\mu + 945945\mu^2)$ $+ \sigma^3(644490\epsilon\mu^2 + 1091475\epsilon^2\mu + 65835\mu^3)$ $- \sigma(10935\epsilon\mu^3 + 99225\epsilon^3\mu + 74385\epsilon^2\mu^2 + 255\mu^4)$
$f_{10} = -34459425\sigma^8\mu + \sigma^6(56756700\epsilon\mu + 18918900\mu^2)$ $- \sigma^4(17027010\epsilon\mu^2 + 28378350\epsilon^2\mu + 1891890\mu^3)$ $+ \sigma^2(599940\epsilon\mu^3 + 4365900\epsilon^3\mu + 3421440\epsilon^2\mu^2 + 21120\mu^4)$ $- 498\epsilon\mu^4 - 99225\epsilon^4\mu - 85410\epsilon^3\mu^2 - 15066\epsilon^2\mu^3 - \mu^5$
$f_{11} = 654729075\sigma^9\mu - \sigma^7(1240539300\epsilon\mu + 413513100\mu^2)$ $+ \sigma^5(465404940\epsilon\mu^2 + 766215450\epsilon^2\mu + 54864810\mu^3)$ $- \sigma^3(27027000\epsilon\mu^3 + 170270100\epsilon^3\mu + 137837700\epsilon^2\mu^2$ $+ 1201200\mu^4) + \sigma(114444\epsilon\mu^4 + 9823275\epsilon^4\mu + 9058500\epsilon^3\mu^2$ $+ 2023758\epsilon^2\mu^3 + 1023\mu^5)$
$f_{12} = -13749310575\sigma^{10}\mu + \sigma^8(29462808375\epsilon\mu + 9820936125\mu^2)$ $- \sigma^6(13315121820\epsilon\mu^2 + 21709437750\epsilon^2\mu + 1640268630\mu^3)$ $+ \sigma^4(1122971850\epsilon\mu^3 + 6385128750\epsilon^3\mu + 5298643350\epsilon^2\mu^2$ $+ 58108050\mu^4) - \sigma^2(12072060\epsilon\mu^4 + 638512875\epsilon^4\mu$ $+ 618918300\epsilon^3\mu^2 + 159729570\epsilon^2\mu^3 + 195195\mu^5) + 2031\epsilon\mu^5$ $+ 9823275\epsilon^5\mu + 9951525\epsilon^4\mu^2 + 2480958\epsilon^3\mu^3 + 164610\epsilon^2\mu^4 + \mu^6$
$g_0 = 0$
$g_1 = 1$
$g_2 = 0$
$g_3 = -\mu$
$g_4 = 6\sigma\mu$
$g_5 = -45\sigma^2\mu + 9\epsilon\mu + \mu^2$
$g_6 = 420\sigma^3\mu - \sigma(180\epsilon\mu + 30\mu^2)$
$g_7 = -4725\sigma^4\mu + \sigma^2(3150\epsilon\mu + 630\mu^2) - 54\epsilon\mu^2 - 225\epsilon^2\mu - \mu^3$
$g_8 = 62370\sigma^5\mu - \sigma^3(56700\epsilon\mu + 12600\mu^2)$ $+ \sigma(3024\epsilon\mu^2 + 9450\epsilon^2\mu + 126\mu^3)$
$g_9 = -945945\sigma^6\mu + \sigma^4(1091475\epsilon\mu + 259875\mu^2)$ $- \sigma^2(111510\epsilon\mu^2 + 297675\epsilon^2\mu + 6615\mu^3) + 243\epsilon\mu^3 + 11025\epsilon^3\mu$ $+ 4131\epsilon^2\mu^2 + \mu^4$
$g_{10} = 16216200\sigma^7\mu - \sigma^5(22702680\epsilon\mu + 5675670\mu^2)$ $+ \sigma^3(3617460\epsilon\mu^2 + 8731800\epsilon^2\mu + 263340\mu^3)$ $- \sigma(35100\epsilon\mu^3 + 793800\epsilon^3\mu + 371790\epsilon^2\mu^2 + 510\mu^4)$
$g_{11} = -310134825\sigma^8\mu + \sigma^6(510810300\epsilon\mu + 132432300\mu^2)$ $- \sigma^4(113513400\epsilon\mu^2 + 255405150\epsilon^2\mu + 9459450\mu^3)$ $+ \sigma^2(2589840\epsilon\mu^3 + 39293100\epsilon^3\mu + 21116700\epsilon^2\mu^2 + 63360\mu^4)$ $- 1008\epsilon\mu^4 - 893025\epsilon^4\mu - 457200\epsilon^3\mu^2 - 50166\epsilon^2\mu^3 - \mu^5$
$g_{12} = 6547290750\sigma^9\mu - \sigma^7(12405393000\epsilon\mu + 3308104800\mu^2)$ $+ \sigma^5(3587023440\epsilon\mu^2 + 7662154500\epsilon^2\mu + 329188860\mu^3)$ $- \sigma^3(145945800\epsilon\mu^3 + 1702701000\epsilon^3\mu + 1005404400\epsilon^2\mu^2$ $+ 4804800\mu^4) + \sigma(355608\epsilon\mu^4 + 98232750\epsilon^4\mu + 60350400\epsilon^3\mu^2$ $+ 9227196\epsilon^2\mu^3 + 2046\mu^5)$

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### Chapter 3

#### The Solution of the N-Body Problem by Power Series

The n-body problem is defined in the following way. Consider n bodies with masses  $m_1, m_2, \dots, m_n$  with such an internal mass distribution that they may be considered as particles which attract each other according to the Newtonian law of gravitation. They are free to move in space, initially in any given manner. The problem is to find their subsequent motion.

The notation used in this chapter is given below.

The position vectors of the particles and their co-ordinates in a Cartesian right handed inertial system are:

$$\underline{r}_1 \equiv (x_1, y_1, z_1), \quad \underline{r}_2 \equiv (x_2, y_2, z_2), \quad \dots, \quad \underline{r}_n \equiv (x_n, y_n, z_n). \quad (3.1)$$

The vector connecting the  $i^{th}$  and  $j^{th}$  ( $i, j = 1, \dots, n, i \neq j$ ) particles is:

$$\underline{r}_{ij} = \underline{r}_i - \underline{r}_j. \quad (3.2)$$

The derivatives of the position vectors of the bodies, with respect to  $\tau$ , are:

$$\underline{r}_i^{(1)} \equiv \dot{\underline{r}}_i \equiv \frac{d\underline{r}_i}{d\tau}, \quad \underline{r}_i^{(2)} \equiv \ddot{\underline{r}}_i \equiv \frac{d^2\underline{r}_i}{d\tau^2} \quad \text{and in general} \quad \underline{r}_i^{(v)} \equiv \frac{d^v \underline{r}_i}{d\tau^v} \quad (i=1, \dots, n), \quad (3.3)$$

$v \geq 1$

where  $\tau = k(t - t_0)$ . These derivatives, with respect to  $t$ , are:

$$\underline{r}_i^{[1]} \equiv \dot{\underline{r}}_i \equiv \frac{d\underline{r}_i}{dt}, \quad \underline{r}_i^{[2]} \equiv \ddot{\underline{r}}_i \equiv \frac{d^2\underline{r}_i}{dt^2} \quad \text{and in general} \quad \underline{r}_i^{[v]} \equiv \frac{d^v \underline{r}_i}{dt^v} \quad (i=1, \dots, n). \quad (3.4)$$

$v \geq 1$

Hence the following relation is evident:

$$k^v \tilde{r}_i^{(v)} = \tilde{r}_i^{[v]} \quad v \gg 1 \quad (i = 1; \dots; n). \quad (3.5)$$

Neglecting any acceleration possibly caused by thrust, drag, gravitational forces exterior to the system of the bodies, etc., the force acting on the  $i^{\text{th}}$  body due to the other bodies is given by the relation

$$\tilde{F}_i = -k^2 m_i \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{\tilde{r}_i - \tilde{r}_j}{\tilde{r}_{ij}^3} \quad (i = 1; \dots; n). \quad (3.6)$$

Since this force, according to Newton's second law, is equal to

$m_i d^2 \tilde{r}_i / dt^2$  ( $i = 1; \dots; n$ ) equation (3.6) becomes

$$m_i \frac{d^2 \tilde{r}_i}{dt^2} = -k^2 m_i \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{\tilde{r}_i - \tilde{r}_j}{\tilde{r}_{ij}^3} \quad (i = 1; \dots; n). \quad (3.7)$$

However, the form of equation (3.7) is not very useful for practical applications. We consider, therefore, an  $(n + 1)$ -body system, and for the sake of convenience the origin of the co-ordinate system is transferred to a particular body. The form of the equations of motion, referred to this relative co-ordinate system, fixed to one of the bodies, say to the  $(n+1)^{\text{th}}$ , are

$$\frac{d^2 \tilde{r}_i}{dt^2} = -k^2 (m_0 + m_i) \frac{\tilde{r}_i}{\tilde{r}_i^3} - k^2 \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{\tilde{r}_i - \tilde{r}_j}{\tilde{r}_{ij}^3} + \frac{\tilde{r}_j}{\tilde{r}_j^3} \right) \quad (i = 1; \dots; n), \quad (3.8)$$

where  $k$  is the gravitational constant,  $m_0 \equiv m_{n+1}$  is the mass of the central body which is considered as the origin of the co-ordinate system,  $m_i$  is the mass of the  $i^{\text{th}}$  body,  $\tilde{r}_i$  the distance of the  $i^{\text{th}}$  body from the origin and  $\tilde{r}_{ij}$  the distance between  $m_i$  and  $m_j$ . It

is obvious that

$$\underline{r}_i = |\underline{r}_i| = (x_i^2 + y_i^2 + z_i^2)^{1/2} \quad (i=1, \dots, n), \quad (3.9)$$

$$\underline{r}_{ij} = |\underline{r}_j - \underline{r}_i| = \left[ (x_j - x_i)^2 + (y_j - y_i)^2 + (z_j - z_i)^2 \right]^{1/2} \quad (i, j=1, \dots, n, i \neq j).$$

Since the system being considered is the Solar System, to establish the equations of motion using dimensionless variables, we express the distances in astronomical units, the masses in solar masses and the time in  $1/k$  mean solar days. Then equation (3.8), by introduction of the notation (3.3) and the equation (3.5), becomes

$$\underline{r}_i'' = -(1+m_i) \frac{\underline{r}_i}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{\underline{r}_i - \underline{r}_j}{r_{ij}^3} + \frac{\underline{r}_j}{r_j^3} \right) \quad (i=1, \dots, n), \quad (3.10)$$

or

$$\underline{r}_i'' = \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] \underline{r}_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) \underline{r}_j \quad (i=1, \dots, n).$$

The system (3.10) consists of  $n$  second-order differential equations for the vectors  $\underline{r}_i$  ( $i=1, 2, \dots, n$ ) and it is equivalent to a system of  $3n$  second-order differential equations for the co-ordinates  $x_i, y_i, z_i$  ( $i=1, \dots, n$ ). That is

$$\begin{aligned} x_i'' &= \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] x_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) x_j, \\ y_i'' &= \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] y_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) y_j, \quad (i=1, \dots, n) \\ z_i'' &= \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] z_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) z_j. \end{aligned} \quad (3.11)$$

We reduce this second-order system to another of first order, by introducing new variables given by

$$Q_i = (u_i, v_i, w_i) \equiv (x'_i, y'_i, z'_i) \quad (i = 1, \dots, n), \quad (3.12)$$

and we obtain

$$\begin{aligned} x'_i &= u_i \\ y'_i &= v_i \\ z'_i &= w_i \end{aligned}$$

$$u'_i = \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] x_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) x_j \quad (3.13)$$

$$v'_i = \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] y_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) y_j \quad (i = 1, \dots, n)$$

$$w'_i = \left[ -(1+m_i) \frac{1}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{1}{r_{ij}^3} \right] z_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{1}{r_{ij}^3} - \frac{1}{r_j^3} \right) z_j.$$

In order to prove that there exists a solution of this system, three theorems are given below, which will be used for this purpose.

**Theorem 1:** If a function  $f$  has a derivative at a point  $\tau_1$  then it is also continuous at  $\tau_1$ . (Apostol, Vol. I, p. 116)

**Theorem 2:** Let  $f$  and  $g$  be continuous functions at a point  $\tau_1$ , then the sum  $f + g$ , the difference  $f - g$  and the product  $f \cdot g$  are also continuous at  $\tau_1$ . The same is true for the quotient  $f/g$  if  $g(\tau_1) \neq 0$ . (Apostol, Vol. I, p. 115).

**Theorem 3:** A general first-order system for  $m$  unknowns functions  $\varphi_1, \varphi_2, \dots, \varphi_m$ , may be written as:

$$\varphi'_1 = f_1(\tau, \varphi_1, \varphi_2, \dots, \varphi_m)$$

$$\varphi'_2 = f_2(\tau, \varphi_1, \varphi_2, \dots, \varphi_m) \quad (3.14)$$

$$\varphi'_m = f_m(\tau, \varphi_1, \varphi_2, \dots, \varphi_m).$$

Suppose that  $f_1, f_2, \dots, f_m$  and the derivatives  $\partial f_i / \partial \varphi_j$  ( $i, j = 1, \dots, m$ ) are continuous in a box

$$|\tau - \tau^0| < K,$$

$$|\varphi_i - \varphi_i^0| < K \quad (i = 1, \dots, m),$$

Where  $\tau^0, \varphi_1^0, \dots, \varphi_m^0$  are given numbers. Then for some positive number  $h$  there exists a solution  $\varphi(\tau) = (\varphi_1(\tau), \varphi_2(\tau), \dots, \varphi_m(\tau))$  of the system (3.14) which is defined for  $\tau$  in the interval  $|\tau - \tau^0| < h$  and satisfies the conditions  $\varphi_i(\tau^0) = \varphi_i^0$  ( $i = 1, \dots, m$ ). The solution is unique in the sense that, if  $\varphi_i^* = \varphi_i^*(\tau)$  ( $i = 1, \dots, m$ ) is another solution and satisfies  $\varphi_i^*(\tau^0) = \varphi_i^0$  ( $i = 1, \dots, m$ ), then  $\varphi_i^*(\tau) = \varphi_i(\tau)$  in their common interval of definition (Morrey, p. 698)

Firstly, we notice that the existence of the derivatives  $\dot{x}_i, \dot{y}_i, \dot{z}_i, \ddot{u}_i \equiv \ddot{x}_i, \ddot{v}_i \equiv \ddot{y}_i, \ddot{w}_i \equiv \ddot{z}_i$  ( $i = 1, \dots, n$ ) is obvious by the nature of the problem, and for the reason that the components of the velocity and acceleration vectors (to which the derivatives are identical) are limited for every value of the time  $\tau$ . Similarly, the functions  $\tilde{r}_i = \tilde{r}_i(\tau), \tilde{r}_{ij} = \tilde{r}_{ij}(\tau)$  ( $i, j = 1, \dots, n, i \neq j$ ), possess first order derivatives in the interval  $(-\infty, +\infty)$ , which are

calculated as follows:

$$\underline{r}_i \cdot \underline{r}_i = r_i^2 \rightarrow 2 \underline{r}_i \cdot \underline{r}_i' = 2 r_i r_i' \rightarrow r_i' = \frac{\underline{r}_i \cdot \underline{r}_i'}{r_i} = \frac{x_i x_i' + y_i y_i' + z_i z_i'}{(x_i^2 + y_i^2 + z_i^2)^{1/2}} \quad (i=1, \dots, n), \quad (3.15)$$

$$\underline{r}_{ij} \cdot \underline{r}_{ij} = r_{ij}^2 \rightarrow 2 \underline{r}_{ij} \cdot \underline{r}_{ij}' = 2 r_{ij} r_{ij}' \rightarrow r_{ij}' = \frac{\underline{r}_{ij} \cdot \underline{r}_{ij}'}{r_{ij}} = \frac{(\underline{r}_i - \underline{r}_j) \cdot (\underline{r}_i' - \underline{r}_j')}{r_{ij}} \quad (3.16)$$

hence

$$r_{ij}' = \frac{(x_j - x_i)(x_j' - x_i') + (y_j - y_i)(y_j' - y_i') + (z_j - z_i)(z_j' - z_i')}{((x_j - x_i)^2 + (y_j - y_i)^2 + (z_j - z_i)^2)^{1/2}} \quad (i, j = 1, \dots, n \quad i \neq j).$$

The functions  $r_i^{-3} = r_i^{-3}(\tau)$ ,  $r_{ij}^{-3} = r_{ij}^{-3}(\tau)$  ( $i, j = 1, \dots, n \quad i \neq j$ )

therefore, possess first-order derivatives for every value of  $\tau$  in the interval  $(-\infty, +\infty)$ . These are given by

$$(r_i^{-3})' = -3 r_i^{-4} r_i' \quad (r_{ij}^{-3})' = -3 r_{ij}^{-4} r_{ij}' \quad (i, j = 1, \dots, n \quad i \neq j).$$

We must, obviously, exclude the points of singularity, if they exist.

Consequently, according to theorems 1 and 2, the right hand side terms of system (3.13) are continuous in the open interval  $(-\infty, +\infty)$ , except at the points of singularity.

In the same way we can easily prove that the partial derivatives of the right hand side terms of the system (3.13) are continuous in the same interval.

So the theorem 3 assures the existence of a unique solution of system (3.13).

The next step is to prove that the position vectors  $\underline{r}_i$  ( $i=1, \dots, n$ ), being considered as functions of the modified time  $\tau$ , possess derivatives of all orders and so the unique solution of the system (3.13)

can be expanded in power series. For this purpose the following expressions are introduced

$$\begin{aligned} \alpha_i &\equiv \underline{r}_i^{-3}, & \beta_{ijk} &\equiv \frac{\underline{r}_i' \cdot \underline{r}_j}{\underline{r}_k^2} \quad (i, j, k = 1 \dots n), \\ \gamma_{ijk} &\equiv \frac{\underline{r}_i' \cdot \underline{r}_j'}{\underline{r}_k^2}, & \delta_{ijk} &\equiv \frac{\underline{r}_i \cdot \underline{r}_j}{\underline{r}_k^2} \quad (i, j, k = 1 \dots n), \\ \alpha_{ij} &\equiv \underline{r}_{ij}^{-3}, & b_{ij} &\equiv \frac{\underline{r}_i^2}{\underline{r}_{ij}^2} \quad (i, j = 1 \dots n \quad i \neq j), \end{aligned} \quad (3.17)$$

where it is obvious that  $\gamma_{ijk} = \gamma_{jik}$ ,  $\delta_{ijk} = \delta_{jik}$  ( $i, j, k = 1 \dots n$ ),  $\alpha_{ij} = \alpha_{ji}$  ( $i, j = 1 \dots n \quad i \neq j$ ) and  $\delta_{iii} = 1$  ( $i = 1 \dots n$ ).

The proof that the derivatives of these expressions are functions of the expressions themselves is given below.

They are initially given the formulae for the acceleration vectors  $\underline{r}_i''$ ,  $\underline{r}_j''$  of the  $i^{\text{th}}$  and  $j^{\text{th}}$  particles by changing the indices of equation (3.10), a fact which will help us later to avoid confusion with the indices of the expressions (3.17)

$$\underline{r}_i'' = -(1 + m_i) \frac{\underline{r}_i}{\underline{r}_i^3} - \underline{r}_i \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{1}{\underline{r}_{i\lambda}^3} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\underline{r}_\lambda}{\underline{r}_{i\lambda}^3} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\underline{r}_\lambda}{\underline{r}_\lambda^3} \quad (i = 1 \dots n), \quad (3.18)$$

$$\underline{r}_j'' = -(1 + m_j) \frac{\underline{r}_j}{\underline{r}_j^3} - \underline{r}_j \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{1}{\underline{r}_{j\mu}^3} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{\underline{r}_\mu}{\underline{r}_{j\mu}^3} - \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{\underline{r}_\mu}{\underline{r}_\mu^3} \quad (j = 1 \dots n). \quad (3.19)$$

We proceed now to the calculation of the derivatives

$$\alpha_i', \beta_{ijk}', \gamma_{ijk}', \delta_{ijk}' \quad (i, j, k = 1 \dots n), \alpha_{ij}', b_{ij}' \quad (i, j = 1 \dots n \quad i \neq j).$$

Differentiating the first of the relations (3.17) once with respect to  $\tau$  we obtain



$$\alpha'_i = (\Gamma_i^{-3})' = -3 \Gamma_i' \Gamma_i^{-4} \quad (i=1 \dots n),$$

which by introduction of equation (3.15) becomes

$$\alpha'_i = -3 \Gamma_i^{-4} \frac{\Gamma_i \cdot \Gamma_i'}{\Gamma_i} = -3 \Gamma_i^{-3} \frac{\Gamma_i \cdot \Gamma_i'}{\Gamma_i^2} = -3 \alpha_i \beta_{iii} \quad (i=1 \dots n). \quad (3.20)$$

Similarly, differentiation of the second of the relations (3.17) gives

$$\beta'_{ijk} = \left( \frac{\Gamma_i \cdot \Gamma_j}{\Gamma_k^2} \right)' = \frac{\Gamma_i'' \cdot \Gamma_j}{\Gamma_k^2} + \frac{\Gamma_i' \cdot \Gamma_j'}{\Gamma_k^2} - 2 \frac{\Gamma_i' \cdot \Gamma_j}{\Gamma_k^3} \Gamma_k' \quad (i, j, k=1 \dots n),$$

Making use of equations (3.15) and (3.18) we obtain

$$\begin{aligned} \beta'_{ijk} &= \frac{\Gamma_j}{\Gamma_k^2} \left[ -(1+m_i) \frac{\Gamma_i}{\Gamma_k^3} - \Gamma_i \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{1}{\Gamma_{i\lambda}^3} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\Gamma_\lambda}{\Gamma_{i\lambda}^3} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\Gamma_\lambda}{\Gamma_\lambda^3} \right] + \\ &+ \frac{\Gamma_i' \cdot \Gamma_j'}{\Gamma_k^2} - 2 \frac{\Gamma_i' \cdot \Gamma_j}{\Gamma_k^3} \frac{\Gamma_k' \cdot \Gamma_k}{\Gamma_k} = \\ &= -(1+m_i) \Gamma_i^{-3} \frac{\Gamma_i \cdot \Gamma_j}{\Gamma_k^2} - \frac{\Gamma_i \cdot \Gamma_j}{\Gamma_k^2} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \Gamma_{i\lambda}^{-3} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \Gamma_{i\lambda}^{-3} \frac{\Gamma_j \cdot \Gamma_\lambda}{\Gamma_k^2} - \\ &- \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \Gamma_\lambda^{-3} \frac{\Gamma_j \cdot \Gamma_\lambda}{\Gamma_k^2} + \frac{\Gamma_i' \cdot \Gamma_j'}{\Gamma_k^2} - 2 \frac{\Gamma_i' \cdot \Gamma_j}{\Gamma_k^2} \frac{\Gamma_k' \cdot \Gamma_k}{\Gamma_k^2} \quad (i, j, k=1 \dots n), \end{aligned}$$

and according to the expressions (3.17)

$$\begin{aligned} \beta'_{ijk} &= -(1+m_i) \alpha_i \delta_{ijk} - \delta_{ijk} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} \delta_{j\lambda k} - \\ &- \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_\lambda \delta_{j\lambda k} + \gamma_{ijk} - 2 \beta_{ijk} \beta_{kkk} \quad (i, j, k=1 \dots n). \end{aligned} \quad (3.21)$$

Differentiating both sides of the third of the relations (3.17) with respect  $\tau$  we obtain

$$\gamma'_{ijk} = \left( \frac{\Gamma_i' \cdot \Gamma_j'}{\Gamma_k^2} \right)' = \frac{\Gamma_i'' \cdot \Gamma_j'}{\Gamma_k^2} + \frac{\Gamma_i' \cdot \Gamma_j''}{\Gamma_k^2} - 2 \frac{\Gamma_i' \cdot \Gamma_j'}{\Gamma_k^3} \Gamma_k',$$

which upon substitution of equations (3.15), (3.18) and (3.19) becomes

$$\begin{aligned}
 \gamma'_{ijk} &= \frac{\underline{\gamma}_j'}{\underline{\gamma}_k^2} \left[ -(1+m_i) \frac{\underline{\gamma}_i}{\underline{\gamma}_i^3} - \underline{\gamma}_i \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{1}{\underline{\gamma}_{i\lambda}^3} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\underline{\gamma}_\lambda}{\underline{\gamma}_{i\lambda}^3} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \frac{\underline{\gamma}_\lambda}{\underline{\gamma}_\lambda^3} \right] + \\
 &+ \frac{\underline{\gamma}_i'}{\underline{\gamma}_k^2} \left[ -(1+m_j) \frac{\underline{\gamma}_j}{\underline{\gamma}_j^3} - \underline{\gamma}_j \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{1}{\underline{\gamma}_{j\mu}^3} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{\underline{\gamma}_\mu}{\underline{\gamma}_{j\mu}^3} - \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \frac{\underline{\gamma}_\mu}{\underline{\gamma}_\mu^3} \right] - \\
 &- 2 \frac{\underline{\gamma}_i' \cdot \underline{\gamma}_j'}{\underline{\gamma}_k^3} \frac{\underline{\gamma}_k \cdot \underline{\gamma}_k'}{\underline{\gamma}_k} = \\
 &= -(1+m_i) \underline{\gamma}_i^{-3} \frac{\underline{\gamma}_j \cdot \underline{\gamma}_i}{\underline{\gamma}_k^2} - \frac{\underline{\gamma}_j \cdot \underline{\gamma}_i}{\underline{\gamma}_k^2} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \underline{\gamma}_\lambda^{-3} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \underline{\gamma}_\lambda^{-3} \frac{\underline{\gamma}_j \cdot \underline{\gamma}_\lambda}{\underline{\gamma}_k^2} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \underline{\gamma}_\lambda^{-3} \frac{\underline{\gamma}_j \cdot \underline{\gamma}_\lambda}{\underline{\gamma}_k^2} - \\
 &- (1+m_j) \underline{\gamma}_j^{-3} \frac{\underline{\gamma}_i \cdot \underline{\gamma}_j}{\underline{\gamma}_k^2} - \frac{\underline{\gamma}_i \cdot \underline{\gamma}_j}{\underline{\gamma}_k^2} \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \underline{\gamma}_\mu^{-3} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \underline{\gamma}_\mu^{-3} \frac{\underline{\gamma}_i \cdot \underline{\gamma}_\mu}{\underline{\gamma}_k^2} - \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \underline{\gamma}_\mu^{-3} \frac{\underline{\gamma}_i \cdot \underline{\gamma}_\mu}{\underline{\gamma}_k^2} - \\
 &- 2 \frac{\underline{\gamma}_i' \cdot \underline{\gamma}_j'}{\underline{\gamma}_k^2} \frac{\underline{\gamma}_k \cdot \underline{\gamma}_k'}{\underline{\gamma}_k^2} \quad (i, j, k = 1, \dots, n).
 \end{aligned}$$

Introduction of expressions (3.17) gives

$$\begin{aligned}
 \gamma'_{ijk} &= -(1+m_i) \alpha_i \beta_{jik} - \beta_{jik} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} \beta_{j\lambda k} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_\lambda \beta_{j\lambda k} - \\
 &- (1+m_j) \alpha_j \beta_{ijk} - \beta_{ijk} \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} \beta_{i\mu k} - \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_\mu \beta_{i\mu k} - \quad (3.22) \\
 &- 2 \gamma_{ijk} \beta_{kkk} \quad (i, j, k = 1, \dots, n).
 \end{aligned}$$

To find the derivative  $\delta'_{ijk}$  ( $i, j, k = 1, 2, \dots, n$ ) we differentiate both sides of the relation

$$\delta_{ijk} = \frac{\underline{\gamma}_i \cdot \underline{\gamma}_j}{\underline{\gamma}_k^2} \quad (i, j, k = 1, \dots, n)$$

with respect to  $\underline{\gamma}$  to give

$$\begin{aligned}
\delta'_{ijk} &\equiv \left( \frac{\underline{r}_i \cdot \underline{r}_j}{r_k^2} \right)' = \frac{\underline{r}_i' \cdot \underline{r}_j}{r_k^2} + \frac{\underline{r}_i \cdot \underline{r}_j'}{r_k^2} - 2 \frac{\underline{r}_i \cdot \underline{r}_j}{r_k^3} r_k' = \\
&= \frac{\underline{r}_i' \cdot \underline{r}_j}{r_k^2} + \frac{\underline{r}_i \cdot \underline{r}_j'}{r_k^2} - 2 \frac{\underline{r}_i \cdot \underline{r}_j}{r_k^2} \frac{r_k' \cdot r_k}{r_k^2} = \\
&= b_{ijk} + b_{jik} - 2 \delta_{ijk} b_{kkk} \quad (i, j, k = 1 \dots n).
\end{aligned} \tag{3.23}$$

Similarly, from the relation  $\alpha_{ij} \equiv r_{ij}^{-3}$  ( $i, j = 1, \dots, n \quad i \neq j$ ) we obtain

$$\alpha'_{ij} \equiv (r_{ij}^{-3})' = -3 r_{ij}^{-4} r_{ij}',$$

which upon substitution of equation (3.16) becomes

$$\begin{aligned}
\alpha'_{ij} &= -3 r_{ij}^{-4} \frac{(\underline{r}_j - \underline{r}_i) \cdot (\underline{r}_j' - \underline{r}_i')}{r_{ij}} = \\
&= -3 r_{ij}^{-3} \frac{r_i^2}{r_{ij}^2} \frac{\underline{r}_j' \cdot \underline{r}_i - \underline{r}_i' \cdot \underline{r}_j - \underline{r}_j' \cdot \underline{r}_i + \underline{r}_i' \cdot \underline{r}_i}{r_i^2} = \\
&= -3 r_{ij}^{-3} \frac{r_i^2}{r_{ij}^2} \left[ \frac{\underline{r}_j' \cdot \underline{r}_j}{r_i^2} - \frac{\underline{r}_i' \cdot \underline{r}_j}{r_i^2} - \frac{\underline{r}_j' \cdot \underline{r}_i}{r_i^2} + \frac{\underline{r}_i' \cdot \underline{r}_i}{r_i^2} \right].
\end{aligned}$$

This, according to expressions (3.17), takes the form

$$\alpha'_{ij} = -3 \alpha_{ij} b_{ij} (b_{jji} - b_{iji} - b_{jii} + b_{iii}) \quad (i, j = 1, \dots, n \quad i \neq j). \tag{3.24}$$

We obtain the derivative  $b'_{ij}$  ( $i, j = 1, \dots, n \quad i \neq j$ ) from the following

$$b'_{ij} = \left( \frac{r_i^2}{r_{ij}^2} \right)' = 2 \frac{\underline{r}_i \cdot \underline{r}_i'}{r_{ij}^2} - 2 \frac{r_i^2}{r_{ij}^3} r_{ij}'$$

which with the help of the equations (3.15) and (3.16) becomes

$$\begin{aligned}
 b'_{ij} &= 2 \frac{\Gamma_i \frac{\Gamma'_i \cdot \Gamma_i}{\Gamma_i}}{\Gamma_{ij}^2} - 2 \frac{\Gamma_i^2}{\Gamma_{ij}^3} \frac{(\Gamma_j - \Gamma_i) \cdot (\Gamma'_j - \Gamma'_i)}{\Gamma_{ij}} = \\
 &= 2 \frac{\Gamma'_i \cdot \Gamma_i}{\Gamma_{ij}^2} - 2 \frac{\Gamma_i^4}{\Gamma_{ij}^4} \frac{(\Gamma_j - \Gamma_i) \cdot (\Gamma'_j - \Gamma'_i)}{\Gamma_i^2} = \\
 &= 2 \frac{\Gamma'_i \cdot \Gamma_i}{\Gamma_i^2} \frac{\Gamma_i^2}{\Gamma_{ij}^2} - 2 \left( \frac{\Gamma_i^2}{\Gamma_{ij}^2} \right)^2 \left( \frac{\Gamma_j \cdot \Gamma_j}{\Gamma_i^2} - \frac{\Gamma'_i \cdot \Gamma'_j}{\Gamma_i^2} - \frac{\Gamma_i \cdot \Gamma'_j}{\Gamma_i^2} + \frac{\Gamma'_i \cdot \Gamma_i}{\Gamma_i^2} \right).
 \end{aligned}$$

Introduction of expressions (3.17) gives

$$b'_{ij} = 2 b_{ij} b_{iii} - 2 b_{ij}^2 (b_{jji} - b_{yji} - b_{jii} + b_{iii}) \quad (i, j = 1 \dots n \quad i \neq j). \quad (3.25)$$

For the sake of convenience, the results of the above calculations are summarized in the following

$$\begin{aligned}
 \alpha'_i &= -3 \alpha_i b_{iii} \quad (i = 1, \dots, n), \\
 b'_{ijk} &= -(1+m_i) \alpha_i \delta_{ijk} - \delta_{ijk} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} \delta_{j\lambda k} - \\
 &\quad - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} \delta_{j\lambda k} + \gamma_{ijk} - 2 b_{ijk} b_{kkk} \quad (i, j, k = 1 \dots n), \\
 \gamma'_{ijk} &= -(1+m_i) \alpha_i b_{jik} - b_{jik} \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} b_{j\lambda k} - \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} b_{j\lambda k} - \\
 &\quad - (1+m_j) \alpha_j b_{ijk} - b_{ijk} \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} b_{i\mu k} - \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} b_{i\mu k} - \\
 &\quad - 2 \gamma_{ijk} b_{kkk} \quad (i, j, k = 1 \dots n), \\
 \delta'_{ijk} &= b_{ijk} + b_{jik} - 2 \delta_{ijk} b_{kkk} \quad (i, j, k = 1 \dots n), \\
 \alpha'_{ij} &= -3 \alpha_{ij} b_{ij} (b_{jji} - b_{yji} - b_{jii} + b_{iii}) \quad (i, j = 1 \dots n \quad i \neq j), \\
 b'_{ij} &= -2 b_{ij} (b_{ij} (b_{jji} - b_{yji} - b_{jii} + b_{iii}) - b_{iii}) \quad (i, j = 1 \dots n \quad i \neq j).
 \end{aligned} \quad (3.26)$$

Differentiation of equations (3.26) with respect to  $\tau$ , and the introduction of the same equations, as soon as the derivatives  $\alpha'_i$ ,

$\beta'_{ijk}, \gamma'_{ijk}, \delta'_{ijk} (i, j, k = 1 \dots n), \alpha'_{ij}, b'_{ij} (i, j = 1 \dots n, i \neq j)$  appear, gives the second-order derivatives of the expressions (3.17) as functions of the expressions.

In order to find the higher-order derivatives of the expressions (3.17), we can repeat this differentiation process, each time eliminating  $\alpha'_i$ ,  $\beta'_{ijk}, \gamma'_{ijk}, \delta'_{ijk} (i, j, k = 1 \dots n), \alpha'_{ij}, b'_{ij} (i, j = 1 \dots n, i \neq j)$  by means of equations (3.26) as the case demands.

As the next step in the course of the proof it will be shown that, by making use of expressions (3.17), we can actually obtain the derivatives

$\underline{r}_i^{(v)} \quad v \geq 3 \quad (i = 1, \dots, n)$  as functions of the position and the velocity vectors of the bodies  $\underline{r}_i, \underline{r}_i' \quad (i = 1, \dots, n)$ .

The equations of motion already give the second-order derivatives  $\underline{r}_i'' \quad (i = 1, \dots, n)$  in the desired form. On substituting expressions (3.17) into equation (3.10) we obtain

$$\underline{r}_i'' = \left[ -(1+m_i)\alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \right] \underline{r}_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha_{ij} - \alpha_j) \underline{r}_j \quad (i = 1, \dots, n). \quad (3.27)$$

Introducing a more general notation we can write this as follows

$$\underline{r}_i'' = \sum_{j=1}^n (C_{ij2} \underline{r}_j + D_{ij2} \underline{r}_j') \quad (i = 1, \dots, n), \quad (3.28)$$

where

$$C_{ii2} \equiv -(1+m_i)\alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \quad (i = 1, \dots, n),$$

$$C_{ij2} \equiv m_j (\alpha_{ij} - \alpha_j) \quad (i, j = 1, \dots, n, i \neq j), \quad (3.29)$$

$$D_{ij2} \equiv 0 \quad (i, j = 1, \dots, n).$$

The third-order derivative  $\tilde{\Gamma}_i^{(3)}$  ( $i=1, \dots, n$ ) is easily calculated by differentiating equation (3.27)

$$\begin{aligned} \tilde{\Gamma}_i^{(3)} = & \left[ -(1+m_i) \alpha'_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha'_{ij} \right] \tilde{\Gamma}_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha'_{ij} - \alpha'_j) \tilde{\Gamma}_j + \\ & + \left[ -(1+m_i) \alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \right] \tilde{\Gamma}'_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha_{ij} - \alpha_j) \tilde{\Gamma}'_j \quad (i=1, \dots, n), \end{aligned}$$

which upon substitution of equations (3.26) becomes

$$\begin{aligned} \tilde{\Gamma}_i^{(3)} = & \left[ 3(1+m_i) \alpha_i b_{iii} + \right. \\ & + 3 \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji}) \left. \right] \tilde{\Gamma}_i - \\ & - 3 \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha_{ij} b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji}) - \alpha_j b_{jjj}) \tilde{\Gamma}_j + \\ & + \left( -(1+m_i) \alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \right) \tilde{\Gamma}'_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha_{ij} - \alpha_j) \tilde{\Gamma}'_j \quad (i=1, \dots, n). \end{aligned} \quad (3.30)$$

We may write this in the general form of equation (3.28), that is

$$\tilde{\Gamma}_i^{(3)} = \sum_{j=1}^n (C_{ij3} \tilde{\Gamma}_j + D_{ij3} \tilde{\Gamma}'_j) \quad (i=1, \dots, n), \quad (3.31)$$

where

$$C_{ii3} \equiv 3 \left[ (1+m_i) \alpha_i b_{iii} + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji}) \right] \quad (i=1, \dots, n)$$

$$C_{ij3} \equiv -3m_j(\alpha_{ij}b_{ij}(\delta_{iii}-\delta_{jii}-\delta_{iji}+\delta_{jji})-\alpha_j\delta_{jjj}) \quad (i, j=1, \dots, n \quad i \neq j),$$

$$D_{ii3} \equiv -(1+m_i)\alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \quad (i=1, \dots, n),$$

$$D_{ij3} \equiv m_j(\alpha_{ij}-\alpha_j) \quad (i, j=1, \dots, n \quad i \neq j).$$

Having differentiated equation (3.30) once with respect to  $\tau$  and having made use of equations (3.26) and (3.27), as soon as the derivatives  $\alpha'_i, \delta'_{ijk}, \gamma'_{ijk}, \delta'_{ijk}, \tau_i''$  ( $i, j, k=1, \dots, n$ ),  $\alpha'_{ij}, \delta'_{ij}$  ( $i, j=1, \dots, n \quad i \neq j$ ) appear (and after substantial algebraic calculations), the fourth-order derivative

$$\tau_i^{(4)} \quad (i=1, \dots, n) \quad \text{is obtained}$$

$$\begin{aligned} \tau_i^{(4)} = & \left\{ (1+m_i)\alpha_i \cdot (-15\delta_{iii}^2 - 2(1+m_i)\alpha_i + 3\gamma_{iii}) + \right. \\ & + \sum_{\substack{j=1 \\ j \neq i}}^n \left[ (1+m_i)m_j\alpha_i (-\alpha_{ij} + 3(\alpha_{ij}-\alpha_j)\delta_{iji}) + \right. \\ & + 3m_j\alpha_{ij}b_{ij}(-5b_{ij}(\delta_{iii}-\delta_{jii}-\delta_{iji}+\delta_{jji})^2 + \gamma_{iii}-\gamma_{iji}-\gamma_{jii}+\gamma_{jji} + \\ & + (1+m_i)\alpha_i(\delta_{iji}-1) + (1+m_j)\alpha_j(\delta_{jii}-\delta_{jji}) + \\ & + m_\lambda \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n (\alpha_{i\lambda}(\delta_{i\lambda i}-\delta_{j\lambda i}+\delta_{iij}-1) + \alpha_\lambda(\delta_{j\lambda i}-\delta_{i\lambda i})) + \\ & + m_\mu \sum_{\substack{\mu=1 \\ \mu \neq j}}^n (\alpha_{j\mu}(\delta_{j\mu i}-\delta_{i\mu i}+\delta_{jii}-\delta_{jji}) + \alpha_\mu(\delta_{i\mu i}-\delta_{j\mu i})) \Big] + \\ & + m_i m_j (\alpha_{ij}-\alpha_j)(\alpha_{ji}-\alpha_i) + m_j \alpha_{ij} \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \Big] \tau_i - \\ & - \sum_{\substack{j=1 \\ j \neq i}}^n \left\{ 3 \left[ \alpha_i (4\delta_{iii}^2 + (1+m_i)\alpha_i - \gamma_{iii}) + \alpha_j \delta_{jjj}^2 + \right. \right. \\ & + \alpha_i \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda (\alpha_{i\lambda} - (\alpha_{i\lambda}-\alpha_\lambda)\delta_{i\lambda i}) + \end{aligned}$$

$$\begin{aligned}
& + 3m_j \alpha_{ij} b_{ij} \left( -5b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji})^2 + \gamma_{jjj} - \gamma_{iji} - \gamma_{jii} + \gamma_{jji} + \right. \\
& + (1+m_i) \alpha_i \delta_{iji} + (1+m_j) \alpha_j (\delta_{jii} - \delta_{jji} - 1) + 2(b_{iii}^2 - b_{jji}^2) + \\
& + m_\lambda \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n (\alpha_{i\lambda} (\delta_{i\lambda i} - \delta_{j\lambda i}) + \alpha_\lambda \delta_{j\lambda i}) + \\
& + m_\mu \sum_{\substack{\mu=1 \\ \mu \neq j}}^n (\alpha_{j\mu} (\delta_{j\mu i} - \delta_{i\mu i} + \delta_{j\mu j} + \delta_{jii} - \delta_{jji} - 1) + \alpha_\mu (\delta_{i\mu i} - \delta_{j\mu i} - \delta_{j\mu j})) \Big) \Big] + \\
& + m_j (\alpha_{ij} - \alpha_j) \left( (1+m_i) \alpha_i + (1+m_j) \alpha_j + \right. \\
& + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n m_\lambda \alpha_{i\lambda} + \sum_{\substack{\mu=1 \\ \mu \neq j}}^n m_\mu \alpha_{j\mu} \Big) \Big\} \underline{\Gamma}_j + \\
& + \sum_{\substack{\lambda=1 \\ \lambda \neq i}}^n \left( m_\lambda (\alpha_{i\lambda} - \alpha_\lambda) \sum_{\substack{j=1 \\ j \neq i \\ j \neq \lambda}}^n m_\lambda (\alpha_{\lambda j} - \alpha_j) \underline{\Gamma}_j \right) + \\
& + 6 \left[ (1+m_i) \alpha_i b_{iii} + \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji}) \right] \underline{\Gamma}'_i - \\
& - 6 \sum_{\substack{j=1 \\ j \neq i}}^n \left[ m_j (\alpha_{ij} b_{ij} (b_{iii} - b_{jii} - b_{iji} + b_{jji}) - \alpha_i b_{iii}) \right] \underline{\Gamma}'_j . \\
& \hspace{25em} (i=1, \dots, n) .
\end{aligned}
\tag{3.32}$$

Equation (3.32) obviously has the form

$$\underline{\Gamma}_i^{(4)} = \sum_{j=1}^n (C_{ij4} \underline{\Gamma}_j + D_{ij4} \underline{\Gamma}'_j) \quad (i = 1 \dots n) .$$

In a completely analogous manner, and since the expressions (3.17) are functions of the position and the velocity vectors of the bodies, one can find the derivatives of all orders of the position vectors,  $\underline{\Gamma}_i$  ( $i = 1 \dots n$ ), as functions of the position and velocity vectors of the bodies. It is also evident that these derivatives have the general form



$$\tilde{f}_i^{(\nu)} = \sum_{j=1}^n (C_{ij\nu} \tilde{f}_j + D_{ij\nu} \tilde{f}_j') \quad (i=1 \dots n) \quad \nu \geq 2, \quad (3.33)$$

and are continuous as algebraic combinations of continuous functions (see theorem 2).

The indices  $i, j, \nu$  mean that, each  $C_{ij\nu}$  or  $D_{ij\nu}$  is a different expression of  $\alpha_i, \beta_{ij\kappa}, \gamma_{ij\kappa}, \delta_{ij\kappa} (i, j, \kappa = 1, \dots, n), \alpha_{ij}, b_{ij} (i, j = 1, \dots, n, i \neq j)$  for different  $\tilde{f}_i (i = 1 \dots n)$  or different  $\tilde{f}_j (j = 1, 2, \dots, n)$  or different order of derivative.

If we consider  $\tilde{f}_i^{(0)} (i = 1, 2, \dots, n)$  to mean  $\tilde{f}_i (i = 1, \dots, n)$  then we obtain

$$\tilde{f}_i^{(\nu)} = \sum_{j=1}^n (C_{ij\nu} \tilde{f}_j + D_{ij\nu} \tilde{f}_j') \quad (i=1, \dots, n) \quad \nu \geq 0. \quad (3.34)$$

Comparing equation (3.34), for  $\nu = 0$ , with the equation

$\tilde{f}_i^{(0)} \equiv \tilde{f}_i (i = 1, \dots, n)$  it follows that the "coefficients"  $C_{ij0}, D_{ij0}$  have the values

$$\begin{aligned} C_{ij0} &= \delta_{ij} \quad (i, j = 1, \dots, n), \\ D_{ij0} &= 0 \quad (i, j = 1, \dots, n), \end{aligned} \quad \tau \in (-\infty, +\infty) \quad (3.35)$$

where  $\delta_{ij}$  is the Kronecker's delta.

Similarly, comparing equation (3.34), for  $\nu = 1$ , with the equation  $\tilde{r}_i^{(1)} \equiv \tilde{r}_i' \quad (i = 1, \dots, n)$  gives the values of  $C_{ij1}, D_{ij1}$

$$\begin{aligned} C_{ij1} &= 0 \quad (i, j = 1, \dots, n), \\ D_{ij1} &= \delta_{ij} \quad (i, j = 1, \dots, n). \end{aligned} \quad \tau \in (-\infty, +\infty) \quad (3.36)$$

We have already proved that the solution  $\tilde{r}_i(\tau) \quad (i=1, \dots, n)$  of the system (3.13) is defined in the open interval  $(-\infty, +\infty)$ , (except at the points of singularity), and all the derivatives of this exist in the same interval. Hence, we can form the Taylor's series for  $\tilde{r}_i(\tau) \quad (i=1, \dots, n)$  in powers of the independent variable  $\tau$  about some epoch point, say  $\tau_{i0} \quad (i = 1, \dots, n)$ .

$$\tilde{r}_i = \sum_{\nu=0}^{\infty} \tilde{r}_{i0}^{(\nu)} \frac{\tau^\nu}{\nu!} \quad (i = 1, \dots, n). \quad (3.37)$$

The proof that this series converges in an open interval  $(-\tau^*, \tau^*)$  is given in the appendix A-1.

In equation (3.37) we interpret  $\tilde{r}_{i0}^{(0)} \quad (i = 1, \dots, n)$  to mean  $\tilde{r}_i \quad (i = 1, \dots, n)$  at  $\tau = 0$  and  $\tilde{r}_{i0}^{(\nu)} \equiv \left( d^\nu \tilde{r}_i / d\tau^\nu \right)_{\tau=0} \quad (i=1, \dots, n), \nu \geq 1$ .

Later it will be shown that recursion formulae can be derived, which will provide numerical values for the power series coefficients. These formulae will enable us to compute  $\tilde{r}_{i0}^{(\nu)} / \nu! \quad (i = 1, \dots, n) \quad \nu \geq 2$  successively in terms of  $\tilde{r}_{i0}$  and  $\tilde{r}_{i0}' \quad (i = 1, \dots, n)$ . So as a first step we have to find formulae for the calculation of the velocity vectors  $\tilde{r}_{i0}' \quad (i = 1, \dots, n)$ .

Equation (3.34) gives the general form of the derivatives  $\tilde{r}_i^{(\nu)} \quad (i=1, \dots, n)$   $\nu \geq 0$  for every value of the time  $\tau$ . In the case of  $\tau = 0$  we obtain

$$\underline{r}_{i0}^{(\nu)} = \sum_{j=1}^n (C_{ij\nu 0} \underline{r}_{j0} + D_{ij\nu 0} \underline{r}_{j0}') \quad (i=1, \dots, n) \quad \nu \gg 0, \quad (3.38)$$

where

$$C_{ij\nu 0} \equiv C_{ij\nu} \Big|_{\tau=0} \quad (i, j=1, \dots, n) \quad \nu \gg 0,$$

$$D_{ij\nu 0} \equiv D_{ij\nu} \Big|_{\tau=0} \quad (i, j=1, \dots, n) \quad \nu \gg 0.$$

If, for the sake of convenience and simplicity, we introduce the notation

$$f_{ij\nu+1} \equiv C_{ij\nu 0} / \nu! \quad (i, j=1, \dots, n) \quad \nu \gg 0,$$

$$g_{ij\nu+1} \equiv D_{ij\nu 0} / \nu! \quad (i, j=1, \dots, n) \quad \nu \gg 0, \quad (3.39)$$

we get

$$\underline{r}_{i0}^{(\nu)} = \sum_{j=1}^n (f_{ij\nu+1} \underline{r}_{j0} + g_{ij\nu+1} \underline{r}_{j0}') \nu! \quad (i=1, \dots, n) \quad \nu \gg 0,$$

or

$$\frac{\underline{r}_{i0}^{(\nu)}}{\nu!} = \sum_{j=1}^n (f_{ij\nu+1} \underline{r}_{j0} + g_{ij\nu+1} \underline{r}_{j0}') \quad (i=1, \dots, n) \quad \nu \gg 0. \quad (3.40)$$

Substitution of equation (3.40) in the power series (3.37) yields

$$\underline{r}_i = \sum_{\nu=0}^{\infty} \left( \sum_{j=1}^n f_{ij\nu+1} \underline{r}_{j0} + g_{ij\nu+1} \underline{r}_{j0}' \right) \tau^{\nu} \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

or

$$\underline{r}_i = \sum_{j=1}^n \sum_{\nu=1}^{\infty} (f_{ij\nu} \underline{r}_{j0} + g_{ij\nu} \underline{r}_{j0}') \tau^{\nu-1} \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

or

$$\underline{r}_i = \sum_{j=1}^n \left\{ \left( \sum_{\nu=1}^{\infty} f_{ij\nu} \tau^{\nu-1} \right) \underline{r}_{j0} + \left( \sum_{\nu=1}^{\infty} g_{ij\nu} \tau^{\nu-1} \right) \underline{r}_{j0}' \right\} \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.41)$$

It is also obvious from equations (3.35), (3.36) and (3.39) that

$$\begin{aligned} f_{ij1} &= \delta_{ij} & (i, j = 1, \dots, n), \\ g_{ij1} &= 0 & (i, j = 1, \dots, n), \end{aligned}$$

and

$$\begin{aligned} f_{ij2} &= 0 & (i, j = 1, \dots, n), \\ g_{ij2} &= \delta_{ij} & (i, j = 1, \dots, n). \end{aligned} \quad (3.42)$$

Equation (3.41), being derived from equation (3.37), is valid at every interior point of the open interval  $(-\tau^*, \tau^*)$ , since this is the interval of convergence of the series (3.37). On the other hand, the vector  $\underline{\Gamma}_i$  ( $i = 1, \dots, n$ ), in relation (3.41), has a finite value in this interval of time. Hence, the coefficients of the vectors  $\underline{\Gamma}_{j0}$  and  $\underline{\Gamma}_{j0}'$  ( $j = 1, \dots, n$ ), which are in fact the series  $\sum_{v=1}^{\infty} f_{ijv} \tau^{v-1}$  and  $\sum_{v=1}^{\infty} g_{ijv} \tau^{v-1}$  ( $i, j = 1, \dots, n$ ), must have precise values at every point  $\tau \in (-\tau^*, \tau^*)$ . This means that the series converge within interval of convergence  $(-\tau^*, \tau^*)$ . Hence

$$\begin{aligned} \sum_{v=1}^{\infty} f_{ijv} \tau^{v-1} &= f_{ij} & (i, j = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \\ \sum_{v=1}^{\infty} g_{ijv} \tau^{v-1} &= g_{ij} & (i, j = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \end{aligned} \quad (3.43)$$

Using equations (3.43) equation (3.41) becomes

$$\underline{\Gamma}_i = \sum_{j=1}^n (f_{ij} \underline{\Gamma}_{j0} + g_{ij} \underline{\Gamma}_{j0}') \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.44)$$

Since  $\underline{\Gamma}_{j0}$  and  $\underline{\Gamma}_{j0}'$  ( $j = 1, \dots, n$ ) are constant, it is possible to differentiate equation (3.44) once with respect to  $\tau$  to obtain the velocity vector  $\underline{\Gamma}_i'$  ( $i = 1, \dots, n$ ) as

$$\underline{\Gamma}_i' = \sum_{j=1}^n (f_{ij}' \underline{\Gamma}_{j0} + g_{ij}' \underline{\Gamma}_{j0}') \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.45)$$

One more differentiation gives the acceleration vector  $\underline{\underline{r}}_i''$  ( $i=1, \dots, n$ ) as:

$$\underline{\underline{r}}_i'' = \sum_{j=1}^n (\dot{f}_{ij}'' \underline{\underline{r}}_{j0} + \dot{g}_{ij}'' \underline{\underline{r}}_{j0}') \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) \quad (3.46)$$

On the other hand equation (3.10) is valid for all the values of the modified time  $\tau$ , so changing the notation in this equation, we have

$$\underline{\underline{r}}_i'' = \left[ -(1+m_i) \frac{1}{\underline{\underline{r}}_i^3} - \sum_{\substack{k=1 \\ k \neq i}}^n m_k \frac{1}{\underline{\underline{r}}_{ik}^3} \right] \underline{\underline{r}}_i + \sum_{\substack{k=1 \\ k \neq i}}^n m_k \left( \frac{1}{\underline{\underline{r}}_{ik}^3} - \frac{1}{\underline{\underline{r}}_k^3} \right) \underline{\underline{r}}_k \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) \quad (3.47)$$

or, writing this in a more general form, we obtain

$$\underline{\underline{r}}_i'' = \sum_{k=1}^n A_{ik} \underline{\underline{r}}_k \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) \quad (3.48)$$

where

$$A_{ii} \equiv -(1+m_i) \frac{1}{\underline{\underline{r}}_i^3} - \sum_{\substack{k=1 \\ k \neq i}}^n m_k \frac{1}{\underline{\underline{r}}_{ik}^3} \quad (i=1, \dots, n) \quad (3.49)$$

$$A_{ik} \equiv m_k \left( \frac{1}{\underline{\underline{r}}_{ik}^3} - \frac{1}{\underline{\underline{r}}_k^3} \right) \quad (i, k=1, \dots, n \quad i \neq k).$$

Making use of equation (3.44), namely

$$\underline{\underline{r}}_k = \sum_{j=1}^n (\dot{f}_{kj} \underline{\underline{r}}_{j0} + \dot{g}_{kj} \underline{\underline{r}}_{j0}') \quad (k=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

equation (3.48) becomes

$$\underline{\underline{r}}_i'' = \sum_{k=1}^n A_{ik} \left( \sum_{j=1}^n (\dot{f}_{kj} \underline{\underline{r}}_{j0} + \dot{g}_{kj} \underline{\underline{r}}_{j0}') \right) \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

or 
$$\underline{\underline{r}}_i'' = \sum_{k=1}^n \sum_{j=1}^n (A_{ik} \dot{f}_{kj} \underline{\underline{r}}_{j0} + A_{ik} \dot{g}_{kj} \underline{\underline{r}}_{j0}') \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

$$\text{or } \underline{f}_i'' = \sum_{j=1}^n \left[ \left( \sum_{k=1}^n A_{ik} f_{kj} \right) \underline{f}_{j0} + \left( \sum_{k=1}^n A_{ik} g_{kj} \right) \underline{f}_{j0}' \right] \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.50)$$

Subtracting equation (3.46) from equation (3.50) we obtain

$$\sum_{j=1}^n \left[ \left( \sum_{k=1}^n A_{ik} f_{kj} - f_{ij}'' \right) \underline{f}_{j0} + \left( \sum_{k=1}^n A_{ik} g_{kj} - g_{ij}'' \right) \underline{f}_{j0}' \right] = 0 \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.51)$$

Since equation (3.51) is valid for every value of the variable  $\tau$  in the open interval  $(-\tau^*, \tau^*)$ , it can be written as

$$\sum_{j=1}^n \left[ \left( \sum_{k=1}^n A_{ik} f_{kj} - f_{ij}'' \right) \underline{f}_{j0} + \left( \sum_{k=1}^n A_{ik} g_{kj} - g_{ij}'' \right) \underline{f}_{j0}' \right] \equiv 0 \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.52)$$

So, the left hand side is identical to zero in the interval  $(-\tau^*, \tau^*)$ , and  $\underline{f}_{j0} \neq 0$ ,  $\underline{f}_{j0}' \neq 0$  ( $j=1, \dots, n$ ). It can easily be shown, that the expressions which appear as coefficients of  $\underline{f}_{j0}$  and  $\underline{f}_{j0}'$  in relation (3.52), must have the values zero in the interval  $(-\tau^*, \tau^*)$ . That is

$$\sum_{k=1}^n A_{ik} f_{kj} = f_{ij}'' \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \quad (3.53)$$

$$\sum_{k=1}^n A_{ik} g_{kj} = g_{ij}'' \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.54)$$

A function represented by power series has, in its interval of convergence, derivatives of every order which may be obtained by means of term-by-term successive differentiations. Hence, we easily obtain, by using equations (3.43), the derivatives  $f_{ij}''$  and  $g_{ij}''$  ( $i, j=1, \dots, n$ )

$$\begin{aligned} f_{ij}'' &= \sum_{v=3}^{\infty} (v-1)(v-2) f_{ijv} \tau^{v-3} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \\ g_{ij}'' &= \sum_{v=3}^{\infty} (v-1)(v-2) g_{ijv} \tau^{v-3} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \end{aligned} \quad (3.55)$$

or

$$\begin{aligned}
 f_{ij}'' &= \sum_{v=1}^{\infty} v(v+1) f_{ijv+2} \tau^{v-1} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \\
 g_{ij}'' &= \sum_{v=1}^{\infty} v(v+1) g_{ijv+2} \tau^{v-1} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*).
 \end{aligned} \quad (3.56)$$

Substitution of these equations and equations (3.43) in equations (3.53)

and (3.54) gives

$$\sum_{k=1}^n \left( A_{ik} \sum_{v=1}^{\infty} f_{k j v} \tau^{v-1} \right) = \sum_{v=1}^{\infty} f_{i j v+2} (v+1) v \tau^{v-1} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \quad (3.57)$$

$$\sum_{k=1}^n \left( A_{ik} \sum_{v=1}^{\infty} g_{k j v} \tau^{v-1} \right) = \sum_{v=1}^{\infty} g_{i j v+2} (v+1) v \tau^{v-1} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.58)$$

Since  $A_{ik} \quad (i, k=1, \dots, n)$  are functions of the variable  $\tau$ , and we do not know the analytical expressions  $A_{ik} = A_{ik}(\tau) \quad (i, k=1, \dots, n)$ , we can not solve the systems of the differential equations (3.57) and (3.58). So, in the first approximation we proceed as follows: We consider the functions  $A_{ik}(\tau) \quad (i, k=1, \dots, n)$  as constant and equal to  $A_{ik}(\tau_1) \quad (i, k=1, \dots, n)$ , where  $\tau_1$  belongs to the interval  $(-\tau^*, \tau^*)$ , then according to the identity theorem for power series the coefficients of terms of the same power of  $\tau$  must be equal. That is

$$v(v+1) f_{ijv+2} = \sum_{k=1}^n A_{ik} f_{k j v} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) \quad v \gg 1, \quad (3.59)$$

$$v(v+1) g_{ijv+2} = \sum_{k=1}^n A_{ik} g_{k j v} \quad (i, j=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) \quad v \gg 1. \quad (3.60)$$

Analytically, for every  $v=1, v=2, v=3, \dots$  we have

$$\begin{aligned}
 f_{ij3} &= \left( \sum_{k=1}^n A_{ik} f_{kj1} \right) / 1 \cdot 2, & f_{ij4} &= \left( \sum_{k=1}^n A_{ik} f_{kj2} \right) / 2 \cdot 3, \\
 f_{ij5} &= \left( \sum_{k=1}^n A_{ik} f_{kj3} \right) / 3 \cdot 4, & f_{ij6} &= \left( \sum_{k=1}^n A_{ik} f_{kj4} \right) / 4 \cdot 5, \\
 & \vdots & & \vdots \\
 f_{ij2\mu+1} &= \left( \sum_{k=1}^n A_{ik} f_{kj2\mu-1} \right) / (2\mu-1) \cdot 2\mu, & f_{ij2\mu+2} &= \left( \sum_{k=1}^n A_{ik} f_{kj2\mu} \right) / 2\mu \cdot (2\mu+1), \\
 & & & (i, j = 1, \dots, n)
 \end{aligned} \tag{3.61}$$

and

$$\begin{aligned}
 g_{ij3} &= \left( \sum_{k=1}^n A_{ik} g_{kj1} \right) / 1 \cdot 2, & g_{ij4} &= \left( \sum_{k=1}^n A_{ik} g_{kj2} \right) / 2 \cdot 3, \\
 g_{ij5} &= \left( \sum_{k=1}^n A_{ik} g_{kj3} \right) / 3 \cdot 4, & g_{ij6} &= \left( \sum_{k=1}^n A_{ik} g_{kj4} \right) / 4 \cdot 5, \\
 & \vdots & & \vdots \\
 g_{ij2\mu+1} &= \left( \sum_{k=1}^n A_{ik} g_{kj2\mu-1} \right) / (2\mu-1) \cdot 2\mu, & g_{ij2\mu+2} &= \left( \sum_{k=1}^n A_{ik} g_{kj2\mu} \right) / 2\mu \cdot (2\mu+1), \\
 & & & (i, j = 1, \dots, n).
 \end{aligned} \tag{3.62}$$

Since these relations correlate the coefficients of the series of order  $2\mu+1$  and  $2\mu+2$  with the coefficients of order  $2\mu-1$  and  $2\mu$  correspondingly, this enables us to find all the coefficients of the series in terms of the first two.

Introducing equations (3.42) in equations (3.61) and (3.62) we obtain

$$\begin{aligned}
 f_{ij1} &= \delta_{ij}, & f_{ij2} &= 0, \\
 f_{ij3} &= A_{ij}/2, & f_{ij4} &= 0, \\
 f_{ij5} &= \left( \sum_{k=1}^n A_{ik} A_{kj} \right) / 2 \cdot 3 \cdot 4, & f_{ij6} &= 0,
 \end{aligned} \tag{3.63}$$



$$f_{ij7} = \left( \sum_{k=1}^n \sum_{\lambda=1}^n A_{ik} A_{k\lambda} A_{\lambda j} \right) / 6! , \quad f_{ij8} = 0 ,$$

$$(i, j = 1, \dots, n) ,$$

and

$$\begin{aligned} g_{ij1} &= 0 , \\ g_{ij2} &= \delta_{ij} , \\ g_{ij3} &= 0 , \\ g_{ij4} &= A_{ij} / 2 \cdot 3 , \\ g_{ij5} &= 0 , \\ g_{ij6} &= \left( \sum_{k=1}^n A_{ik} A_{kj} \right) / 5! , \\ g_{ij7} &= 0 , \\ g_{ij8} &= \left( \sum_{k=1}^n \sum_{\lambda=1}^n A_{ik} A_{k\lambda} A_{\lambda j} \right) / 7! , \end{aligned} \quad (3.64)$$

$$(i, j = 1, \dots, n) .$$

Since the coefficients of the even order of the series  $f_{ij}$  ( $i, j = 1, \dots, n$ ) are equal to zero, these series have the form

$$f_{ij} = \sum_{v=1}^{\infty} f_{ij2v-1} \tau^{2v-2} \quad (i, j = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) . \quad (3.65)$$

Similarly, since the coefficients of the odd order of the series  $g_{ij}$  ( $i, j = 1, \dots, n$ ) are equal to zero, these series have the form

$$g_{ij} = \sum_{v=1}^{\infty} g_{ij2v} \tau^{2v-1} \quad (i, j = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) . \quad (3.66)$$

It has already been shown that the series  $f_{ij}$  and  $g_{ij}$

$(i, j = 1, \dots, n)$  converge in the interval  $(-\tau^*, \tau^*)$  (for the general case). Since in the first approximation the series were derived with the assumption that the functions  $A_{ik}(\tau)$  ( $i, k = 1, \dots, n$ ) are constant in the interval  $(-\tau^*, \tau^*)$ , we have to prove the convergence of these modified series.

Let us take  $A \equiv \max \{ |A_{ik}(\tau)| \mid (i, k = 1, 2, \dots, n), \tau \in (-\tau^*, \tau^*) \}$ . From equations (3.63) it is easily derived that

$$|f_{ij3} \tau^2| \ll A \frac{|\tau^2|}{2!} \equiv \alpha_1,$$

$$|f_{ij5} \tau^4| \ll A^2 \frac{|\tau^4|}{4!} \equiv \alpha_2,$$

$$|f_{ij7} \tau^6| \ll A^3 \frac{|\tau^6|}{6!} \equiv \alpha_3, \quad (3.67)$$

$$(i, j = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*)$$

$$|f_{ij, 2\mu+1} \tau^{2\mu}| \ll A^\mu \frac{n^{\mu-1} |\tau^{2\mu}|}{(2\mu)!} \equiv \alpha_\mu,$$

According to d'Alembert's ratio test the series

$$\sum_{\mu=1}^{\infty} \frac{A^\mu n^{\mu-1} |\tau^{2\mu}|}{(2\mu)!} \equiv \sum_{\mu=1}^{\infty} \alpha_\mu$$

is convergent for every time  $\tau \in (-\tau^*, \tau^*)$  because

$$\lim_{\mu \rightarrow \infty} \frac{\alpha_{\mu+1}}{\alpha_\mu} \equiv \lim_{\mu \rightarrow \infty} \frac{\frac{A^{\mu+1} n^\mu |\tau^{2\mu+2}|}{(2\mu+2)!}}{\frac{A^\mu n^{\mu-1} |\tau^{2\mu}|}{(2\mu)!}} = \lim_{\mu \rightarrow \infty} \frac{A n |\tau^2|}{(2\mu+1)(2\mu+2)} = 0 < 1.$$

Since this series converges, the absolute convergence, and so the simple convergence of the series  $f_{ij} \ (i, j = 1, \dots, n)$ , follows directly from the relations (3.67).

An entirely analogous process shows that the series  $g_{ij} \ (i, j = 1, 2, \dots, n)$  converges in the same interval of time  $(-\tau^*, \tau^*)$ .

Unfortunately, we have no analytical expressions for the  $f_{ij}$  and  $g_{ij}$  series where  $n > 2$ . Consequently, in practical applications we have to truncate the series after a finite number of terms.

An extensive investigation for different numbers of terms and different values of  $\tau$  shows that these series converge rapidly for values of  $\tau$  less than 0.2, provided that the number of terms is greater than 60.

The series can easily be made to converge more rapidly by changing the units of the masses and distances (and hence the values of the quantities  $A_{ik} \ (i, k = 1, \dots, n)$ ), and therefore the values of the coefficients of the series.

The calculation of the velocities of the bodies is now an easy problem, and is obtained as follows: Given the position vectors of the bodies at two different instants and their corresponding times, say  $\underline{r}_{i1}, \underline{r}_{i2}$   $(i = 1, \dots, n)$ ,  $t_1, t_2$  we can take

$$\begin{aligned} t_0 &\equiv t_1, & t &\equiv t_2, \\ \underline{r}_{i0} &\equiv \underline{r}_{i1}, & \underline{r}_i &\equiv \underline{r}_{i2} \quad (i = 1, \dots, n). \end{aligned}$$

Then the value of the modified time  $\tau = k(t - t_0)$  is calculated. With the presupposition that this value is included in the interval of convergence of the series (3.37), equations (3.49), (3.63) and (3.64) are used to calculate the values of the series  $f_{ij}, g_{ij} \ (i, j = 1, 2, \dots, n)$ . Then the solution of the system

$$\underline{r}_i = \sum_{j=1}^n (f_{ij} \underline{r}_{j0} + g_{ij} \underline{r}'_{j0}) \quad (i=1, \dots, n)$$

gives the velocity vectors of the bodies,  $\underline{r}'_{j0}$  ( $j=1, \dots, n$ ), with respect to the known position vectors  $\underline{r}_{j0}$  ( $j=1, \dots, n$ ) and  $\underline{r}_i$  ( $i=1, \dots, n$ ).

Having found the velocity vectors as functions of the position vectors of the bodies, we now return to the differential equations (3.13) which describe the relative motion of the bodies.

We will next develop a method for the calculation of the coefficients of the power series (3.37), which is the solution of the system (3.13).

If we resolve the vector series (3.37) into components series then the solution has the form

$$\begin{aligned} x_i &= \sum_{v=1}^{\infty} x_{iv} \tau^{v-1}, \\ y_i &= \sum_{v=1}^{\infty} y_{iv} \tau^{v-1}, \\ z_i &= \sum_{v=1}^{\infty} z_{iv} \tau^{v-1}, \end{aligned} \quad (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \quad (3.68)$$

where

$$\underline{r}_{i0}^{(v)} / v! \equiv (x_{iv+1}, y_{iv+1}, z_{iv+1}) \quad (i=1, \dots, n) \quad v \geq 0.$$

Note that the above series are initiated at  $v=1$ , as this change in notation will make subsequent numerical calculations (with the help of computer) feasible.

The solution (3.68) must be subjected to certain initial conditions. In order to find them the series (3.68) are considered at time  $\tau=0$ . It is obvious that

$$x_{i\tau=0} = x_{i1} ,$$

$$y_{i\tau=0} = y_{i1} ,$$

$$z_{i\tau=0} = z_{i1} ,$$

$$(i = 1, \dots, n) .$$

(3.69)

Hence, the co-ordinates of the positions of the bodies, at time  $\tau = 0$  are equal to the first terms of the power series (3.68).

Differentiating once equation (3.68) with respect to  $\tau$ , the following is obtained

$$x'_i = u_i = \sum_{v=2}^{\infty} x_{iv} (v-1) \tau^{v-2} ,$$

$$y'_i = v_i = \sum_{v=2}^{\infty} y_{iv} (v-1) \tau^{v-2} ,$$

$$z'_i = w_i = \sum_{v=2}^{\infty} z_{iv} (v-1) \tau^{v-2} ,$$

$$(i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) .$$

(3.70)

At the point  $\tau = 0$  equations (3.70) give

$$x'_{i\tau=0} = u_{i\tau=0} = x_{i2} ,$$

$$y'_{i\tau=0} = v_{i\tau=0} = y_{i2} ,$$

$$z'_{i\tau=0} = w_{i\tau=0} = z_{i2} ,$$

$$(i = 1, \dots, n) .$$

(3.71)

Therefore, the components of the velocities of the bodies at the point  $\tau = 0$  are equal to the coefficients of the second terms of the series (3.68).

Equations (3.69) and (3.71) give the initial conditions to which the power series solution must be subjected.

The next step in this process is to obtain expansions in power series for the other variables of the equations of motion.

We work in three-dimensional Euclidean space, hence the relation

$$\bar{r}_i^2 = \bar{x}_i^2 + \bar{y}_i^2 + \bar{z}_i^2 \quad (i = 1, \dots, n), \quad (3.72)$$

is valid for every value of the time  $\tau$ . Since the functions  $\bar{x}_i = \bar{x}_i(\tau)$ ,  $\bar{y}_i = \bar{y}_i(\tau)$  and  $\bar{z}_i = \bar{z}_i(\tau)$  ( $i = 1, \dots, n$ ) are represented by power series in the interval  $(-\tau^*, \tau^*)$ , and the function  $\bar{r}_i = \bar{r}_i(\tau)$  ( $i = 1, \dots, n$ ) has derivatives of all orders, according to the theory of infinite series, the relation (3.72) assures us of a power series expansion of the form

$$\bar{r}_i = \sum_{\nu=1}^{\infty} \bar{r}_{i\nu} \tau^{\nu-1} \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.73)$$

Differentiation of equations (3.72) and (3.73) gives

$$\begin{aligned} \bar{r}_i \bar{r}_i' &= \bar{x}_i \bar{x}_i' + \bar{y}_i \bar{y}_i' + \bar{z}_i \bar{z}_i' \quad (i = 1, \dots, n), \\ \bar{r}_i' &= \sum_{\nu=2}^{\infty} \bar{r}_{i\nu} (\nu-1) \tau^{\nu-2} \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \end{aligned} \quad (3.74)$$

By introducing equations (3.68), (3.70), (3.73) and the second of the equations (3.74) in the first of the equations (3.74), the following is obtained

$$\begin{aligned} \left( \sum_{\nu=1}^{\infty} \bar{r}_{i\nu} \tau^{\nu-1} \right) \left( \sum_{\nu=2}^{\infty} \bar{r}_{i\nu} (\nu-1) \tau^{\nu-2} \right) &= \left( \sum_{\nu=1}^{\infty} \bar{x}_{i\nu} \tau^{\nu-1} \right) \left( \sum_{\nu=2}^{\infty} \bar{x}_{i\nu} (\nu-1) \tau^{\nu-2} \right) + \\ &+ \left( \sum_{\nu=1}^{\infty} \bar{y}_{i\nu} \tau^{\nu-1} \right) \left( \sum_{\nu=2}^{\infty} \bar{y}_{i\nu} (\nu-1) \tau^{\nu-2} \right) + \left( \sum_{\nu=1}^{\infty} \bar{z}_{i\nu} \tau^{\nu-1} \right) \left( \sum_{\nu=2}^{\infty} \bar{z}_{i\nu} (\nu-1) \tau^{\nu-2} \right) \\ &\quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \end{aligned}$$

$$\begin{aligned}
\text{or } \sum_{v=1}^{\infty} \left( \sum_{k=1}^v \bar{r}_{ik} \bar{r}_{i v+2-k} (v+1-k) \right) \tau^{v-1} &= \sum_{v=1}^{\infty} \left( \sum_{k=1}^v \chi_{ik} \chi_{i v+2-k} (v+1-k) \right) \tau^{v-1} + \\
&+ \sum_{v=1}^{\infty} \left( \sum_{k=1}^v y_{ik} y_{i v+2-k} (v+1-k) \right) \tau^{v-1} + \quad (3.75) \\
&+ \sum_{v=1}^{\infty} \left( \sum_{k=1}^v z_{ik} z_{i v+2-k} (v+1-k) \right) \tau^{v-1} \\
(i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) .
\end{aligned}$$

By equating the coefficients of terms of the same power of  $\tau$ , it follows

$$\begin{aligned}
\text{that } \sum_{k=1}^v \bar{r}_{ik} \bar{r}_{i v+2-k} (v+1-k) &= \sum_{k=1}^v \chi_{ik} \chi_{i v+2-k} (v+1-k) + \\
&+ \sum_{k=1}^v y_{ik} y_{i v+2-k} (v+1-k) + \\
&+ \sum_{k=1}^v z_{ik} z_{i v+2-k} (v+1-k) \quad (i=1, \dots, n) \quad v \geq 1,
\end{aligned}$$

$$\text{or } \sum_{k=1}^v \bar{r}_{ik} \bar{r}_{i v+2-k} (v+1-k) = \sum_{k=1}^v (\chi_{ik} \chi_{i v+2-k} + y_{ik} y_{i v+2-k} + z_{ik} z_{i v+2-k}) (v+1-k) \quad (i=1, \dots, n) \quad v \geq 1,$$

$$\begin{aligned}
\text{or } v \cdot \bar{r}_{i1} \bar{r}_{i v+1} + \sum_{k=2}^v \bar{r}_{ik} \bar{r}_{i v+2-k} (v+1-k) &= \\
= \sum_{k=1}^v (\chi_{ik} \chi_{i v+2-k} + y_{ik} y_{i v+2-k} + z_{ik} z_{i v+2-k}) (v+1-k) \quad (i=1, \dots, n) \quad v \geq 1.
\end{aligned}$$

hence

$$\begin{aligned}
\bar{r}_{i v+1} &= \frac{1}{\bar{r}_{i1} v} \left[ - \sum_{k=2}^v \bar{r}_{ik} \bar{r}_{i v+2-k} (v+1-k) + \sum_{k=1}^v (\chi_{ik} \chi_{i v+2-k} + y_{ik} y_{i v+2-k} + z_{ik} z_{i v+2-k}) (v+1-k) \right] \quad (3.76) \\
(i=1, \dots, n) \quad v \geq 1.
\end{aligned}$$

This relation gives the coefficients of every order (greater than two) of the series (3.73) in terms of the lower order coefficients of the same series, and in terms of the lower or equal order coefficients of the series (3.68).

In order to find the first order coefficient,  $\bar{r}_{i1}$  ( $i=1, \dots, n$ ), the series (3.73) is considered at the point  $\tau=0$  and gives

$$\bar{r}_{i\tau=0} = \bar{r}_{i1} \quad (i=1, 2, \dots, n). \quad (3.77)$$

On the other hand, equation (3.72), at the point  $\tau=0$  gives

$$\bar{r}_{i\tau=0} = (\chi_{i\tau=0}^2 + y_{i\tau=0}^2 + Z_{i\tau=0}^2)^{1/2} \quad (i=1, \dots, n), \quad (3.78)$$

and substituting equations (3.69) and (3.77), equation (3.78) yields

$$\bar{r}_{i1} = (\chi_{i1}^2 + y_{i1}^2 + Z_{i1}^2)^{1/2} \quad (i=1, \dots, n). \quad (3.79)$$

As in the case of the function  $\bar{r}_i = \bar{r}_i(\tau)$  ( $i=1, \dots, n$ ), it can be similarly proved that the function  $\bar{r}_{ij} = \bar{r}_{ij}(\tau)$  ( $i, j=1, \dots, n$   $i \neq j$ ) possesses a power series expansion in the interval  $(-\tau^*, \tau^*)$ , that is

$$\bar{r}_{ij} = \sum_{\nu=1}^{\infty} \bar{r}_{ij\nu} \tau^{\nu-1} \quad (i, j=1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*). \quad (3.80)$$

The equation

$$\bar{r}_{ij}^2 = (\chi_i - \chi_j)^2 + (y_i - y_j)^2 + (Z_i - Z_j)^2 \quad (i, j=1, \dots, n \ i \neq j), \quad (3.81)$$

is valid for every value of the time  $\tau$ .



Differentiation of equations (3.80) and (3.81) gives

$$\begin{aligned} \widetilde{r}_{ij} \widetilde{r}'_{ij} &= (\chi_i - \chi_j)(\chi'_i - \chi'_j) + (y_i - y_j)(y'_i - y'_j) + (z_i - z_j)(z'_i - z'_j) \quad (i, j = 1, \dots, n \quad i \neq j), \\ \widetilde{r}'_{ij} &= \sum_{v=2}^{\infty} \widetilde{r}_{ijv} (v-1) \tau^{v-2} \quad (i, j = 1, \dots, n \quad i \neq j) \quad \tau \in (-\tau^*, \tau^*). \end{aligned} \quad (3.82)$$

Making use of the equations (3.68), (3.70) and the second of the equations (3.82), the first of the equations (3.82) becomes

$$\begin{aligned} \left( \sum_{v=1}^{\infty} \widetilde{r}_{ijv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} \widetilde{r}_{ijv} (v-1) \tau^{v-2} \right) &= \left( \sum_{v=1}^{\infty} \chi_{iv} \tau^{v-1} - \sum_{v=1}^{\infty} \chi_{jv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} \chi_{iv} (v-1) \tau^{v-2} - \sum_{v=2}^{\infty} \chi_{jv} (v-1) \tau^{v-2} \right) + \\ &+ \left( \sum_{v=1}^{\infty} y_{iv} \tau^{v-1} - \sum_{v=1}^{\infty} y_{jv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} y_{iv} (v-1) \tau^{v-2} - \sum_{v=2}^{\infty} y_{jv} (v-1) \tau^{v-2} \right) + \\ &+ \left( \sum_{v=1}^{\infty} z_{iv} \tau^{v-1} - \sum_{v=1}^{\infty} z_{jv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} z_{iv} (v-1) \tau^{v-2} - \sum_{v=2}^{\infty} z_{jv} (v-1) \tau^{v-2} \right) \\ &\quad (i, j = 1, \dots, n \quad i \neq j) \quad \tau \in (-\tau^*, \tau^*), \\ \text{or } \left( \sum_{v=1}^{\infty} \widetilde{r}_{ijv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} \widetilde{r}_{ijv} (v-1) \tau^{v-2} \right) &= \left( \sum_{v=1}^{\infty} (\chi_{iv} - \chi_{jv}) \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} (v-1) (\chi_{iv} - \chi_{jv}) \tau^{v-2} \right) + \\ &+ \left( \sum_{v=1}^{\infty} (y_{iv} - y_{jv}) \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} (v-1) (y_{iv} - y_{jv}) \tau^{v-2} \right) + \\ &+ \left( \sum_{v=1}^{\infty} (z_{iv} - z_{jv}) \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} (v-1) (z_{iv} - z_{jv}) \tau^{v-2} \right) \\ &\quad (i, j = 1, \dots, n \quad i \neq j) \quad \tau \in (-\tau^*, \tau^*), \end{aligned}$$

therefore

$$\begin{aligned} \sum_{v=1}^{\infty} \left( \sum_{k=1}^v \widetilde{r}_{ijk} \widetilde{r}_{ijv+2-k} (v+1-k) \right) \tau^{v-1} &= \sum_{v=1}^{\infty} \left( \sum_{k=1}^v (\chi_{ik} - \chi_{jk}) (\chi_{iv+2-k} - \chi_{jv+2-k}) (v+1-k) \right) \tau^{v-1} + \\ &+ \sum_{v=1}^{\infty} \left( \sum_{k=1}^v (y_{ik} - y_{jk}) (y_{iv+2-k} - y_{jv+2-k}) (v+1-k) \right) \tau^{v-1} + \\ &+ \sum_{v=1}^{\infty} \left( \sum_{k=1}^v (z_{ik} - z_{jk}) (z_{iv+2-k} - z_{jv+2-k}) (v+1-k) \right) \tau^{v-1} \\ &\quad (i, j = 1, \dots, n \quad i \neq j) \quad \tau \in (-\tau^*, \tau^*). \end{aligned}$$

Equating the coefficients of terms of the same power of  $\tau$  the following is obtained

$$\begin{aligned} \sum_{k=1}^{\nu} \bar{r}_{ij k} \bar{r}_{ij \nu+2-k} (\nu+1-k) = & \sum_{k=1}^{\nu} (\chi_{ik} - \chi_{jk}) (\chi_{i \nu+2-k} - \chi_{j \nu+2-k}) (\nu+1-k) + \\ & + \sum_{k=1}^{\nu} (\gamma_{ik} - \gamma_{jk}) (\gamma_{i \nu+2-k} - \gamma_{j \nu+2-k}) (\nu+1-k) + \\ & + \sum_{k=1}^{\nu} (z_{ik} - z_{jk}) (z_{i \nu+2-k} - z_{j \nu+2-k}) (\nu+1-k) \\ & (i, j = 1, \dots, n \quad i \neq j) \quad \nu \gg 1 \end{aligned}$$

or

$$\begin{aligned} \nu \bar{r}_{ij 1} \bar{r}_{ij \nu+1} + \sum_{k=2}^{\nu} \bar{r}_{ij k} \bar{r}_{ij \nu+2-k} (\nu+1-k) = \\ = \sum_{k=1}^{\nu} (\nu+1-k) \left[ (\chi_{ik} - \chi_{jk}) (\chi_{i \nu+2-k} - \chi_{j \nu+2-k}) + \right. \\ \left. + (\gamma_{ik} - \gamma_{jk}) (\gamma_{i \nu+2-k} - \gamma_{j \nu+2-k}) + (z_{ik} - z_{jk}) (z_{i \nu+2-k} - z_{j \nu+2-k}) \right] \\ (i, j = 1, \dots, n \quad i \neq j) \quad \nu \gg 1 \end{aligned}$$

Solution of this equation with respect to  $\bar{r}_{ij \nu+1}$  gives:

$$\begin{aligned} \bar{r}_{ij \nu+1} = & \left\{ - \sum_{k=2}^{\nu} \bar{r}_{ij k} \bar{r}_{ij \nu+2-k} (\nu+1-k) + \sum_{k=1}^{\nu} (\nu+1-k) \left[ (\chi_{ik} - \chi_{jk}) (\chi_{i \nu+2-k} - \chi_{j \nu+2-k}) + \right. \right. \\ & \left. \left. + (\gamma_{ik} - \gamma_{jk}) (\gamma_{i \nu+2-k} - \gamma_{j \nu+2-k}) + (z_{ik} - z_{jk}) (z_{i \nu+2-k} - z_{j \nu+2-k}) \right] \right\} / \nu \bar{r}_{ij 1} \quad (3.83) \\ & (i, j = 1, \dots, n \quad i \neq j) \quad \nu \gg 1 \end{aligned}$$

and since this relation gives the coefficients  $\bar{r}_{ij \nu}$  for  $\nu \gg 2$  the coefficient  $\bar{r}_{ij 1}$  ( $i, j = 1, \dots, n \quad i \neq j$ ) must be found by a different method. The

power series (3.80), at the point  $\tau=0$ , reduces to the relation

$$\bar{r}_{ij \tau=0} = \bar{r}_{ij1} \quad (i, j = 1, \dots, n \quad i \neq j), \quad (3.84)$$

while, on the other hand, equation (3.81) at the point  $\tau=0$ , becomes

$$\bar{r}_{ij \tau=0} = \left[ (\chi_{i \tau=0} - \chi_{j \tau=0})^2 + (\gamma_{i \tau=0} - \gamma_{j \tau=0})^2 + (Z_{i \tau=0} - Z_{j \tau=0})^2 \right]^{\frac{1}{2}} \quad (i, j = 1, \dots, n \quad i \neq j), \quad (3.85)$$

which, by introduction of equations (3.69) and (3.84), becomes

$$\bar{r}_{ij1} = \left[ (\chi_{i1} - \chi_{j1})^2 + (\gamma_{i1} - \gamma_{j1})^2 + (Z_{i1} - Z_{j1})^2 \right]^{\frac{1}{2}} \quad (i, j = 1, \dots, n \quad i \neq j). \quad (3.86)$$

Now, because the function  $\bar{r}_i = \bar{r}_i(\tau) \quad (i = 1, \dots, n)$  can be expressed as a power series in the open interval  $(-\tau^*, \tau^*)$ , the same will be valid for the function  $R_i = \bar{r}_i^{-3}(\tau) \quad (i = 1, \dots, n)$  in the same interval of time. Hence, it can be written that

$$\bar{r}_i^{-3} = \sum_{\nu=1}^{\infty} R_{i\nu} \tau^{\nu-1} \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.87)$$

Differentiating  $\bar{r}_i^{-3} \quad (i = 1, \dots, n)$  with respect to  $\tau$  gives

$$(\bar{r}_i^{-3})' = \sum_{\nu=2}^{\infty} R_{i\nu} (\nu-1) \tau^{\nu-2} \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*), \quad (3.88)$$

also

$$(\bar{r}_i^{-3})' = -3 \bar{r}_i^{-4} \bar{r}_i' \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

or 
$$(\bar{r}_i^{-3})' \bar{r}_i = -3 \bar{r}_i^{-3} \bar{r}_i' \quad (i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*). \quad (3.89)$$

The last equation, by introduction of equations (3.73), (3.74), (3.87) and (3.88), becomes

$$\left( \sum_{v=1}^{\infty} \tilde{r}_{iv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} R_{iv} (v-1) \tau^{v-2} \right) = -3 \left( \sum_{v=1}^{\infty} R_{iv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} \tilde{r}_{iv} (v-1) \tau^{v-2} \right),$$

or

$$\sum_{v=1}^{\infty} \left( \sum_{k=1}^v \tilde{r}_{ik} R_{iv+2-k} (v+1-k) \right) \tau^{v-1} = -3 \sum_{v=1}^{\infty} \left( \sum_{k=1}^v R_{ik} \tilde{r}_{iv+2-k} (v+1-k) \right) \tau^{v-1}$$

$$(i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*),$$

By equating the coefficients of terms of the same power of  $\tau$  it follows that

$$\sum_{k=1}^v \tilde{r}_{ik} R_{iv+2-k} (v+1-k) = -3 \sum_{k=1}^v R_{ik} \tilde{r}_{iv+2-k} (v+1-k) \quad (i=1, \dots, n) \quad v \gg 1,$$

or

$$v \tilde{r}_{i1} R_{iv+1} + \sum_{k=2}^v \tilde{r}_{ik} R_{iv+2-k} (v+1-k) = -3 \sum_{k=1}^v R_{ik} \tilde{r}_{iv+2-k} (v+1-k)$$

$$(i=1, \dots, n) \quad v \gg 1,$$

and the solution with respect to  $R_{iv+1}$  yields the result

$$R_{iv+1} = \left[ - \sum_{k=2}^v (v+1-k) \tilde{r}_{ik} R_{iv+2-k} - 3 \sum_{k=1}^v R_{ik} \tilde{r}_{iv+2-k} (v+1-k) \right] / v \tilde{r}_{i1} \quad (3.90)$$

$$(i=1, \dots, n) \quad v \gg 1.$$

The coefficient  $R_{i1}$  ( $i=1, \dots, n$ ) is obtained as follows: From the power series expansion of  $\tilde{r}_i^{-3}$  ( $i=1, \dots, n$ ), at time  $\tau=0$ , it is found that

$$\tilde{r}_{i\tau=0}^{-3} = R_{i1} \quad (i=1, \dots, n),$$

which, with equations (3.77) and (3.79), gives

$$R_{i1} = (\chi_{i1}^2 + y_{i1}^2 + z_{i1}^2)^{-3/2} \quad (i=1, \dots, n). \quad (3.91)$$

Now, it can be easily proved that the function  $\bar{r}_{ij}^{-3} = R_{ij}(\tau)$  ( $i, j = 1, \dots, n \ i \neq j$ ) possesses a power series expansion in the interval  $(-\tau^*, \tau^*)$ . Consider, therefore

$$\bar{r}_{ij}^{-3} = \sum_{v=1}^{\infty} R_{ijv} \tau^{v-1} \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*), \quad (3.92)$$

then differentiating  $\bar{r}_{ij}^{-3}$  ( $i, j = 1, \dots, n \ i \neq j$ ), with respect to  $\tau$ , gives

$$(\bar{r}_{ij}^{-3})' = \sum_{v=2}^{\infty} R_{ijv} (v-1) \tau^{v-2} \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*), \quad (3.93)$$

also

$$(\bar{r}_{ij}^{-3})' = -3 \bar{r}_{ij}^{-4} \bar{r}_{ij}' \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*),$$

or

$$\bar{r}_{ij} (\bar{r}_{ij}^{-3})' = -3 \bar{r}_{ij}^{-3} \bar{r}_{ij}' \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*), \quad (3.94)$$

Equation (3.94), by introduction of equations (3.80), (3.82), (3.92) and (3.93), becomes

$$\begin{aligned} & \left( \sum_{v=1}^{\infty} \bar{r}_{ijv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} R_{ijv} (v-1) \tau^{v-2} \right) = \\ & = -3 \left( \sum_{v=1}^{\infty} R_{ijv} \tau^{v-1} \right) \left( \sum_{v=2}^{\infty} \bar{r}_{ijv} (v-1) \tau^{v-2} \right) \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*), \end{aligned}$$

or

$$\begin{aligned} & \sum_{v=1}^{\infty} \left( \sum_{k=1}^v (v+1-k) \bar{r}_{ijk} R_{ijv+2-k} \right) \tau^{v-1} = \\ & = -3 \sum_{v=1}^{\infty} \left( \sum_{k=1}^v (v+1-k) R_{ijk} \bar{r}_{ijv+2-k} \right) \tau^{v-1} \quad (i, j = 1, \dots, n \ i \neq j) \quad \tau \in (-\tau^*, \tau^*). \end{aligned}$$

Making use of the identity theorem for power series we obtain

$$\sum_{k=1}^{\nu} (\nu+1-k) \tilde{r}_{ijk} R_{ij\nu+2-k} =$$

$$= -3 \sum_{k=1}^{\nu} (\nu+1-k) R_{ijk} \tilde{r}_{ij\nu+2-k} \quad (i, j=1, \dots, n \quad i \neq j) \quad \nu \gg 1$$

or

$$\nu \tilde{r}_{ij1} R_{ij\nu+1} + \sum_{k=2}^{\nu} (\nu+1-k) \tilde{r}_{ijk} R_{ij\nu+2-k} =$$

$$= -3 \sum_{k=1}^{\nu} (\nu+1-k) R_{ijk} \tilde{r}_{ij\nu+2-k} \quad (i, j=1, \dots, n \quad i \neq j) \quad \nu \gg 1$$

Solution with respect to  $R_{ij\nu+1}$  ( $i, j=1, \dots, n \quad i \neq j$ ) yields the result

$$R_{ij\nu+1} = \left[ -\sum_{k=2}^{\nu} (\nu+1-k) \tilde{r}_{ijk} R_{ij\nu+2-k} - 3 \sum_{k=1}^{\nu} (\nu+1-k) R_{ijk} \tilde{r}_{ij\nu+2-k} \right] / \nu \tilde{r}_{ij1}$$

$$(i, j=1, \dots, n \quad i \neq j) \quad \nu \gg 1. \quad (3.95)$$

In order to find the first order coefficient  $R_{ij1}$  ( $i, j=1, 2, \dots, n \quad i \neq j$ ), the series (3.92) is considered at the point  $\tau = 0$ . Evidently

$$R_{ij1} = \tilde{r}_{ij}^{-3} \Big|_{\tau=0} \quad (i, j=1, \dots, n \quad i \neq j),$$

which, with equations (3.84) and (3.86), becomes

$$R_{ij1} = \left[ (x_{i1} - x_{j1})^2 + (y_{i1} - y_{j1})^2 + (z_{i1} - z_{j1})^2 \right]^{-3/2} \quad (i, j=1, \dots, n \quad i \neq j). \quad (3.96)$$

The co-ordinates of the position vectors of the bodies, being considered as functions of the independent variable  $\tau$  can be expanded in series (3.68). Hence, their first-order derivatives have power series expansions with the same interval of convergence  $(-\tau^*, \tau^*)$ , which are

$$x'_i \equiv u_i = \sum_{\nu=1}^{\infty} u_{i\nu} \tau^{\nu-1},$$

$$y'_i \equiv v_i = \sum_{\nu=1}^{\infty} v_{i\nu} \tau^{\nu-1}, \quad (3.97)$$

$$Z'_i \equiv W_i = \sum_{\nu=1}^{\infty} W_{i\nu} \tau^{\nu-1} \\ (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) .$$

Using expansions (3.70), the following equations are easily obtained

$$\begin{aligned} \sum_{\nu=2}^{\infty} \chi_{i\nu} (\nu-1) \tau^{\nu-2} &= \sum_{\nu=1}^{\infty} u_{i\nu} \tau^{\nu-1} , \\ \sum_{\nu=2}^{\infty} y_{i\nu} (\nu-1) \tau^{\nu-2} &= \sum_{\nu=1}^{\infty} v_{i\nu} \tau^{\nu-1} , \\ \sum_{\nu=2}^{\infty} Z_{i\nu} (\nu-1) \tau^{\nu-2} &= \sum_{\nu=1}^{\infty} W_{i\nu} \tau^{\nu-1} , \end{aligned} \\ (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*) .$$

The above three equations hold for every value of  $\tau$  in the common interval of convergence of the series, hence the identity theorem for power series secures that the coefficients of terms of the same power of  $\tau$  are equal. That is

$$\begin{aligned} \nu \chi_{i\nu+1} &= u_{i\nu} \quad \text{or} \quad \chi_{i\nu+1} = u_{i\nu} / \nu , \\ \nu y_{i\nu+1} &= v_{i\nu} \quad \text{or} \quad y_{i\nu+1} = v_{i\nu} / \nu , \\ \nu Z_{i\nu+1} &= W_{i\nu} \quad \text{or} \quad Z_{i\nu+1} = W_{i\nu} / \nu , \end{aligned} \tag{3.98}$$

$$(i=1, \dots, n) \quad \nu \gg 1 .$$

The equations of motion give the last three of the recursion formulae. Equation (3.10) is equivalent to the following equations for the co-ordinates  $\chi_i, y_i, Z_i$  ( $i=1, \dots, n$ )

$$\begin{aligned} \chi''_i = u'_i &= -(1+m_i) \frac{\chi_i}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{\chi_i - \chi_j}{r_{ij}^3} + \frac{\chi_j}{r_j^3} \right) , \\ y''_i = v'_i &= -(1+m_i) \frac{y_i}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{y_i - y_j}{r_{ij}^3} + \frac{y_j}{r_j^3} \right) , \end{aligned} \tag{3.99}$$

$$Z''_i = W'_i = -(1+m_i) \frac{Z_i}{r_i^3} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \frac{Z_i - Z_j}{r_{ij}^3} + \frac{Z_j}{r_j^3} \right),$$

$$(i = 1, \dots, n).$$

Introduction of the power series expansions (3.68), (3.87), (3.92), (3.97) in equations (3.99) gives

$$\begin{aligned} \sum_{v=2}^{\infty} u_{iv} (v-1) \tau^{v-2} = & -(1+m_i) \left( \sum_{v=1}^{\infty} x_{iv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{iv} \tau^{v-1} \right) - \\ & - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left\{ \left( \sum_{v=1}^{\infty} (x_{iv} - x_{jv}) \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{ijv} \tau^{v-1} \right) + \left( \sum_{v=1}^{\infty} x_{jv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{jv} \tau^{v-1} \right) \right\}, \\ \sum_{v=2}^{\infty} v_{iv} (v-1) \tau^{v-2} = & -(1+m_i) \left( \sum_{v=1}^{\infty} y_{iv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{iv} \tau^{v-1} \right) - \\ & - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left\{ \left( \sum_{v=1}^{\infty} (y_{iv} - y_{jv}) \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{ijv} \tau^{v-1} \right) + \left( \sum_{v=1}^{\infty} y_{jv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{jv} \tau^{v-1} \right) \right\}, \end{aligned}$$

(3.100)

$$\begin{aligned} \sum_{v=2}^{\infty} w_{iv} (v-1) \tau^{v-2} = \\ = -(1+m_i) \left( \sum_{v=1}^{\infty} z_{iv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{iv} \tau^{v-1} \right) - \\ - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left\{ \left( \sum_{v=1}^{\infty} (z_{iv} - z_{jv}) \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{ijv} \tau^{v-1} \right) + \left( \sum_{v=1}^{\infty} z_{jv} \tau^{v-1} \right) \left( \sum_{v=1}^{\infty} R_{jv} \tau^{v-1} \right) \right\}, \end{aligned}$$

$$(i = 1, \dots, n) \quad \tau \in (-\tau^*, \tau^*)$$



The derivatives  $u'_i$ ,  $V'_i$  and  $W'_i$  were obtained by differentiation of the power series (3.97) term-by-term. Equations (3.100) can be written as follows:

$$\begin{aligned}
 & \sum_{v=1}^{\infty} u_{iv+1} v \tau^{v-1} = \\
 & = -(1+m_i) \sum_{v=1}^{\infty} \left( \sum_{k=1}^v \chi_{ik} R_{iv+1-k} \right) \tau^{v-1} - \\
 & - \sum_{v=1}^{\infty} \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left[ \left( \sum_{k=1}^v (\chi_{ik} - \chi_{jk}) R_{ijv+1-k} \right) + \left( \sum_{k=1}^v \chi_{jk} R_{jv+1-k} \right) \right] \right\} \tau^{v-1}, \\
 & \sum_{v=1}^{\infty} V_{iv+1} v \tau^{v-1} = \\
 & = -(1+m_i) \sum_{v=1}^{\infty} \left( \sum_{k=1}^v \gamma_{ik} R_{iv+1-k} \right) \tau^{v-1} - \\
 & - \sum_{v=1}^{\infty} \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left[ \left( \sum_{k=1}^v (\gamma_{ik} - \gamma_{jk}) R_{ijv+1-k} \right) + \left( \sum_{k=1}^v \gamma_{jk} R_{jv+1-k} \right) \right] \right\} \tau^{v-1}, \quad (3.101) \\
 & \sum_{v=1}^{\infty} W_{iv+1} v \tau^{v-1} = \\
 & = -(1+m_i) \sum_{v=1}^{\infty} \left( \sum_{k=1}^v z_{ik} R_{iv+1-k} \right) \tau^{v-1} - \\
 & - \sum_{v=1}^{\infty} \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left[ \left( \sum_{k=1}^v (z_{ik} - z_{jk}) R_{ijv+1-k} \right) + \left( \sum_{k=1}^v z_{jk} R_{jv+1-k} \right) \right] \right\} \tau^{v-1}, \\
 & (i=1, \dots, n) \quad \tau \in (-\tau^*, \tau^*).
 \end{aligned}$$

Equating the coefficients of terms of the same power of  $\tau$  we obtain

$$\begin{aligned}
 u_{iv+1} = & \left[ -(1+m_i) \sum_{k=1}^v \chi_{ik} R_{iv+1-k} - \right. \\
 & \left. - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^v (\chi_{ik} - \chi_{jk}) R_{ijv+1-k} + \chi_{jk} R_{jv+1-k} \right) \right] / v,
 \end{aligned}$$

$$V_{iv+1} = \left[ -(1+m_i) \sum_{k=1}^v y_{ik} R_{iv+1-k} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^v (y_{ik} - y_{jk}) R_{ijv+1-k} + y_{jk} R_{jv+1-k} \right) \right] / v, \quad (3.102)$$

$$W_{iv+1} = \left[ -(1+m_i) \sum_{k=1}^v z_{ik} R_{iv+1-k} - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^v (z_{ik} - z_{jk}) R_{ijv+1-k} + z_{jk} R_{jv+1-k} \right) \right] / v, \\ (i=1, \dots, n) \quad v \gg 1.$$

Equations (3.97), at the point  $\tau = 0$  give

$$\chi'_{i\tau=0} \equiv u_{i\tau=0} = u_{i1},$$

$$y'_{i\tau=0} \equiv v_{i\tau=0} = v_{i1},$$

$$z'_{i\tau=0} \equiv w_{i\tau=0} = w_{i1}, \\ (i=1, \dots, n),$$

and, making use of the equations (3.71), it follows that

$$u_{i1} = \chi_{i2},$$

$$v_{i1} = y_{i2}, \quad (3.103)$$

$$w_{i1} = z_{i2}, \\ (i=1, \dots, n).$$

Summarizing the results of the above calculations the following table is constructed

$$\chi_{i1} = \chi_{i\tau=0}, \\ y_{i1} = y_{i\tau=0}, \\ z_{i1} = z_{i\tau=0}, \\ (i=1, \dots, n),$$

$$u_{i1} = x'_{i \tau=0},$$

$$v_{i1} = y'_{i \tau=0},$$

$$w_{i1} = z'_{i \tau=0},$$

$$(i = 1, \dots, n),$$

$$r_{i1} = (x_{i1}^2 + y_{i1}^2 + z_{i1}^2)^{1/2},$$

$$r_{ij1} = ((x_{i1} - x_{j1})^2 + (y_{i1} - y_{j1})^2 + (z_{i1} - z_{j1})^2)^{1/2},$$

$$R_{i1} = r_{i1}^{-3},$$

$$R_{ij1} = r_{ij1}^{-3},$$

$$(i, j = 1, \dots, n \quad i \neq j),$$

$$x_{iv+1} = u_{iv} / \nu,$$

$$y_{iv+1} = v_{iv} / \nu,$$

$$z_{iv+1} = w_{iv} / \nu,$$

$$(i = 1, \dots, n) \quad \nu \gg 1,$$

$$u_{iv+1} = \left[ -(1+m_i) \sum_{k=1}^{\nu} x_{ik} R_{iv+1-k} - \right.$$

$$\left. - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^{\nu} (x_{ik} - x_{jk}) R_{ijv+1-k} + x_{jk} R_{jv+1-k} \right) \right] / \nu,$$

$$v_{iv+1} = \left[ -(1+m_i) \sum_{k=1}^{\nu} y_{ik} R_{iv+1-k} - \right.$$

$$\left. - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^{\nu} (y_{ik} - y_{jk}) R_{ijv+1-k} + y_{jk} R_{jv+1-k} \right) \right] / \nu,$$

$$w_{iv+1} = \left[ -(1+m_i) \sum_{k=1}^{\nu} z_{ik} R_{iv+1-k} - \right.$$

$$\left. - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \left( \sum_{k=1}^{\nu} (z_{ik} - z_{jk}) R_{ijv+1-k} + z_{jk} R_{jv+1-k} \right) \right] / \nu,$$

$$r_{iv+1} = \left[ - \sum_{k=2}^{\nu} r_{ik} r_{iv+2-k} (\nu+1-k) + \sum_{k=1}^{\nu} (\nu+1-k) (x_{ik} x_{iv+2-k} + y_{ik} y_{iv+2-k} + z_{ik} z_{iv+2-k}) \right] / \nu r_{i1},$$

$$\bar{r}_{ijv+1} = \left[ -\sum_{k=2}^v \bar{r}_{ijk} \bar{r}_{ijv+2-k} (v+1-k) + \sum_{k=1}^v (v+1-k) \left( (\chi_{ik} - \chi_{jk})(\chi_{iv+2-k} - \chi_{jv+2-k}) + \right. \right. \\ \left. \left. (\gamma_{ik} - \gamma_{jk})(\gamma_{iv+2-k} - \gamma_{jv+2-k}) + (z_{ik} - z_{jk})(z_{iv+2-k} - z_{jv+2-k}) \right) \right] / v \bar{r}_{ij1} ,$$

$$R_{iv+1} = \left[ -\sum_{k=2}^v (v+1-k) \bar{r}_{ik} R_{iv+2-k} - 3 \sum_{k=1}^v R_{ik} \bar{r}_{iv+2-k} (v+1-k) \right] / v \bar{r}_{i1} ,$$

$$R_{ijv+1} = \left[ -\sum_{k=2}^v (v+1-k) \bar{r}_{ijk} R_{ijv+2-k} - 3 \sum_{k=1}^v (v+1-k) R_{ijk} \bar{r}_{ijv+2-k} \right] / v \bar{r}_{ij1} ,$$

$$(i, j = 1, \dots, n \quad i \neq j) \quad v \gg 1 .$$

If the equations are used in the order where they are given above, they are perfectly recurrent, that is, each coefficient depends only on the preceding coefficients. All the first-order coefficients are given by the initial conditions. After the coefficients of the series (3.87) and (3.92) are found we substitute these series in the equations (3.49) to obtain  $\bar{A}_{ik}(\tau)$  ( $i, k = 1, \dots, n$ ) as power series, the introduction of which in the equations (3.53), (3.54) enables us to solve the system (3.53), (3.54) (by equating the coefficients of terms with the same power of  $\tau$ ). Since  $\bar{f}_{ij}$ ,  $\bar{g}_{ij}$  ( $i, j = 1, \dots, n$ ) are known, we proceed then to the second approximation. This process is repeated until successive approximations of the velocities agree up to the desired accuracy.

In the special case of the two-body problem the equation of motion is

$$\ddot{r} = -\mu \frac{r}{r^3} . \quad (3.104)$$

Let us consider the wellknown equation

$$r = f r_0 + g r_0' , \quad (3.105)$$

where  $f$  and  $g$  are series in powers of the independent variable  $\tau$ ,

and  $(-\tau^{**}, \tau^{**})$  is their common interval of convergence.

Since  $\underline{r}_0$  and  $\underline{r}_0'$  are constant vectors, we can differentiate equation (3.105) once with respect to  $\tau$  to obtain the velocity vector

$$\underline{r}' = f' \underline{r}_0 + g' \underline{r}_0' \quad \tau \in (-\tau^{**}, \tau^{**}) . \quad (3.106)$$

Differentiating once more gives

$$\underline{r}'' = f'' \underline{r}_0 + g'' \underline{r}_0' \quad \tau \in (-\tau^{**}, \tau^{**}) , \quad (3.107)$$

which upon substitution of equation (3.104) becomes

$$-\mu \frac{\underline{r}}{r^3} = f'' \underline{r}_0 + g'' \underline{r}_0' \quad \tau \in (-\tau^{**}, \tau^{**}) ,$$

or

$$\underline{r} = -\frac{r^3}{\mu} f'' \underline{r}_0 - \frac{r^3}{\mu} g'' \underline{r}_0' \quad \tau \in (-\tau^{**}, \tau^{**}) . \quad (3.108)$$

Subtraction of equation (3.108) from equation (3.105) gives

$$\left(f + \frac{r^3}{\mu} f''\right) \underline{r}_0 + \left(g + \frac{r^3}{\mu} g''\right) \underline{r}_0' = 0 \quad \tau \in (-\tau^{**}, \tau^{**}) . \quad (3.109)$$

Since the vectors  $\underline{r}_0$  and  $\underline{r}_0'$  are independent, their coefficients in the relation (3.109) must be equal to zero. Therefore,

$$\begin{aligned} f &= -\frac{r^3}{\mu} f'' , \\ g &= -\frac{r^3}{\mu} g'' , \end{aligned} \quad \tau \in (-\tau^{**}, \tau^{**}) . \quad (3.110)$$

Suppose that  $f$  and  $g$  have the form

$$\begin{aligned} f &= \sum_{v=0}^{\infty} f_v \frac{\tau^v}{v!}, \\ g &= \sum_{v=0}^{\infty} g_v \frac{\tau^v}{v!}, \\ \tau &\in (-\tau^{**}, \tau^{**}), \end{aligned} \quad (3.111)$$

then differentiating these equations twice with respect to  $\tau$  gives

$$\begin{aligned} f'' &= \sum_{v=2}^{\infty} (v-1) v f_v \frac{\tau^{v-2}}{v!}, \\ g'' &= \sum_{v=2}^{\infty} (v-1) v g_v \frac{\tau^{v-2}}{v!}, \end{aligned}$$

or

$$\begin{aligned} f'' &= \sum_{v=2}^{\infty} f_v \frac{\tau^{v-2}}{(v-2)!}, \\ g'' &= \sum_{v=2}^{\infty} g_v \frac{\tau^{v-2}}{(v-2)!}, \end{aligned}$$

or

$$\begin{aligned} f'' &= \sum_{v=0}^{\infty} f_{v+2} \frac{\tau^v}{v!}, \\ g'' &= \sum_{v=0}^{\infty} g_{v+2} \frac{\tau^v}{v!}, \\ \tau &\in (-\tau^{**}, \tau^{**}). \end{aligned} \quad (3.112)$$

Equations (3.110), upon substitution of equations (3.112) become

$$\begin{aligned} \sum_{v=0}^{\infty} f_v \frac{\tau^v}{v!} &= - \frac{r^3}{\mu} \sum_{v=0}^{\infty} f_{v+2} \frac{\tau^v}{v!}, \\ \sum_{v=0}^{\infty} g_v \frac{\tau^v}{v!} &= - \frac{r^3}{\mu} \sum_{v=0}^{\infty} g_{v+2} \frac{\tau^v}{v!}. \end{aligned} \quad \tau \in (-\tau^{**}, \tau^{**})$$

Consider  $r^3$  as constant in the interval  $(-\tau^{**}, \tau^{**})$  (an accurate approximation for small intervals of time), the coefficients of terms of the same power of  $\tau$  must be equal. That is

$$\begin{aligned} f_v &= - \frac{r^3}{\mu} f_{v+2}, \\ g_v &= - \frac{r^3}{\mu} g_{v+2}. \end{aligned} \quad v \gg 0 \quad (3.113)$$

Analytically, for  $V=0$  ,  $V=1$  ,  $V=2$  , . . . . . we find the following

$$\begin{array}{llll}
 f_2 = -\frac{\mu}{r^3} f_0 & f_3 = -\frac{\mu}{r^3} f_1 & g_2 = -\frac{\mu}{r^3} g_0 & g_3 = -\frac{\mu}{r^3} g_1 \\
 f_4 = -\frac{\mu}{r^3} f_2 & f_5 = -\frac{\mu}{r^3} f_3 & g_4 = -\frac{\mu}{r^3} g_2 & g_5 = -\frac{\mu}{r^3} g_3 \\
 \vdots & \vdots & \vdots & \vdots \\
 f_{2\lambda} = -\frac{\mu}{r^3} f_{2\lambda-2} & f_{2\lambda+1} = -\frac{\mu}{r^3} f_{2\lambda-1} & g_{2\lambda} = -\frac{\mu}{r^3} g_{2\lambda-2} & g_{2\lambda+1} = -\frac{\mu}{r^3} g_{2\lambda-1} \\
 \vdots & \vdots & \vdots & \vdots
 \end{array} \tag{3.114}$$

Obviously, the knowledge of the coefficients of the first two terms, namely  $f_0$  ,  $g_0$  ,  $f_1$  ,  $g_1$  , permits all the coefficients of the series (3.111) to be calculated.

The coefficients  $f_0$  and  $g_0$  are obtained as follows: At time  $\tau=0$  equations (3.111) and (3.105) give

$$\begin{aligned}
 f_{\tau=0} &= f_0 , \\
 g_{\tau=0} &= g_0 , \\
 \underline{r}_{\tau=0} &= f_{\tau=0} \underline{r}_0 + g_{\tau=0} \underline{r}'_0 ,
 \end{aligned}$$

or

$$\underline{r}_0 = f_0 \underline{r}_0 + g_0 \underline{r}'_0 ,$$

which yields

$$f_0 = 1, \quad g_0 = 0, \quad (3.115)$$

since  $\underline{r}_0 \equiv \underline{r}_{\tau=0}$ .

On the other hand, equation (3.106), at time  $\tau = 0$  gives

$$\underline{r}'_{\tau=0} = f'_{\tau=0} \underline{r}_0 + g'_{\tau=0} \underline{r}'_0. \quad (3.116)$$

Since  $\underline{r}'_{\tau=0} \equiv \underline{r}'_0$  and because  $f'_{\tau=0} = f_1$  and  $g'_{\tau=0} = g_1$  equation (3.116) becomes

$$\underline{r}'_0 = f_1 \underline{r}_0 + g_1 \underline{r}'_0,$$

which yields

$$f_1 = 0, \quad g_1 = 1. \quad (3.117)$$

Introduction of these values in the equations (3.114) gives

$$f_{2\lambda} = \left(-\frac{\mu}{r^3}\right)^\lambda, \quad f_{2\lambda+1} = 0, \quad g_{2\lambda} = 0, \quad g_{2\lambda+1} = \left(-\frac{\mu}{r^3}\right)^\lambda, \quad \lambda \geq 0, \quad (3.118)$$

and hence the  $f$  and  $g$  series have the form

$$\begin{aligned} f &= \sum_{\nu=0}^{\infty} (-1)^\nu \left(\frac{\mu}{r^3}\right)^\nu \frac{\tau^{2\nu}}{(2\nu)!}, \\ g &= \sum_{\nu=0}^{\infty} (-1)^\nu \left(\frac{\mu}{r^3}\right)^\nu \frac{\tau^{2\nu+1}}{(2\nu+1)!}, \end{aligned} \quad \tau \in (-\tau^{**}, \tau^{**}) \quad (3.119)$$

or

$$f = \sum_{\nu=0}^{\infty} (-1)^\nu \left(\sqrt{\frac{\mu}{r^3}} \tau\right)^{2\nu} / (2\nu)!, \quad (3.120)$$



$$g = \left\{ \sum_{v=0}^{\infty} (-1)^v \left( \sqrt{\frac{\mu}{r^3}} \tau \right)^{2v+1} / (2v+1)! \right\} \sqrt{\frac{r^3}{\mu}}, \quad \tau \in (-\tau^{**}, \tau^{**}).$$

If we now apply the series for  $\sin x$  and  $\cos x$

$$\cos x = \sum_{v=0}^{\infty} (-1)^v x^{2v} / (2v)! ,$$

$$\sin x = \sum_{v=0}^{\infty} (-1)^v x^{2v+1} / (2v+1)! ,$$

then equations (3.120) give

$$f = \cos \left( \sqrt{\frac{\mu}{r^3}} \tau \right) , \quad (3.121)$$

$$g = \sqrt{\frac{r^3}{\mu}} \sin \left( \sqrt{\frac{\mu}{r^3}} \tau \right) ,$$

$$\tau \in (-\tau^{**}, \tau^{**}).$$

Consequently, two known position vectors and their corresponding times, say  $\underline{r}_1, \underline{r}_2, t_1, t_2$ , permits the calculation of the power series (3.121) (assuming  $\underline{r} = \text{constant} = \underline{r}_1 \text{ or } \underline{r}_2$ ). Solving equation (3.105) with respect to  $\underline{r}_0'$  gives the velocity of the body.

Let us return now to the n-body problem. Clearly, knowledge of the position vectors of the bodies at two different instants enables us to calculate the initial conditions of the problem and to form the series (3.68), (3.97). By inserting in these series a value, say  $\Delta \tau$ , of the variable  $\tau$ , we can calculate the position and velocity vectors of the bodies at a subsequent instant,  $\Delta \tau / k$  days later. Taking these new values as initial conditions we repeat the process, thereby detailing the paths of the bodies in space.

## Chapter 4

### Reduction of the plates and numerical results

The first stage in the numerical application of the above, briefly described methods, is the measurement of the photographic plates and their reduction.

For such a purpose the first task to be undertaken was the identification of the minor planet on the plates. This was accomplished using a Blink Comparator. Two plates, with the same guiding star, were used each time.

After that, the measurement of the plates was carried out on a Zeiss measuring machine. All the stars on the plates for which the right ascension and declination are given in the Star Catalogue of the Smithsonian Astrophysical Observatory were taken as reference stars.

We give, in brief, the method of reduction of the measurements and the applied corrections.

A photographic plate (free from errors) is the central projection of a part of the celestial sphere from its centre (ex. the centre of the object glass) on to the tangent plane at a point defined by the intersection of the optical axis of the instrument with the celestial sphere. The rectangular co-ordinates in this plane, called the "Standard co-ordinates", can be defined as follows:

- (a) The co-ordinate system lies in a plane tangent to the celestial sphere.
- (b) The origin of the system is the tangent point  $T$ .
- (c) The  $Y$ -axis is tangent to the declination circle through  $T$ . Its positive direction is in the direction in which the distance of  $T$  from the north celestial sphere is less than  $180^\circ$ .
- (d) The  $X$ -axis is perpendicular to the  $Y$ -axis at  $T$ . Its positive direction is eastward of the declination circle, hence the increasing value of  $X$  corresponds to increasing right ascension.

(e) The unit of length is the radius of the sphere (in practice the focal length,  $f$  ).

(f) The standard co-ordinates  $X$  and  $Y$  of a point  $S$  on the celestial sphere are the rectangular co-ordinates, in the defined system, of the central projection of  $S$  on the tangent plane from the centre of the sphere.

The co-ordinates of the stars that are obtained from the measurement of the plates are usually called the "measured co-ordinates".

The aim of the reduction is the derivation of the spherical co-ordinates  $\alpha, \delta$  of the objects of interest on the plate. This is possible because there is one-to-one correspondence between the points on the sphere and the points on the tangent plane. As a rule the reduction is obtained in two steps. Firstly, we transform the measured co-ordinates into standard co-ordinates, then these are transformed into spherical co-ordinates  $\alpha, \delta$ .

In practice, we make the measured co-ordinates a close approximation to the standard. Then only small corrections are needed. These corrections may be divided into groups: "instrumental" corrections, depending on the state of the telescope while taking the plates, namely, scale, orientation, zero point and plate skewness; and "spherical corrections", due to astronomical causes, namely, refraction, aberration, precession and nutation.

For the second group of corrections formulae can be derived from which they can be computed with sufficient accuracy, on the basis of the known exposure data. For the first group, however, at least some of the coefficients have to be determined empirically, using the known positions of the reference stars.

The displacement of the image of a star on the plate from the position corresponding to its standard co-ordinates is given, generally with sufficient accuracy, as a linear expression in the co-ordinates. Hence, if  $X$  and  $Y$  are the standard co-ordinates of a star, and  $x, y$  its measured

co-ordinates, we can write

$$\Delta x \equiv X - x = Ax + By + C, \quad (4.1)$$

$$\Delta y \equiv Y - y = A^*x + B^*y + C^*.$$

It is possible to go a step further and to introduce quadratic terms, so the most general equations then take the form

$$\begin{aligned} \Delta x &= Ax + By + C + Dx^2 + Exy + Fy^2, \\ \Delta y &= A^*x + B^*y + C^* + D^*x^2 + E^*xy + F^*y^2. \end{aligned} \quad (4.2)$$

The introduction of these additional constants is not without its disadvantages, since a correspondingly larger number of reference stars will be required to determine them with adequate precision.

In order to achieve the second step of the reduction, that is, the transformation of the standard co-ordinates into spherical co-ordinates,  $\alpha, \delta$  we make use of the formulae

$$\begin{aligned} \tan(\alpha - \alpha_0) &= \frac{X}{\cos \delta_0 - Y \sin \delta_0}, \\ \sin \delta &= \frac{\sin \delta_0 + Y \cos \delta_0}{(1 + X^2 + Y^2)^{1/2}}, \end{aligned} \quad (4.3)$$

where  $\alpha_0$  and  $\delta_0$  are the right ascension and declination of the origin of the standard co-ordinates, and  $\alpha, \delta$  the right ascension and declination of the star with standard co-ordinates  $X$  and  $Y$ , all of which are referred to the mean equinox of 1950.0.

The formulae, which give the standard co-ordinates  $X, Y$  as functions of the spherical equatorial co-ordinates, have the form

$$X = \frac{\cos \delta \sin (\alpha - \alpha_0)}{\sin \delta_0 \sin \delta + \cos \delta_0 \cos \delta \cos (\alpha - \alpha_0)}$$

$$Y = \frac{\sin \delta \cos \delta_0 - \sin \delta_0 \cos \delta \cos (\alpha - \alpha_0)}{\sin \delta \sin \delta + \cos \delta_0 \cos \delta \cos (\alpha - \alpha_0)} \quad (4.4)$$

The calculations were carried out using the IBM 360/44 computer of St Andrews University and the IBM 370/165 computer of Cambridge University (for the power series method). When writing the programs for the computations, a deliberate attempt was made to significantly reduce the time required for the calculations.

The numerical results are tabulated as follows:

The first five tables 1a, 1b, 1c, 1d, 1e refer to five different photographic plates, taken on different dates. These tables include the following information for each reference star:

- (a) A serial number (A/A).
- (b) The numbers which the stars possess in the Star Catalogue of the Smithsonian Astrophysical Observatory (SAOSC).
- (c) The visual magnitude of the star (MAGN).
- (d) The right ascension (RA) in hours, minutes and seconds, and the declination (DEC) in degrees, minutes and seconds of arc, for equator equinox and epoch 1950.0.
- (e) The annual proper motion for right ascension (MA) and declination (MD) in seconds of time and seconds of arc respectively.
- (f) The date of observation (DATE) and the interval of time, in tropical year, elapsed since 1950.0 (T).

The first two lines give the values for the guiding star.

The tables 2a, 2b, 2c, 2d, 2e, give:

- (a) The serial number for each reference star (A/A).

(b) The numbers which the stars possess in the Star Catalogue of the Smithsonian Astrophysical Observatory (SAOSC).

(c) The visual magnitude of the star (MAGN).

(d) The right ascension (RA) in hours, minutes and seconds, and the declination (DEC) in degrees, minutes and seconds of arc, for the date of observation and the equator and equinox of epoch 1950.0.

(e) The standard co-ordinates of the stars (X, Y) in seconds of time and seconds of arc respectively and the same quantities in mm.

(f) The date of observation (DATE).

The first line gives the values for the guiding star.

In order to find the standard co-ordinates of the stars the formulae (4.4) were used.

The tables 3a, 3b, 3c, 3d, 3e, give

(a) The serial number (A/A).

(b) The numbers which the stars possess in the Star Catalogue of the Smithsonian Astrophysical Observatory (SAOSC).

(c) The measured co-ordinates of the stars (X-X<sub>0</sub>, Y-Y<sub>0</sub>) with respect to the guiding star and the values taken from the measurement (X, Y), in mm.

The first line gives the date of observation (DATE) and the number which is given in the guiding star in the Star Catalogue of the Smithsonian Astrophysical Observatory (SAOSC(G.S.)).

The first two lines of the columns refer to the guiding star and the minor planet respectively.

The value of each co-ordinate is the mean value of at least ten measurements. To obtain great accuracy, we measured each co-ordinate in two positions of the plate, differing by  $180^{\circ}$ .

In table 4 the following information is given:

(a) The serial number (A/A).

(b) The numbers which the stars possess in the Star Catalogue of the Smithsonian Astrophysical Observatory (SAOSC).

(c) The right ascension (RA) in hours, minutes and seconds and the declination (DEC) in degrees, minutes and seconds of arc, as calculated from the measured co-ordinates.

(d) The difference of the calculated right ascension and declination from the corresponding values given in the tables 2a, 2b, 2c, 2d, 2e (DRA, DDEC), in seconds of time and seconds of arc respectively.

In order to calculate the right ascension and the declination of the stars from their measured co-ordinates, we transformed the measured co-ordinates into standard co-ordinates using the corrections given by relations (4.1). The least squares method was used for the calculation of the coefficient of formulae (4.1). Then the relations (4.3) give the spherical co-ordinates

Values for the right ascension and the declination have been derived by using the method of Dependences. These values are of slightly less accuracy than the values derived by using the least squares method.

Table 4 also gives results using stars distributed symmetrically around the guiding star.

Three stars were used as test stars for each photographic plate.

The results in the table 4 are given in five different groups, which correspond to the five different photographic plates.

Table 5 gives the following information for each of the observations:

(a) The day of observation (DA).

(b) The local mean sidereal time (MTOO(LMST)) and the Greenwich mean sidereal time (MTOO (GMST)), which corresponds to the mid-point of the exposure, in hours, minutes and seconds.

(c) The Greenwich mean sidereal time at  $0^h$  U.T. (on the date of observation), in hours, minutes and seconds (GMST AT 0 U.T.).

(d) The difference between the Greenwich mean sidereal time, corresponding to the mid-point of the observation, and the Greenwich mean sidereal time at  $0^h$  U.T., in hours, minutes and seconds. This difference is given in mean sidereal time (DIFFER.(MST)) and in mean solar time (DIFFER. (MSL.T.)).

(e) The month of observation (MH).

(f) The Universal time (UT), the correction  $\Delta T = E.T. - U.T.$  (in second of time), and the ephemeris time (ET).

(g) The U.T. and the E.T. measured from the first day of the month of the first observation ( $UT^*$ ,  $ET^*$ ).

(h) The values of  $T_0$  and  $T$  ( $T_0$ ,  $T$ ), in tropical countries, where  $T_0$  is the time elapsed since 1900.0 and  $T$  the time elapsed from the initial epoch to the epoch 1950.0.

(i) The angles  $\zeta_0$  and  $z$  ( $\zeta_0$ ,  $z$ ) in seconds of time.

(j) The right ascension (RA) of the minor planet, in hours, minutes and seconds and the right ascension ( $RA^*$ ) and the declination (DEC) of the minor planet, in degrees, minutes and seconds of arc.

Tables 6a, 6b, 6c, 6d, 6e, give the topocentric rectangular co-ordinates of the Sun on the date of observation ( $X$ ,  $Y$ ,  $Z$ ) and the components ( $\lambda, \mu, \nu$ ) of the unit-vector  $\hat{\rho}$  along the topocentric position vector of the planet ( $LAMDA, MI, NI$ ).

To obtain the topocentric rectangular co-ordinates of the Sun on the date of observation we made use of the Everett's interpolation formula

$$f_p = (1-p) f_0 + p f_1 + E_2 \delta_0^2 + F_2 \delta_1^2,$$

and introduced the topocentric corrections ( $\Delta X$ ,  $\Delta Y$ ,  $\Delta Z$ ), given by the relations

$$\Delta X = \Delta_{xy} \cos \theta, \quad \Delta Y = \Delta_{xy} \sin \theta, \quad \Delta Z = \Delta_z.$$



The coefficients  $E_2$  and  $F_2$  are given by the formulae

$$E_2 = (1-p) \frac{(1-p)^2 - 1}{6}, \quad F_2 = p \frac{p^2 - 1}{6},$$

and the factors  $\Delta_{xy}$  and  $\Delta_z$  are given, for each observatory, in the Astronomical Ephemeris.

$\Theta$  is the local sidereal time, with respect to the mean equinox 1950.0, hence

$$\Theta = L.S.T. + M,$$

where L.S.T. is the local sidereal time, with respect to the equinox of the date, and  $M = \Sigma + Z$  the general precession in right ascension.

Tables 7a, 7b, 7c, 7d refer to the four approximations of the Gaussian method. These tables give

- (a) The modified times  $\tau_1, \tau_2, \tau_3, (\tau_1, \tau_2, \tau_3)$ .
- (b) The values of the quantities  $B_1, B_2, B_3, 1+B_1\tau_1^{-3}, 1-B_2\tau_2^{-3}, 1+B_3\tau_3^{-3}, C_1, C_3, v_1$  and  $v_3$ .
- (c) The solution of the system of the equations (1.8) and (1.21) by iteration ( $P_2, R_2$ ).
- (d) The distances  $\rho_1, \rho_2, \rho_3, R_1, R_2, R_3, (P_1, P_2, P_3, R_1, R_2, R_3)$  and the components of the vectors  $\underline{R}_1, \underline{R}_2, \underline{R}_3$ .
- (e) The final values of the constants  $C_1, C_3$ . Generally, the final values are determined when successive approximations differ by less than  $10^{-10}$ .

Table 8 gives

- (a) The values of the quantities  $K_i, m_i, l_i$  ( $i=1,2,3$ ),  $(K_1, K_2, K_3, M_1, M_2, M_3, L_1, L_2, L_3)$ .
- (b) The first approximation for the quantities  $h_i, \tilde{y}_i$  ( $i=1,2,3$ ),  $(H_1, H_2, H_3, Y_1, Y_2, Y_3)$ .
- (c) The second approximation of the same quantities, including the

values of  $\chi_i, \xi_i$  ( $i=1,2,3$ ), ( $X_1, X_2, X_3, KS_1, KS_2, KS_3$ ).

(d) The values of  $C_1$  and  $C_3$ , obtained from the relations,

$$C_1 = \frac{\tau_1 \tilde{y}_2}{\tau_2 \tilde{y}_1}, \quad C_3 = \frac{\tau_3 \tilde{y}_2}{\tau_2 \tilde{y}_3}.$$

These differ by less than  $10^{-9}$  from the values of the last approximation (Table 7d)

Tables 9a and 9b give the final results of the Gauss method. Table 9b is obtained as follows: After the values of  $\tilde{y}_1, \tilde{y}_2, \tilde{y}_3$  are known we take instead of relations (1.19) the relations

$$V_1 = C_1 \tau_2^3 \left( \frac{\tilde{y}_2}{\tilde{y}_1} - 1 \right), \quad V_3 = C_3 \tau_2^3 \left( \frac{\tilde{y}_2}{\tilde{y}_3} - 1 \right),$$

and we proceed as described in the first chapter.

Tables 10a and 10b refer to Laplace's method. These tables give the coefficients and the solutions of systems (2.18) (2.19) and (2.20) before and after the correction for the planetary aberration. Notice that the data from all the observations are used to find the values of the coefficients given in tables 10a, 10b.

Tables 11a and 11b give

- (a) The values of the determinants  $D, D_1, D_2, (D, D_1, D_2)$ .
- (b) The solution of the system of equations (2.23) and (2.24) by iteration ( $RO, PO$ ).
- (c) The modified times  $\tau_1, \tau_2, (T_1, T_2)$ .
- (d) The values of  $\rho_o, R_o$  and  $\rho'_o, (PO, RO, POD)$ .

Table 11b gives the above quantities after the correction for the planetary aberration. It also gives the components ( $VX, VY, VZ$ ) of the velocity vector.

Tables 12a and 12b give the final results of Laplace's method. We obtained Table 12b by using relations (3.121) and (3.105) to find the velocity vector

Table 13 gives the heliocentric rectangular equatorial co-ordinates (for the mean equinox and equator 1950.0) of the planets Mercury, Venus, Earth, Mars, Jupiter, Saturn, Uranus, Neptune and the minor planet, for the dates 1971 Nov 14, 20, 25 at 0<sup>h</sup> E.T.

In order to find these values the apparent right ascension and the apparent declination, given in the Astronomical Ephemeris, were transformed into mean right ascension and declination by using first and second order corrections. Then, using the true distances of planets from the Earth and the heliocentric equatorial rectangular co-ordinates of the Earth for mean equinox and equator 1950.0 and for the dates 1971 Nov 14, 20, 21 at 0<sup>h</sup> E.T., the values given in the table are obtained.

The co-ordinates of the minor planet were found, by correcting the values given in Table 7d.

Table 14 gives

- (a) The velocities of the bodies.
- (b) The total initial energy of the system.
- (c) The heliocentric equatorial rectangular co-ordinates of the bodies for equinox and equator 1950.0, and for 0<sup>h</sup> and 12<sup>h</sup> E.T.
- (d) The total energy for every step (C).
- (e) The right ascension and declination of the minor planet (RA, DEC) for mean equinox and equator 1950.0.

The ephemeris of the asteroid were constructed by solving the equations

$$\xi = \rho \cos \delta \cos \alpha, \quad \eta = \rho \cos \delta \sin \alpha, \quad \zeta = \rho \sin \delta,$$

where  $\underline{\rho} = (\xi, \eta, \zeta)$  is the geocentric position vector of the asteroid,

obtained from the heliocentric position vectors of the Earth and the Asteroid.

TABLE 1a

GUIDING STAR		SAOSC	MAGN	h	RA <sup>m</sup>	DEC	DATE
		110723	4.4	2	14 <sup>s</sup> .102	9° 54' 15".02	1971.8707670
		MA = 0.0190	MD = -0.030	T = 21.8707670 T.Y.			
A/A	SAOSC	MAGN	h	RA <sup>m</sup>	DEC	MA <sup>s</sup>	MD <sup>"</sup>
1	93088	8.7	2	42	35	56.21	-0.012
2	93091	8.8	2	43	10	46.77	-0.019
3	93110	8.5	2	44	1	6.43	-0.053
4	93136	8.8	2	47	25	24.69	-0.012
5	93139	8.9	2	47	12	1.96	-0.021
6	93150	8.5	2	49	6	8.62	-0.012
7	93151	8.6	2	49	10	17.46	-0.422
8	93152	8.7	2	49	35	28.04	-0.056
9	93153	9.0	2	49	45	28.00	0.005
10	93161	8.8	2	50	27	56.42	-0.015
11	93162	8.7	2	50	27	54.17	0.003
12	110737	8.9	2	43	11	29.87	0.014
13	110742	9.1	2	44	57	58.93	0.059
14	110743	9.0	2	44	32	28.09	0.005
15	110745	8.0	2	44	6	0.27	-0.043
16	110752	8.7	2	45	43	0.72	0.005
17	110753	8.7	2	45	41	27.63	-0.007
18	110753	9.0	2	45	41	40.46	0.012
19	110662	9.5	2	36	16	26.84	0.032
20	110674	9.0	2	37	17	25.74	-0.006
21	110693	9.8	2	39	35	27.79	0.023
22	110702	9.7	2	40	20	12.94	-0.034
23	110716	8.7	2	41	1	10.21	-0.013
24	93034	6.9	2	36	25	22.78	-0.058
25	93036	9.0	2	36	27	25.04	0.0
26	93050	8.7	2	38	8	13.36	0.003
27	93059	6.7	2	39	19	56.62	-0.025
28	93067	6.3	2	39	31	46.87	-0.018
29	93071	8.7	2	40	28	45.13	-0.027
30	93078	8.9	2	41	2	46.59	0.037

TABLE 1b

GUIDING STAR			SAOSC	MAGN	RA		DEC		DATE		
			110698	6.8	2 <sup>h</sup>	39 <sup>m</sup>	52 <sup>s</sup> .986	9°	35'	27.79"	1971.3870742
			MA = 0.0010 MD = 0.023 T = 21.8870742 T.Y.								
A/A	SAOSC	MAGN	h	m	RA	s	°	'	''	MA	MD
1	110723	4.4	2	42	14.102	14.102	9	54	15.02	0.0190	-0.030
2	93071	8.7	2	40	24.728	24.728	10	28	45.13	0.0012	-0.027
3	93078	8.9	2	41	14.472	14.472	10	2	46.59	0.0001	0.037
4	93088	8.7	2	42	50.547	50.547	10	35	56.21	0.0008	-0.012
5	93091	8.8	2	43	13.671	13.671	10	10	46.77	0.0060	-0.019
6	93110	8.5	2	44	55.640	55.640	10	1	6.43	0.0033	-0.053
7	110702	9.7	2	40	39.224	39.224	9	20	12.94	0.0066	-0.034
8	110716	8.7	2	41	44.984	44.984	9	1	10.21	-0.0001	-0.013
9	110737	8.9	2	43	43.725	43.725	9	11	29.87	0.0012	0.014
10	110742	9.1	2	44	11.597	11.597	8	57	58.93	0.0035	0.059
11	110743	9.0	2	44	18.686	18.686	8	32	28.09	0.0006	0.005
12	110745	8.0	2	44	42.089	42.089	9	6	0.27	0.0006	-0.043
13	110752	8.7	2	45	12.423	12.423	8	43	0.72	0.0071	0.005
14	110753	8.7	2	45	18.273	18.273	8	41	27.63	0.0012	-0.007
15	110646	8.6	2	34	44.670	44.670	9	20	44.08	-0.0012	0.010
16	110650	8.7	2	35	5.804	5.804	8	44	41.95	0.0012	0.008
17	110658	8.3	2	36	19.201	19.201	8	42	17.78	0.0005	-0.018
18	110662	9.5	2	36	40.478	40.478	9	16	26.84	0.0051	0.032
19	110674	9.0	2	37	55.511	55.511	9	17	25.74	0.0042	-0.006
20	110686	7.8	2	38	43.622	43.622	8	18	52.10	-0.0007	-0.032
21	110632	8.7	2	33	0.996	0.996	9	54	18.62	0.0020	-0.011
22	93026	8.8	2	34	7.871	7.871	10	19	19.14	0.0013	-0.004
23	93034	6.9	2	36	21.619	21.619	10	25	22.74	0.0029	-0.058
24	93036	9.0	2	36	29.123	29.123	10	27	25.04	0.0007	0.0
25	93050	8.7	2	38	5.888	5.888	10	8	13.36	0.0	0.003
26	93059	6.7	2	39	18.507	18.507	10	19	56.62	-0.0014	-0.025
27	93067	6.3	2	39	47.143	47.143	10	31	46.85	-0.0018	-0.018

TABLE 1c

GUIDING STAR	SAOSC	MAGN	RA h <sup>h</sup> m <sup>m</sup> s <sup>s</sup>	DEC ° ' "	DATE
	110650	8.7	2 35 5.804	8° 44' 41.95	1971.9009253
	MA= 0.0012	MD= 0.008	P= 21.9009253 LY		

A/A	SAOSC	MAGN	h	m	s	°	DEC ' "	MA s	MD "
1	110662	9.5	2	36	40.478	9	15 26.84	0.0051	0.032
2	110674	9.0	2	37	55.511	9	17 25.74	0.0042	-0.006
3	110698	8.8	2	39	52.986	9	35 27.73	0.0010	0.023
4	110702	9.7	2	40	39.224	9	20 12.94	0.0066	-0.034
5	110716	8.7	2	41	44.984	9	1 10.21	-0.0001	-0.013
6	110653	6.5	2	35	21.999	7	28 47.80	0.0056	-0.039
7	110658	8.3	2	36	19.201	8	42 17.74	0.0005	-0.018
8	110663	8.5	2	36	43.656	8	7 49.67	0.0049	-0.005
9	110667	8.4	2	37	6.906	7	59 19.79	-0.0005	-0.013
10	110670	9.2	2	37	22.388	7	33 4.86	-0.0017	0.025
11	110673	8.5	2	38	14.720	8	1 35.72	-0.0013	0.0
12	110686	7.8	2	38	43.622	8	13 52.10	-0.0007	-0.032
13	110696	8.9	2	39	46.561	7	59 42.93	-0.0007	0.006
14	110696	8.6	2	30	19.543	7	40 6.61	-0.0005	0.022
15	110609	8.7	2	30	35.620	8	9 30.26	0.0022	-0.031
16	110610	9.0	2	30	39.993	8	26 9.52	-0.0015	-0.012
17	110640	6.0	2	33	55.925	7	30 47.39	-0.0035	-0.027
18	110643	9.5	2	34	30.283	8	16 0.97	-0.0005	-0.007
19	110647	8.6	2	34	52.854	7	23 16.02	0.0019	-0.002
20	110648	8.6	2	34	55.364	7	20 14.07	0.0008	0.015
21	110651	8.7	2	30	3.794	9	37 34.20	0.0016	-0.002
22	110616	7.7	2	31	32.786	8	46 11.70	0.0020	0.022
23	110632	8.7	2	33	0.996	9	54 18.62	0.0020	-0.011
24	110639	8.7	2	33	51.614	8	55 9.16	0.0051	-0.006
25	110646	8.6	2	34	44.670	9	20 44.08	-0.0012	0.010

TABLE 1d

GUIDING STAR      SAOSC      MAGN      h      m      s      RA<sup>m</sup>      41.149      10°      15'      21.02      DATE  
 93186      8.2      2      52      41.149      10°      15'      21.02      1971.8240538

MA = -0.0012      MD = -0.008      T = 21.8240538TY

A/A	SAOSC	MAGN	h	m	s	RA	DEC	MA	MD
1	93198	8.7	2	54	14.403	10	26	-0.0001	0.011
2	93200	8.7	2	54	25.131	10	36	-0.0009	0.013
3	93204	8.6	2	54	39.749	10	16	-0.0009	-0.058
4	93227	8.5	2	57	7.782	10	13	0.0034	-0.039
5	93228	8.0	2	57	22.177	10	27	0.0091	-0.072
6	93231	8.9	2	57	52.298	10	36	-0.0024	0.0
7	93232	6.2	2	58	1.160	10	40	0.0053	-0.028
8	93244	8.5	2	59	5.790	10	39	0.0028	-0.046
9	93212	7.8	2	55	41.918	10	0	0.0015	0.013
10	93223	8.3	2	56	35.508	10	0	-0.0004	-0.004
11	93234	8.1	2	58	6.877	10	2	0.0003	-0.021
12	110340	8.4	2	52	51.084	9	36	0.0001	-0.054
13	110859	8.3	2	53	47.664	9	55	0.0017	-0.001
14	110862	8.0	2	54	18.827	9	57	-0.0046	-0.083
15	110888	8.6	2	56	58.919	9	26	0.0018	-0.049
16	110783	9.0	2	43	37.656	9	11	0.0003	-0.001
17	110809	8.7	2	50	12.765	8	57	-0.0015	-0.003
18	110817	6.8	2	51	4.867	9	7	0.0038	-0.023
19	110824	8.6	2	51	43.459	9	34	0.0009	0.025
20	110834	8.8	2	52	33.359	8	54	0.0021	-0.017
21	93134	8.6	2	47	35.411	11	24	-0.0004	-0.006
22	93136	3.8	2	47	43.627	10	25	0.0114	-0.012
23	93130	8.9	2	47	52.315	11	12	-0.0025	-0.021
24	93150	3.5	2	49	15.023	11	6	0.0009	-0.012
25	93151	8.6	2	49	15.439	11	10	0.0020	-0.042
26	93152	8.7	2	49	23.043	10	35	-0.0016	-0.056
27	93158	9.0	2	49	52.533	10	45	0.0005	0.005
28	93161	8.8	2	50	10.111	10	27	0.0028	-0.015
29	93162	8.7	2	50	10.519	10	27	0.0011	0.003
30	93175	3.5	2	51	37.939	11	6	0.0	0.0
31	93182	8.8	2	52	18.370	11	17	-0.0010	-0.027

TABLE 1e

GUIDING STAR		SAOSC	MAGN	h	PA	DEC,	8°	47'	2.37	DATE
		110566	7.6	2	26 <sup>m</sup>	55.228				1971.93336219
		MA= 0.0003		MD= 0.017		T= 21.93336219 T.Y.				
A/A	SAOSC	MAGN	h	m	RA	s	DEC	''	MA	MD
1	110574	8.6	2	27	19.623	53	33.69	-0.0026		-0.059
2	110597	9.3	2	29	34.243	55	0.51	0.0005		0.001
3	110601	8.7	2	30	3.794	37	34.20	0.0016		-0.002
4	110639	8.7	2	33	51.614	55	9.16	0.0051		-0.006
5	110568	8.4	2	27	4.682	16	36.16	0.0043		0.001
6	110576	8.6	2	27	32.642	39	23.13	0.0007		-0.022
7	110588	8.6	2	28	48.570	7	38.47	-0.0003		-0.013
8	110606	8.6	2	30	19.543	40	6.61	-0.0005		0.022
9	110609	8.7	2	30	35.620	9	30.26	0.0022		-0.013
10	110610	9.0	2	30	39.393	26	9.52	-0.0015		-0.012
11	110616	7.7	2	31	32.786	46	11.70	0.0020		0.022
12	110502	8.3	2	20	17.079	19	7.27	0.0014		-0.002
13	110520	8.8	2	22	30.612	19	32.73	-0.0035		-0.002
14	110525	8.7	2	22	58.059	29	49.49	0.0011		-0.010
15	110527	8.9	2	23	1.417	47	41.56	0.0003		-0.017
16	110539	8.6	2	25	5.608	38	4.48	0.0025		0.018
17	110543	4.3	2	25	29.791	14	13.15	0.0025		-0.004
18	110546	8.9	2	25	50.915	24	46.89	0.0014		-0.033
19	110548	9.1	2	25	56.644	3	39.22	0.0010		-0.058
20	110550	8.7	2	25	59.756	26	28.59	-0.0067		-0.085
21	110552	9.5	2	26	3.074	32	33.96	0.0029		-0.008
22	110554	8.8	2	26	6.879	7	14.48	0.0001		0.017
23	110556	8.5	2	26	14.767	32	52.13	0.0037		0.001
24	110558	8.6	2	26	20.947	9	24.63	-0.0004		0.013
25	92973	8.9	2	26	43.671	10	12.40	0.0005		0.010
26	110515	8.8	2	21	39.111	9	24.20	0.0021		0.013
27	110516	7.6	2	21	50.025	29	13.41	0.0045		-0.050
28	110537	6.5	2	24	43.583	58	38.74	-0.0195		-0.200
29	110565	6.3	2	26	54.866	9	36.92	-0.0010		-0.016
30	92922	7.3	2	21	29.521	10	47.71	0.0026		-0.021



TABLE 2a

GUIDING STAR	SAOSC	MAGNITUDE	h	m	RA	DEC	DATE
	110723	4.4	2	42	14.518	9° 54' 14.36"	1971.8707670
A/A	SAOSC	MAGN	h	m	RA	DEC	
1	93089	8.7	2	42	50.564	35 55.95	41.697
2	93091	8.8	2	43	13.802	10 46.35	16.539
3	93110	8.5	2	44	55.712	1 5.27	6.889
4	93136	8.8	2	47	43.876	10 24.43	31.344
5	93139	8.9	2	47	52.260	11 12	77.997
6	93150	8.5	2	49	15.043	11 8.36	72.214
7	93151	8.6	2	49	15.483	11 8.23	76.217
8	93152	8.7	2	49	23.008	10 35	41.511
9	93158	9.0	2	49	52.544	10 45	51.583
10	93161	8.8	2	50	10.172	10 27	34.064
11	93162	8.7	2	50	10.543	10 27	34.034
-----***-----							
12	110737	8.9	2	43	43.751	9 11	-42.727
13	110742	9.1	2	44	11.783	8 58	-56.221
14	110743	9.0	2	44	13.699	8 32	-81.764
15	110745	8.0	2	44	42.102	9 5	-48.223
16	110752	8.7	2	45	12.578	8 43	-71.193
17	110753	8.7	2	45	18.299	8 41	-72.746
18	110758	9.0	2	45	28.528	8 41	-72.520
-----***-----							
19	110662	9.5	2	36	40.590	9 16	-37.621
20	110674	9.0	2	37	55.603	9 17	-35.717
21	110698	8.8	2	39	53.008	9 35	-18.733
22	110702	9.7	2	40	39.368	9 29	-34.024
23	110716	8.7	2	41	44.982	9 1	-53.077
-----***-----							
24	93034	6.9	2	36	21.682	10 25	31.321
25	93036	9.0	2	36	29.138	10 27	33.373
26	93050	8.7	2	38	5.888	10 8	14.082
27	93059	6.7	2	39	18.476	10 19	25.745
28	93067	6.3	2	39	47.104	10 31	37.572
29	93071	8.7	2	40	24.754	10 28	34.524
30	93078	8.9	2	41	14.474	10 2	8.556

TABLE 2b

GUIDING STAR	SAOSC	MAGNITUDE	RA			DEC			DATE	
			<sup>h</sup>	<sup>m</sup>	<sup>s</sup>	<sup>°</sup>	<sup>'</sup>	<sup>"</sup>	X IN MM	Y IN MM
	110693	8.3	2	39	53.003	9	35	28.29	1971.8870742	
A/A	SAOSC	MAGN	h	m	s	RA	DEC	X	Y	
1	110723	4.4	2	42	14.518	9	54	14.36	18.799	
2	93071	8.7	2	40	24.754	10	23	44.54	53.277	26.0693
3	93078	8.9	2	41	14.474	10	2	47.40	27.329	5.8383
4	93088	8.7	2	42	50.565	10	35	55.95	60.519	15.0012
5	93091	8.8	2	43	13.802	10	10	46.35	35.366	32.6434
6	93110	8.5	2	44	55.712	10	1	5.27	25.759	36.9620
-----***-----										
7	110702	9.7	2	40	39.368	9	20	12.20	-15.265	55.7528
8	110716	8.7	2	41	44.982	9	1	9.93	-34.290	8.5547
9	110737	8.9	2	43	43.751	9	11	30.18	-23.893	20.6817
10	110742	9.1	2	44	11.783	8	58	0.22	-37.376	42.5998
11	110743	9.0	2	44	13.699	8	32	28.20	-62.914	47.8078
12	110745	8.0	2	44	42.102	9	5	59.33	-29.365	49.1474
13	110752	8.7	2	45	12.576	8	43	0.83	-52.323	53.3897
14	110753	8.7	2	45	13.299	8	41	27.48	-53.874	59.0865
-----***-----										
15	110646	8.6	2	34	44.644	9	20	44.30	-14.595	60.1492
16	110650	6.7	2	35	5.830	8	44	42.13	-50.660	-56.9084
17	110658	8.3	2	36	19.212	8	42	17.39	-53.124	-53.0911
18	110662	9.5	2	36	40.590	9	16	27.54	-18.959	-39.5271
19	110674	9.0	2	37	55.603	9	17	25.61	-18.025	-35.5146
20	110686	7.8	2	38	43.607	8	18	51.40	-76.621	-21.6675
-----***-----										
21	110632	8.7	2	33	1.040	9	54	18.38	19.096	-12.8449
22	93026	8.8	2	34	7.899	10	19	19.05	44.039	-75.9126
23	93034	6.9	2	36	21.682	10	25	21.47	49.962	-63.5088
24	93036	9.0	2	36	29.138	10	27	25.04	52.017	-38.8728
25	93050	8.7	2	38	5.888	10	8	13.43	32.771	-37.4973
26	93059	6.7	2	39	18.476	10	19	56.07	44.467	-19.7200
27	93067	6.3	2	39	47.104	10	31	46.46	56.308	-6.3532
-----***-----										
42.1182										

TABLE 2c

GUIDING STAR	SAOSC	MAGNITUDE	RA	DEC	DATE						
	110650	8.7	2 <sup>h</sup> 35 <sup>m</sup> 5.330 <sup>s</sup>	8° 44' 42.13"	1971.9009253						
A/A	SAOSC	MAGN	h	m	s	RA	DEC	X	Y	X IN MM	Y IN MM
1	110662	9.5	2	36	40.590	9	16	27.54	31.771	17.4894	23.7646
2	110674	9.0	2	37	55.603	9	17	25.61	32.767	31.3340	24.5101
3	110698	8.8	2	39	53.008	9	35	23.29	50.896	52.9647	38.0705
4	110702	9.7	2	40	39.369	9	20	12.20	35.664	61.5603	26.6770
5	110716	8.7	2	41	44.982	9	1	9.93	16.688	73.7392	12.4325
-----***-----											
6	110653	6.5	2	35	21.222	7	28	46.95	-75.932	2.8544	-56.7369
7	110658	8.3	2	36	19.212	8	42	17.35	-2.406	13.5644	-1.7994
8	110663	8.5	2	36	43.763	8	7	49.56	-36.865	18.1307	-27.5752
9	110667	8.4	2	37	5.995	7	59	19.51	-45.362	22.2552	-33.9304
10	110670	9.2	2	37	22.351	7	33	5.41	-71.600	25.3142	-53.5570
11	110678	8.5	2	38	14.692	8	1	35.72	-43.064	34.9759	-32.2120
12	110686	7.8	2	38	43.607	8	18	51.40	-25.734	40.3006	-19.2866
13	110696	8.9	2	39	46.546	7	59	43.66	-44.888	51.9949	-33.5764
-----***-----											
14	110606	8.6	2	30	19.532	7	40	7.09	-64.493	-53.0757	-48.2407
15	110609	8.7	2	30	35.668	8	9	29.53	-35.117	-50.0179	-26.2676
16	110610	9.0	2	30	39.960	8	26	9.26	-18.455	-49.1864	-13.8041
17	110640	6.0	2	33	55.948	7	30	46.90	-73.928	-12.9774	-55.2979
18	110643	9.5	2	34	30.272	8	16	0.82	-28.688	-6.5805	-21.4583
19	110647	8.6	2	34	52.896	7	23	15.93	-81.451	-2.3994	-60.9252
20	110648	8.6	2	34	55.382	7	20	14.40	-84.479	-1.9385	-63.1903
-----***-----											
21	110601	8.7	2	30	3.829	9	37	34.16	53.008	-55.6943	39.6501
22	110616	7.7	2	31	32.830	8	46	12.13	1.563	-39.3684	1.1692
23	110632	8.7	2	33	1.040	9	54	13.38	69.638	-22.9933	52.0890
24	110539	9.7	2	33	51.726	8	55	9.03	10.456	-13.6902	7.8211
25	110646	8.6	2	34	44.644	9	20	44.30	36.038	-3.9095	26.9566





TABLE 3a

-----		DATE		SAOSC (S.S.)		-----	
		1971.8707670		110723			
A/A	SAOSC	X mm	Y mm	X-XO mm	Y-YO mm	MEASUR. CO-OR. OF S.S. MEASUR. CO-OR. OF AST.	
1	93083	503.2754	197.6327	12.3112	-16.0736		
2	93091	515.5366	131.6091	5.6326	31.1304		
3	93110	509.9030	228.8731	10.9062	12.3581		
4	93136	514.1816	210.0408	29.7023	5.1433		
12	110737	532.9782	202.8260	60.5204	23.4112		
13	110742	563.8958	221.0939	15.4838	-31.9733		
14	110743	519.7592	155.7089	21.6576	-42.0674		
15	110745	524.9430	155.6153	22.9738	-51.1745		
16	110752	525.2492	136.5082	27.2595	-36.0946		
17	110753	535.5349	161.5881	32.3193	-53.2639		
18	110753	536.1947	144.4188	33.9825	-54.4190		
19	110662	537.2579	143.2537	35.8642	-54.2652		
20	110674	530.1396	143.4175	-61.6559	-28.1285		
21	110693	441.6195	159.5542	-47.3114	-27.4529		
22	110702	455.4640	170.2193	-26.1070	-14.0040		
23	110715	477.1684	133.6787	-17.5903	-25.4431		
24	93034	495.6851	172.2336	-5.4542	-39.7107		
25	93036	497.8112	157.9720	-64.9229	23.4481		
26	93050	438.3525	221.1303	-63.5584	24.9322		
27	93053	439.7170	222.6749	-45.7885	10.5488		
28	93067	457.4863	208.2315	-32.4011	19.2624		
29	93071	470.8743	216.9451	-27.1124	28.1098		
30	93073	476.1630	225.7325	-20.1394	25.8311		
		483.0860	223.5138	-11.0558	6.3910		
		492.2196	204.0737				



TABLE 3b

-----		DATE	SAOSC (S.S.)		-----			
A/A	SAOSC	1971.8870742	X mm	Y mm	X-KO mm	Y-YO mm	MEASUR. CO-OR. OF S.S.	MEASUR. CO-OR. OF AST.
			503.7087	137.7375	-5.4435	-12.5243		
			497.2651	135.2732	5.3722	39.8467		
	93071		509.5809	237.6442		20.4136		
2	93073		513.7287	218.2111	15.0200	45.2421		
3	93088		535.3888	243.0396	32.6301	25.4141		
4	93091		540.5918	224.2115	35.3331	19.2289		
5	93110		559.4961	217.0264	55.7874	-11.4217		
6	110702		512.2395	136.3758	3.5308	-25.6798		
7	110716		524.3877	172.1177	20.6790	-17.9136		
8	110737		545.3178	179.8839	42.6091	-28.0016		
9	110742		551.5145	169.7959	47.3059	-47.1082		
10	110743		552.8490	150.6893	49.1403	-22.0239		
11	110745		557.1068	175.7735	53.3381	-10.8355		
12	110645		445.7735	135.9120	-55.3302	-37.8785		
15	110650		450.5632	159.9190	-53.1455	-39.7162		
16	110658		454.1415	158.0813	-39.5672	-14.1710		
17	110662		463.1793	183.6265	-35.5294	-13.4916		
18	110674		482.0214	134.3059	-21.5373	-57.3263		
19	110685		490.8310	140.4712	-12.8777	32.9887		
20	93025		440.2054	230.7862	-63.5033	37.3880		
22	93034		464.8594	235.1355	-38.8493	38.9352		
23	93035		465.2253	236.7327	-37.4324	24.5156		
24	93050		483.9929	222.3131	-19.7158	32.2527		
25	93053		497.3745	231.0502	-5.3341	42.1078		
26	93067		502.6563	239.9053	-1.0513			

TABLE 3c

-----		DATE		SAOSC (S.S.)		-----			
		1971.9009253		110650					
A/A	SAOSC	X mm	Y mm	X-XO mm	Y-YO mm	MEASUR. CO-OR. OF S.S. MEASUR. CO-OR. OF AST.			
1	110662	503.9182	197.5792	11.2891	18.1920				
2	110674	515.2073	215.7712	17.5045	23.7533				
3	110693	521.4228	221.3425	31.3422	24.5019				
4	110702	535.2604	222.0311	52.9666	38.0729				
5	110653	556.8848	235.6521	61.5479	26.6310				
6	110653	565.4651	224.2702	2.8388	-56.7718				
7	110658	506.3070	140.8974	13.5799	-1.7816				
8	110663	517.4981	135.7975	13.1415	-27.5762				
9	110667	522.0597	170.0030	22.2793	-33.9269				
10	110667	526.1975	153.6523	25.3576	-53.5613				
11	110670	529.2758	144.0179	34.3981	-32.1994				
12	110678	538.9163	165.3793	40.3326	-19.2803				
13	110685	544.2503	178.2984	52.0296	-33.5726				
14	110695	555.9473	154.0066	-53.5530	-48.2215				
15	110605	450.8552	149.3577	-50.0135	-26.2394				
16	110609	453.9046	171.3393	-49.1845	-13.7337				
17	110610	454.7337	133.7955	-12.9532	-55.2679				
18	110640	490.9650	142.3113	-5.5531	-21.4401				
19	110643	497.3651	176.1391	-2.3505	-50.9012				
20	110647	501.5577	136.6780	-1.0132	-53.1742				
21	110543	502.0050	134.4050	-55.7139	39.6710				
22	110501	448.2043	237.2502	-39.3677	1.1788				
23	110615	464.5505	198.7580	-23.0103	52.0889				
24	110632	480.9079	249.6581	-13.6318	7.8296				
25	110639	490.2264	205.4088	-3.0093	26.9551				
	110645	500.0089	224.5343						



TABLE 3d

-----		DATE		SAOSC (G.S.)		-----	
		1971.3240533		93135			
A/A	SAOSC	X mm	Y mm	X-XO mm	Y-YO mm	MEASUR. CO-OR.	MEASUR. CO-OR. OF G.S. OF AST.
1	93193	502.7843	137.5335	31.0036	5.5392		
2	93200	533.7939	203.2277	17.1797	8.4957		
3	93204	519.3640	205.0342	13.1428	15.5222		
4	93227	521.3271	213.1607	21.3332	1.1543		
5	93223	524.6175	198.6928	43.0983	2.2864		
6	93231	551.3831	199.8249	51.7452	9.2118		
7	93232	554.5305	206.7503	57.2137	15.5737		
8	93212	560.0030	213.2122	53.3576	18.8709		
9	93223	561.5519	216.4394	33.3218	-11.1316		
10	93234	536.1061	136.3569	43.1366	-10.8311		
11	110840	545.9709	136.6574	60.0174	-3.2344		
12	110859	562.3017	199.3041	1.8434	-28.8691		
13	110862	504.6277	168.6594	12.2704	-14.8415		
14	110893	515.0547	182.6970	13.0015	-13.1659		
15	110733	520.7853	134.3726	47.5977	-36.6653		
16	110809	550.3820	160.8732	-44.3586	-47.8269		
17	110817	457.8257	143.7116	-27.4195	-53.3312		
18	110824	475.3648	139.2073	-17.7632	-50.4018		
19	110834	485.0211	147.1367	-10.6217	-30.7695		
20	93135	492.1626	166.7690	-1.4216	-60.4032		
21	93139	501.3627	137.1353	-54.5792	7.6264		
22	93150	443.1051	205.1643	-53.0114	42.4970		
23	93151	443.7729	240.0355	-37.6141	33.0426		
24	93151	464.9702	235.5811	-37.7307	41.0332		
25	93152	465.0536	233.5717	-36.4173	15.0343		
26	93153	466.3665	212.6228	-30.9639	22.5664		
27	93175	471.8154	220.1049	-11.5767	38.2100		
28	93182	491.2076	235.7485	-4.1583	46.4137		
29	93182	498.6260	243.9522				

TABLE 3e

-----		DATE	SAOSC (G.S.)		-----	
A/A	SAOSC	X	Y	X-XO	Y-YO	MEASUR. CO-OR. OF G.S. MEASUR. CO-OR. OF AST.
		mm	mm	mm	mm	
		503.5538	137.9003	25.3115	5.7832	
		528.9653	203.6840	4.5000	43.7575	
		508.1538	247.6533	29.3143	50.8854	
1	110574	532.3681	248.7862	1.7654	-22.7574	
2	110597	505.4192	175.1334	5.3225	-5.7363	
5	110563	510.5763	192.1645	20.9885	-23.4662	
6	110576	524.6423	158.4346	37.3307	-50.3329	
7	110583	541.5445	147.8573	40.3243	-28.0320	
8	110606	544.4781	153.8688	41.5323	-15.5690	
9	110603	545.2467	182.3313	51.3351	-0.5554	
10	110610	554.9889	137.3454	-73.7048	-20.7359	
11	110615	429.3490	177.1549	-49.0024	-20.4973	
12	110502	454.5514	177.4035	-43.8913	-12.8380	
13	110520	453.7625	135.0523	-43.3521	-44.3589	
14	110525	460.3017	153.5413	-20.2579	-6.7054	
15	110527	483.3859	131.1054	-11.3993	-16.6503	
16	110533	491.7540	131.2400	-10.8508	-32.4638	
17	110545	492.8030	155.4370	-10.2830	-15.4142	
18	110543	433.3653	132.4366	-9.6564	-10.8201	
19	110550	403.9374	137.0307	-3.9739	-57.4650	
20	110552	403.9374	140.4353	-7.4785	-10.6086	
21	110554	494.5749	137.2322	-5.5174	-23.1657	
22	110556	495.1753	187.2322	-2.1325	51.4792	
23	110556	497.1364	159.7351	-53.3952	12.3366	
24	110553	497.1364	259.3300	-56.3174	31.6938	
25	32973	501.5213	210.2374	-24.3370	53.5381	
26	110515	445.2536	229.5046	-0.0571	25.1116	
27	110516	447.3364	229.5046			
28	110537	473.3163	251.4383			
29	110565	503.5967	223.0124			

TABLE 4

A/A	SAOSC	DATE 1971.8707670			SAOSC(G.S.) 110723			DRA S	DDEC "
		h	m	RA S	o	l	DEC "		
		2	43	21.271	9	32	45.40 (Asteroid)		
13	110742	2	44	11.803	8	58	0.21	0.0201	-0.0135
24	93034	2	36	21.713	10	25	21.48	0.0305	-0.0274
28	93067	2	39	47.096	10	31	46.42	-0.0082	-0.0575

RESULTS USING SYMMETRICAL DISTRIBUTION OF THE STARS

		2	43	21.264	9	32	45.49 (Asteroid)		
13	110742	2	44	11.791	8	58	0.38	0.0084	0.1580
24	93034	2	36	21.716	10	25	21.34	0.0344	-0.1690
28	93067	2	39	47.097	10	31	46.32	-0.0069	-0.1603

A/A	SAOSC	DATE 1971.8870742			SAOSC(G.S.) 110698			DRA S	DDEC "
		h	m	RA S	o	l	DEC "		
		2	39	18.140	9	18	44.22 (Asteroid)		
4	93088	2	42	50.536	10	35	56.13	-0.0287	0.1837
9	110737	2	43	43.781	9	11	30.31	0.0296	0.1259
18	110662	2	36	40.618	9	16	27.40	0.0284	-0.1383

RESULTS USING SYMMETRICAL DISTRIBUTION OF THE STARS

		2	39	18.140	9	18	44.22 (Asteroid)		
4	93088	2	42	50.536	10	35	56.13	-0.0287	0.1837
9	110737	2	43	43.781	9	11	30.31	0.0296	0.1259
18	110662	2	36	40.618	9	16	27.40	0.0284	-0.1383

A/A	SAOSC	DATE 1971.9009253			(SAOSC(G.S.) 110650			DRA S	DDEC "
		h	m	RA S	o	l	DEC "		
		2	36	6.961	9	9	0.58 (Asteroid)		
3	110698	2	39	53.004	9	35	28.75	-0.0037	0.4630
16	110610	2	30	39.948	8	26	9.37	-0.0121	0.1050
24	110639	2	33	51.705	8	55	8.84	-0.0208	-0.1920

RESULTS USING SYMMETRICAL DISTRIBUTION OF THE STARS

		2	36	6.966	9	9	0.62		
3	110698	2	39	53.014	9	35	28.74	0.0065	0.4473
16	110610	2	30	39.943	8	26	9.50	-0.0165	0.2431
24	110639	2	33	51.706	8	55	8.91	-0.0198	-0.1178

DATE  
1971.8240538

SAOSC(G.S.)  
93186

A/A	SAOSC	RA			DEC			DRA	D DEC
		h	m	s	o	'	"	s	"
		2	55	29.597	10	22	54.06	(Asteroid)	
9	93212	2	55	41.957	10	0	20.42	0.0057	-0.0999
18	110817	2	51	4.924	9	7	57.43	-0.0263	-0.1521
27	93158	2	49	52.537	10	45	28.19	-0.0068	0.0768

RESULTS USING SYMMETRICAL DISTRIBUTION OF THE STARS

		2	55	29.599	10	22	54.19	(Asteroid)	
9	93212	2	55	41.957	10	0	20.51	0.0063	-0.0143
18	110817	2	51	4.925	9	7	57.40	-0.0246	-0.1825
27	93158	2	49	52.545	10	45	28.34	0.0008	0.2333

DATE  
1971.93336219

SAOSC(G.S.)  
110566

A/A	SAOSC	RA			DEC			DRA	D DEC
		h	m	s	o	'	"	s	"
		2	29	12.176	8	54	44.74	(Asteroid)	
7	110588	2	28	48.560	8	7	38.30	-0.0025	0.1248
18	110546	2	25	50.937	8	24	46.17	-0.0092	-0.0046
28	110537	2	24	43.154	9	58	34.59	-0.0010	0.2363

RESULTS USING SYMMETRICAL DISTRIBUTION OF THE STARS

		2	29	12.171	8	54	44.47	(Asteroid)	
7	110588	2	28	48.561	8	7	38.05	-0.0022	-0.1284
18	110546	2	25	50.944	8	24	46.07	-0.0015	-0.0982
28	110537	2	24	43.158	9	58	34.56	0.0026	0.2067

TABLE 5

DA	MTOD(LMST)		MTOD(GMST)		GMST AT 0 UT		DIFFER.(MST)		DIFFER.(MSL.T)		MH	UT	DT	ET
	h	m	s	h	m	s	h	m	s	m			s	
14	4	17	30.00	4	28	45.50	0	58	59.681	50.016	11	14.040856668	42.07	14.041343590
20	3	37	45.00	3	49	0.50	0	-4	-24.651	36.072	11	19.996945273	42.07	19.997432195
25	5	22	40.00	5	33	55.50	1	20	47.572	34.336	11	25.055952963	42.07	25.056439885
28	1	41	30.00	1	52	45.50	0	-29	-58.878	5.034	10	27.979236501	41.92	27.979721587
7	2	29	30.00	2	40	45.50	-2	-19	-41.093	41.791	12	6.903261470	42.22	6.903750128
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10	0.718707670350													
10	0.718870742657													
10	0.719009253701													
10	0.718240538656													
10	0.719333622269													
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TABLE 6a

GENERAL PRECESSION IN RA=											P=	0.0413435895	1-P=	0.9586564105	E2=	-0.0129383284	F2=	-0.0058783202				
LOCAL SIDER. TIME WRT 1950.0=											4 <sup>h</sup>	16 <sup>m</sup>	54 <sup>s</sup> .1510	07	64°	13'	32 <sup>''</sup> .2645					
XJ=	-0.6273867000	D02=	0.0001931000	Y0=	-0.7019288000	D02=	0.0002146000	Z0=	-0.3043764000	D02=	0.0000930000											
X1=	-0.6137040000	D12=	0.0001890000	Y1=	-0.7117795000	D12=	0.0002178000	Z1=	-0.3086484000	D12=	0.0000948000											
(1-P)X0=	-0.6014482818	(1-P)Y0=				-0.6729085438	(1-P)Z0=				-0.2917923871											
P*X1=	-0.0253727428	P*Y1=				-0.0294275195	P*Z1=				-0.0127606328											
E2*DX02=	-0.0000024984	E2*DY02=				-0.0000027766	E2*DZ02=				-0.0000012033											
F2*DX12=	-0.0000013001	F2*DY12=				-0.0000014982	F2*DZ12=				-0.0000006521											
DX=	-0.0000103054	TOPOCEN CORRECTION				DY=	-0.0000213422	TOPOCEN CORRECTION				DZ=	-0.0000353000	TOPOCEN CORRECT								
X=	-0.6268351285	Y=				-0.7023616802	Z=				-0.3045901752											
LAMDA=	0.7460782869	MI=				0.6448758040	VI=				0.1658384372	TEST=				1.0000000000						

TABLE 6b

P= 0.9974321946		1-P= 0.0025678054		E2= -0.0004279647		F2= -0.0008526411			
GENERAL PRECESSION IN RA= 0		LOCAL SIDER. TIME WRT 1950.0=		3 <sup>h</sup>		37 <sup>m</sup>		9.1242	
								or	
								54°	
								17'	
								16.8635"	
XJ= -0.5571281000		D02= 0.0001714000		Y0= -0.7489702000		D02= 0.0002307000		Z0= -0.3247752000	
X1= -0.5425443000		D12= 0.0001667000		Y1= -0.7576987000		D12= 0.0002338000		Z1= -0.3285598000	
(1-P)X0= -0.0014305966		(1-P)Y0= -0.0019232097		(1-P)Z0= -0.0008339595		(1-P)D02= -0.0000000000		(1-P)D12= -0.0000000000	
P*X1= -0.5411511518		P*Y1= -0.7557530772		P*Z1= -0.3277161224		P*D02= -0.0000000000		P*D12= -0.0000000000	
E2*DX02= -0.0000000734		E2*DY02= -0.0000000987		E2*DZ02= -0.0000000428		E2*DX02= -0.0000000000		E2*DY02= -0.0000000000	
F2*DX12= -0.0000001421		F2*DY12= -0.0000001993		F2*DZ12= -0.0000000865		F2*DX12= -0.0000000000		F2*DY12= -0.0000000000	
DX= -0.0000138340		DY= -0.0000192435		DZ= -0.0000353000		TOPOCEN CORRECTION		TOPOCEN CORRECTION	
X= -0.5425957978		Y= -0.7576958285		Z= -0.3285855113		NI= 0.1618153841		TEST= 1.0000000000	
LAMDA= 0.7578762258		MI= 0.6320121896							

TABLE 6c

P= 0.0564398846 1-P= 0.9435601154 E2= -0.0172505291 F2= -0.0093765829  
 GENERAL PRECESSION IN RA= 0<sup>m</sup> -35<sup>s</sup>.8985 LOCAL SIDER. TIME WRT 1950.0= 5<sup>h</sup> 22<sup>m</sup> 4<sup>s</sup>.1015 or 8<sup>o</sup> 31' 1.5230  
 X0= -0.4672209000 D02= 0.0001424000 Y0= -0.7977810000 D02= 0.0002464000 Z0= -0.3459377000 D02= 0.0001057000  
 X1= -0.4517094000 D12= 0.0001374000 Y1= -0.8050677000 D12= 0.0002483000 Z1= -0.3490969000 D12= 0.0001077000  
 (1-P)X0= -0.4408510063 (1-P)Y0= -0.7527543325 (1-P)Z0= -0.3264130161  
 P\*X1= -0.0254944264 P\*Y1= -0.0454379281 P\*Z1= -0.0197029887  
 E2\*DX02= -0.0000024565 E2\*DY02= -0.0000042505 E2\*DZ02= -0.0000018406  
 F2\*DX12= -0.0000012884 F2\*DY12= -0.0000023282 F2\*DZ12= -0.0000010099  
 DX= -0.0000039047 TOPOCEN CORRECTION DY= -0.0000233761 TOPOCEN CORRECTION DZ= -0.0000353000 TOPOCEN CORRECT  
 X= -0.4663530822 Y= -0.7982222154 Z= -0.3461541554  
 LAMDA= 0.7669421338 MI= 0.6217005866 NI= 0.1590224642 TEST= 1.0000000000



TABLE 6d

P= 0.9797216865 1-P= 0.0202783135 E2= -0.0033783291 F2= -0.0055552226  
GENERAL PRECESSION IN RA= 0<sup>m</sup> -35<sup>s</sup>.7725 LOCAL SIDER. TIME WRT 1950.0= 1<sup>h</sup> 40<sup>m</sup> 54<sup>s</sup>.2275 or 25° 13' 33".4131

XJ= -0.8372295000 DJ2= 0.0002514000 Y0= -0.4914175000 DJ2= 0.0001494000 Z0= -0.2130900000 DJ2= 0.0000547000  
X1= -0.8275451000 DJ2= 0.0002484000 Y1= -0.5045793000 DJ2= 0.0001533000 Z1= -0.2187967000 DJ2= 0.0000665000

(1-P)X0= -0.0169776022 (1-P)Y0= -0.0099651181 (1-P)Z0= -0.0043211058  
P\*X1= -0.8107638811 P\*Y1= -0.4943472828 P\*Z1= -0.2143598719  
E2\*DX02= -0.0000008493 E2\*DY02= -0.0000005047 E2\*DZ02= -0.0000002186  
F2\*DX12= -0.0000016283 F2\*DY12= -0.0000010049 F2\*DZ12= -0.0000004359  
DX= -0.0000214398 TOPOCEN CORRECTION DY= -0.0000101007 TOPOCEN CORRECTION DZ= -0.0000353000 TOPOCEN CORRECT

X= -0.8277654008 Y= -0.5043240112 Z= -0.2187169322

LAMDA= 0.7090725757 MI= 0.6817201390 NI= 0.1802047019 TEST= 1.0000000000



TABLE 7a

T1= C.0870255509      T2= 0.1894827764      T3= C.1024572255

P2	R2
2.3190543576	3.2755845365
2.4478495690	3.4038782071
2.4552741439	3.4112746017
2.4556685960	3.4116675812
2.4556894581	3.411683655
2.4556905612	3.4116894645
2.4556906196	3.4116895226
2.4556906226	3.4116895256
2.4556906228	3.4116895258
2.4556906228	3.4116895258

P1= 2.4317952733	P2= 2.4556906228	P3= 2.4839625653	CCNROL BY 3RD EQUAT= 0.CCCCCCCCCC
R1= 2.4081840523	CC-CRCIN. CF R1=(	2.4411410496	2.2705643879
R2= 2.4116895258	CC-CRCIN. CF R2=(	2.4037053388	2.2097222360
R3= 2.4147061792	CC-CRCIN. CF R3=(	2.3714086323	2.2425031993
	C1= 0.4592340887	C3= 0.5407721780	

C.7078744737 )  
C.7259540325 )  
C.7411600034 )

TABLE 7b

T1= C.C87C227420 T2= C.189477593C T3= C.1C2454851C  
 E1= C.CC09866617 B2= C.CC37348C5C B3= C.CC04993219  
 1+E1+R1 \*-3= 1.CCC0249229 1-B2+R2\*-3= 0.9999C59499 1+B3+R3\*-3= 1.CCCC125407  
 C1= 0.4593318659 C3= 0.5407804224  
 N1= 0.CC2170C659 N3= C.CC22889893

P2	R2
2.3189056063	3.2754363877
2.4477138C20	3.40374255C8
2.4551412236	3.4111421778
2.4555359772	3.4115354575
2.455556862C	3.4115562644
2.4555579667	3.4115573649
2.4555580251	3.4115574231
2.4555580282	3.4115574262
2.4555580284	3.4115574264
2.4555580284	3.4115574264

P1= 2.4216465477	P2= 2.4555580284	P3= 2.4838389573	CONTROL BY 3RD	EQUAT= C.CCCCCCCCCC00
R1= 3.4C8C4C8488	CC-CRCIN. OF R1=(	2.441034C429	2.2704718962	C.7078506883 )
R2= 3.4115574264	CC-CRCIN. OF R2=(	2.4C36048487	2.3096384347	C.7259325767 )
R3= 3.4145833595	CC-CRCIN. OF R3=(	2.3713138321	2.3424263520	C.7411403469 )
C1= C.4593318722		C3= 0.5407804291		

TABLE 7c

T1= C.0870227411  
 B1= C.CCC05866617  
 1+B1\*R1 \*\*--3= 1.CCC0249261  
 T2= 0.1894775910  
 E2= 0.CC37348C49  
 1-B2\*R2\*\*--3= 0.9999059389  
 T3= C.1C24548499  
 E3= C.CC04993219  
 1+E3\*R3\*\*--3= 1.CCC0125420  
 C1= C.4593318724  
 N1= C.CC217CC7C4  
 C3= 0.5407804289  
 N3= C.CC22889870

P2  
 2.3189055251  
 2.4477137708  
 2.455141199C  
 2.4555359531  
 2.4555568380  
 2.4555579427  
 2.4555580011  
 2.4555580042  
 2.4555580043  
 2.4555580044  
 R2  
 3.2754363068  
 3.4037425197  
 3.4111421533  
 3.4115354335  
 3.41155624C4  
 3.411557341C  
 3.4115573992  
 3.4115574C22  
 3.4115574024  
 3.4115574024

P1= 2.4316468245  
 F2= 2.4555580044  
 P3= 2.4838389321  
 CCNTRCL BY 3RD EQUAT= 0.CCCCCCCCCC00  
 R1= 3.4C8C4C8257  
 R2= 3.4115574024  
 R3= 3.4145933345  
 CO-CRCLN. CF R1=0  
 CO-CRCLN. CF R2=0  
 CO-CRCLN. CF R3=0  
 C1= 0.4593318724  
 C3= 0.5407804289  
 2.2704718813  
 2.3096384195  
 2.3424263364  
 C.7C78506844 )  
 C.7259325728 )  
 C.7411403429 )

TABLE 7d

T1= C.C870227411  
 B1= C.CC09866617  
 1+B1\*R1 \*-3= 1.CCC0249261  
 T2= 0.189477591C  
 B2= 0.0037348049  
 1-22\*R2\*-3= 0.9999C59389  
 C1= 0.4593318724  
 N1= 0.0021700704  
 T3= C.1024548499  
 B3= C.CCC4593219  
 1+B3\*R3\*-3= 1.CCC0125420  
 C3= C.5407804289  
 N3= C.002289870

P2  
 2.3189055251  
 2.4477137708  
 2.4551411591  
 2.4555359531  
 2.4555568380  
 2.4555579427  
 2.4555580011  
 2.4555580042  
 2.4555580044  
 2.4555580044  
 R2  
 3.2754363068  
 3.4037425197  
 3.4111421533  
 3.4115354325  
 3.4115562404  
 3.4115573410  
 3.4115573592  
 3.4115574023  
 3.4115574024  
 3.4115574024

P1= 2.4316468245  
 P2= 2.4555580044  
 P3= 2.4838389321  
 CCNTR0L BY 3RC EQUAT= 0.CCCCCCCCC000  
 R1= 3.4080408257  
 R2= 2.4115574024  
 R3= 2.4145833345  
 CO-CRCIN. OF R1=( 2.4410340256  
 CC-CRCIN. OF R2=( 2.4036048305  
 CO-CRCIN. OF R3=( 2.3713138128  
 C1= 0.4593318724  
 C3= C.5407804289  
 C.7078506844 )  
 C.7259325728 )  
 C.7411403430 )

TABLE 8

K1=	4.8266887370	K2=	4.8237461520	K3=	4.8220150392
M1=	0.0000238107	M2=	0.0001130882	M3=	0.0000331005
L1=	0.0000126036	L2=	0.0000598764	L3=	0.0000175355
H1=	0.0000285724	H2=	0.0001356961	H3=	0.0000397197
Y1=	1.0000317460	Y2=	1.0001507485	Y3=	1.0000441309
X1=	0.0000112056	X2=	0.0000531777	X3=	0.0000155621
KS1=	0.0000000000	KS2=	0.0000000002	KS3=	0.0000000000
F1=	0.0000285724	F2=	0.0001356961	F3=	0.0000397197
Y1=	1.0000317460	Y2=	1.0001507485	Y3=	1.0000441309

C1= 0.4593318726      C3= 0.5407804288

TABLE 9a

PARAMETER OF ORBIT IN AU= 3.5993471542  
 ECCENTRICITY= 0.0856201377  
 SEMI-MAJOR AXIS IN AU= 3.6259281371  
 MEAN DAILY MOTION IN SEC= 513.8990251332  
 ECCENTRIC ANOMALY AT T1= 45° 25' 31".272  
 ECCENTRIC ANOMALY AT T3= 47° 5' 47".910  
 MEAN ANOMALY AT T1= 41° 55' 51".106  
 MEAN ANOMALY AT T3= 43° 30' 11".598  
 TEST FOR ECCENTRIC ANOMALIES= 0.0000000000  
 TIME OF PERIHELION PASSAGE=1971-CCICB.-248.7095996920  
 VECTOR ELEMENTS  
 PX= 0.5939709540  
 PY= -0.0549672790  
 PZ= -0.0948701261  
 CX= 0.0855459647  
 CY= 0.5300114809  
 CZ= 0.3574360550  
 TEST FOR PX, PY, PZ= -0.0000000000  
 TEST FOR CX, CY, CZ= 0.0000000000  
 TEST FOR TIME OF PER. PAS. IN SEC= -0.0001029785  
 INCLINATION= 4° 26' 59".743  
 LONGITUDE OF PERIHELION= 355° 0' 33".879  
 TRUE ANOMALY AT T1= 49° 2' 1".429  
 TRUE ANOMALY AT T3= 50° 48' 13".138



TABLE 9b

C1= 0.4593318726 C3= 0.5407804288  
 PARAMETER OF ORBIT IN AU= 3.5993471609  
 ECCENTRICITY= 0.0856201276  
 SEMI-MAJOR AXIS IN AU= 3.6259281375  
 MEAN DAILY MOTION IN SEC= 513.8990250537  
 ECCENTRIC ANOMALY AT T1= 45° 25' 31".254  
 ECCENTRIC ANOMALY AT T3= 47° 5' 47".892  
 ECCENTRIC ANOMALY AT T1= 41° 55' 51".091  
 MEAN ANOMALY AT T3= 43° 30' 11".583  
 TEST FOR ECCENTRIC ANOMALIES= -0.0000000000  
 TIME OF PERIHELION PASSAGE=1971 OCTOB.-248.7095703038  
 VECTOR ELEMENTS  
 PX= 0.9939709624  
 PY= -0.0549671873  
 PZ= -0.0948700914  
 QX= 0.0855458669  
 QY= 0.9300114862  
 QZ= 0.3574360646  
 TEST FOR PX,PY,PZ= -0.0000000000  
 TEST FOR QX,QY,QZ= 0.0000000000  
 TEST FOR TIME OF PER. PAS. IN SEC= -0.0001029838  
 INCLINATION= 4° 26' 59".743  
 LONGITUDE OF PERIHELION= 355° 0' 33".899  
 TRUE ANOMALY AT T1= 49° 2' 1".409  
 TRUE ANOMALY AT T3= 50° 48' 13".118

TABLE 10a

## COEFFICIENTS OF THE SYSTEM FOR LAMDA

-0.1024572255D 00	0.5248741533D-02	-0.1792571650D-03	0.4591547946D-05	0.1179793897D-01
0.8702555087D-01	0.3786723252D-02	0.1098472257D-03	0.2389878832D-05	-0.9065907942D-02
-0.3959529338D 00	0.7838936288D-01	-0.1034616507D-01	0.1024148702D-02	0.4880365017D-01
0.2908241540D 00	0.4228934426D-01	0.4099587589D-02	0.2980647730D-03	-0.2798527239D-01

## DERIVATIVES OF LAMDA

0.1092052282	-0.1186800122	0.0219747054	3.8735437667
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## COEFFICIENTS OF THE SYSTEM FOR MI

-0.1024572255D 00	0.5248741533D-02	-0.1792571650D-03	0.4591547946D-05	-0.1286361442D-01
0.8702555087D-01	0.3786723252D-02	0.1098472257D-03	0.2389878832D-05	0.1031160303D-01
-0.3959529338D 00	0.7838936288D-01	-0.1034616607D-01	0.1024148702D-02	-0.4970794937D-01
0.2908241540D 00	0.4228934426D-01	0.4099587589D-02	0.2980647730D-03	0.3333026223D-01

## DERIVATIVES OF MI

-0.1217862263	0.0779301828	0.0193837956	-4.3177456874
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## COEFFICIENTS OF THE SYSTEM FOR NI

-0.1024572255D 00	0.5248741533D-02	-0.1792571650D-03	0.4591547946D-05	-0.4023053148D-02
0.8702555087D-01	0.3786723252D-02	0.1098472257D-03	0.2389878832D-05	0.2792919904D-02
-0.3959529338D 00	0.7838936288D-01	-0.1034616607D-01	0.1024148702D-02	-0.1838931780D-01
0.2908241540D 00	0.4228934426D-01	0.4099587589D-02	0.2980647730D-03	0.6890707339D-02

## DERIVATIVES OF NI

-0.0355359924	0.0767200078	0.0974547762	-0.6708126409
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TABLE 10b

## COEFFICIENTS OF THE SYSTEM FOR LAMDA

-0.1024542772D 00	0.5248439461D-02	-0.1792416905D-03	0.4591019462D-05	0.1179793897D-01
0.8702304662D-01	0.3786505321D-02	0.1098377430D-03	0.2389603758D-05	-0.9065907942D-02
-0.3959415398D 00	0.7838485147D-01	-0.1034527293D-01	0.1024030823D-02	0.4880365017D-01
0.2908157852D 00	0.4228691046D-01	0.4099233689D-02	0.2980304660D-03	-0.2798527239D-01

## DERIVATIVES OF LAMDA

0.1092083708	-0.1186868428	0.0219766036	3.8739896503
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## COEFFICIENTS OF THE SYSTEM FOR MI

-0.1024542772D 00	0.5248439461D-02	-0.1792416905D-03	0.4591019462D-05	-0.1286361442D-01
0.8702304662D-01	0.3786505321D-02	0.1098377430D-03	0.2389603758D-05	0.1031160303D-01
-0.3959415398D 00	0.7838485147D-01	-0.1034527293D-01	0.1024030823D-02	-0.4970794937D-01
0.2908157852D 00	0.4228691046D-01	0.4099233689D-02	0.2980304660D-03	0.3333026223D-01

## DERIVATIVES OF MI

-0.1217897310	0.0779346680	0.0193854691	-4.3182427142
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## COEFFICIENTS OF THE SYSTEM FOR NI

-0.1024542772D 00	0.5248439461D-02	-0.1792416905D-03	0.4591019462D-05	-0.4023053148D-02
0.8702304662D-01	0.3786505321D-02	0.1098377430D-03	0.2389603758D-05	0.2792919904D-02
-0.3959415398D 00	0.7838485147D-01	-0.1034527293D-01	0.1024030823D-02	-0.1838931780D-01
0.2908157852D 00	0.4228691046D-01	0.4099233689D-02	0.2980304660D-03	0.5890707339D-02

## DERIVATIVES OF NI

-0.0355370151	0.0767244234	0.0974631898	-0.6708898599
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TABLE 11a

D= -0.0085737521    D1= -0.0207046313    D2= -0.0049134399

R0	P0
3.2607642859	2.3041735634
3.3890834856	2.4329993137
3.3966706494	2.4405152232
3.3970838759	2.4410300116
3.3971062759	2.4410524962
3.3971074898	2.4410537148
3.3971075556	2.4410537808
3.3971075592	2.4410537844
3.3971075594	2.4410537846
3.3971075594	2.4410537846

T1= -0.1024572255    T2= 0.0870255509

R0= 3.3971075594    P0= 2.4410537846    POD= 0.2895445400

TABLE 11b

D= -0.0085744923      D1= -0.0207052271      D2= -0.0049137227

R0	P0
3.2606322197	2.3040409552
3.3889355616	2.4323508280
3.3965226249	2.4404655391
3.3969358941	2.4408814705
3.3969582990	2.4409039601
3.3969595134	2.4409051790
3.3969595792	2.4409052451
3.3969595828	2.4409052487
3.3969595830	2.4409052489
3.3969595830	2.4409052489

T1= -0.1024542772      T2= 0.0870230466

R0= 3.3969595830      P0= 2.4409052489      P0J= 0.2896353500

VX	VY	VZ
0.8513106812	-0.4998623236	-0.2167338797
0.8526190684	-0.5007068654	-0.2171000662
0.8526191209	-0.5007067610	-0.2171000209
0.8526191206	-0.5007067615	-0.2171000211

TABLE 12a

ANGULAR MOMENTUM PER UNIT MASS=	0.0327144009
PARAMETER OF ORBIT=	3.6167214268
ECCENTRICITY=	0.1017724504
SEMI-MAJOR AXIS=	3.6545741598
MEAN DAILY MOTION=	507".8686595942
ECCENTRIC ANOMALY AT T2=	46° 9' 39".861
MEAN ANOMALY AT T2=	41° 57' 18".491
TIME OF PERIHELION PASSAGE=1971 OCT08.-246.4007949435	
INCLINATION=	4° 24' 58".794
LONGITUDE OF PERIHELION=	354° 29' 39".821
TRUE ANOMALY AT T2=	50° 31' 49".113

TABLE 12b

ANGULAR MOMENTUM PER UNIT MASS=	0.0327130456
PARAMETER OF ORBIT=	3.6164217803
ECCENTRICITY=	0.1014912555
SEMI-MAJOR AXIS=	3.6540603373
MEAN DAILY MOTION=	507".9757861147
ECCENTRIC ANOMALY AT T2=	46° 6' 39".285
MEAN ANOMALY AT T2=	41° 55' 12".450
TIME OF PERIHELION PASSAGE=1971 OCTOB.-246.0899543072	
INCLINATION=	4° 24' 54".649
LONGITUDE OF PERIHELION=	354° 33' 38".849
TRUE ANOMALY AT T2=	50° 27' 50".643

TABLE 13

X	Y	Z
0.2274998773	-0.3149457117	-0.1920250289
0.1130161927	-0.6523456838	-0.3011631125
-0.6273867000	-0.7019288000	-0.3043764000
1.3513716839	0.3337744155	0.1398889233
-1.3713848860	-4.7290200405	-1.9954407553
4.2196437833	7.4884537959	2.9141278533
-17.8009185607	-4.1940954449	-1.5865002988
-14.0294204168	-24.9932138840	-9.8861673093
2.4412041126	2.2702909762	0.7077673727
0.3189455434	-0.2047799301	-0.1424231127
0.2299592237	-0.6238829608	-0.2957193985
-0.5425443000	-0.7576987000	-0.3285598000
1.3279008667	0.4623310824	0.1765808202
-1.3280906775	-4.7372810920	-2.000375196
4.1881924295	7.5022642976	2.9211876171
-17.7952686682	-4.2161457303	-1.5962671380
-14.0128426261	-25.0010305525	-9.8897745565
2.4034986666	2.3097477130	0.7259831568
0.3568822004	-0.0879134149	-0.0837360264
0.3227003821	-0.5869769185	-0.2849443817
-0.4672209000	-0.7977810000	-0.3459377000
1.3045411575	0.5264849803	0.2066581709
-1.2919335927	-4.7439061716	-2.0037690436
4.1619423619	7.5136845426	2.9270508024
-17.7905419921	-4.2345305901	-1.6044304186
-13.9989829134	-25.0075299020	-9.8928269635
2.3710432317	2.3426973118	0.7412663015



# VELOCITIES OF THE PLANETS

	VX	VY	VZ
	0.674229922440345519	1.24340916807981605	0.5966111165705761753
	1.10741042893800157	0.360746153132148584	0.0926312316198701496
	-0.852644829972549895	0.500442733394442354	0.216972148563807060
	-0.251703919455896930	0.753162100207822038	0.352501012201820479
	0.420001820940074766	-0.0783732513728220559	-0.0439530210773910971
	-0.304955616121567213	0.133217626857053781	0.0683401001313072159
	0.0548306703628411744	-0.213762473478564016	-0.0949134509713257662
	0.161118020193995876	-0.0755889966201690466	-0.0354966747839541002
	-0.368434268679320082	0.379299386151404072	0.175549777167255047

INITIAL TOTAL ENERGY = -0.33213347D-07

	X	Y	Z	C	RA	DEC
1971 Nov. 21	0.24004174D+01	0.23129154D+01	0.72744956D+00	-0.33213349D-07	2 38 58.467	9 17 43.16
	0.23972418D+01	0.23161713D+01	0.72895745D+00	-0.33213352D-07	2 38 39.006	9 16 41.01
	0.23940617D+01	0.23194229D+01	0.73046397D+00	-0.33213354D-07	2 38 19.695	9 15 40.08
Nov. 22	0.23908771D+01	0.23226702D+01	0.73196914D+00	-0.33213356D-07	2 38 0.539	9 14 40.38
	0.23876881D+01	0.23259132D+01	0.73347294D+00	-0.33213358D-07	2 37 41.541	9 13 41.93
Nov. 23	0.23844947D+01	0.23291518D+01	0.73497538D+00	-0.33213360D-07	2 37 22.706	9 12 44.75

	X	Y	Z	C	RA	DEC
	0.23812968D+01	0.23323861D+01	0.73647646D+00	-0.33213363D-07	2 37 4.039	9 11 48.85
Nov. 24	0.23780945D+01	0.23356161D+01	0.73797616D+00	-0.33213365D-07	2 36 45.543	9 10 54.25
	0.23748878D+01	0.23388417D+01	0.73947450D+00	-0.33213367D-07	2 36 27.224	9 10 0.97
25	0.23716766D+01	0.23420630D+01	0.74097146D+00	-0.33213370D-07	2 36 9.084	9 9 9.01
	0.23684611D+01	0.23452800D+01	0.74246704D+00	-0.33213372D-07	2 35 51.128	9 8 18.40
26	0.23652411D+01	0.23484925D+01	0.74396125D+00	-0.33213375D-07	2 35 33.360	9 7 29.15
	0.23620168D+01	0.23517008D+01	0.74545407D+00	-0.33213377D-07	2 35 15.784	9 6 41.27
27	0.23587880D+01	0.23549046D+01	0.74694552D+00	-0.33213380D-07	2 34 58.404	9 5 54.78
	0.23555549D+01	0.23581041D+01	0.74843557D+00	-0.33213383D-07	2 34 41.223	9 5 9.69
28	0.23523174D+01	0.23612992D+01	0.74992424D+00	-0.33213385D-07	2 34 24.246	9 4 26.01
	0.23490756D+01	0.23644899D+01	0.75141152D+00	-0.33213388D-07	2 34 7.475	9 3 43.76
29	0.23458294D+01	0.23676763D+01	0.75289740D+00	-0.33213391D-07	2 33 50.914	9 3 2.94
	0.23425788D+01	0.23708583D+01	0.75438189D+00	-0.33213393D-07	2 33 34.568	9 2 23.57
30	0.23393239D+01	0.23740358D+01	0.75586498D+00	-0.33213396D-07	2 33 18.438	9 1 45.66
	0.23360647D+01	0.23772090D+01	0.75734668D+00	-0.33213399D-07	2 33 2.529	9 1 9.23
Dec. 1	0.23328011D+01	0.23803778D+01	0.75882697D+00	-0.33213402D-07	2 32 46.844	9 0 34.27
	0.23295333D+01	0.23835421D+01	0.76030585D+00	-0.33213405D-07	2 32 31.386	9 0 0.81
Dec. 2	0.23262611D+01	0.23867021D+01	0.76178333D+00	-0.33213407D-07	2 32 16.158	9 59 28.84

APPENDIX A-1

Proof of the convergence of the  
series (3.37) (Chapter 3)

The Functions

$$\alpha_i = \alpha_i(\tau), \beta_{ijk} = \beta_{ijk}(\tau), \gamma_{ijk} = \gamma_{ijk}(\tau), \delta_{ijk} = \delta_{ijk}(\tau), \chi_i = \chi_i(\tau), \chi'_i = \chi'_i(\tau) \quad (i, j, k=1, \dots, n)$$

$$\alpha_{ij} = \alpha_{ij}(\tau), \quad b_{ij} = b_{ij}(\tau) \quad (i, j=1, \dots, n \quad i \neq j), \quad (\text{A-1.1})$$

possess first order derivatives with respect to  $\tau$  in any closed interval  $[-\tau_1, \tau_1]$ , as was mentioned previously. Hence, according to the theorem 1 (Chapter 3) the functions (A-1.1) are continuous in this interval, which is closed and obviously bounded. Therefore, the functions (A-1.1) are bounded in this range. (H. S. W. Massey, p 49-50)

Let us take

$$B = \max \left\{ \begin{array}{l} \text{absolute values of the upper and lower bounds} \\ \text{of the functions (A-1.1) in the interval } [-\tau_1, \tau_1] \end{array} \right\}$$

and

$$A = \max \left\{ B, (1+m_i), m_i \quad (i=1, \dots, n) \right\}. \quad (\text{A-1.2})$$

The right hand side of the relation

$$\chi''_i = \left[ -(1+m_i)\alpha_i - \sum_{\substack{j=1 \\ j \neq i}}^n m_j \alpha_{ij} \right] \chi_i + \sum_{\substack{j=1 \\ j \neq i}}^n m_j (\alpha_{ij} - \alpha_j) \chi_j \quad (i=1, \dots, n) \quad (\text{A-1.3})$$

contains  $(3n-2)$  products, with three factors in each one.

Interpreting  $F_1, F_2, \dots, F_n, \dots$  as representing any one of the functions (A-1.1) and the factors  $(1+m_i), m_i, (i=1, \dots, n)$ , the products which appear in the relation (A-1.3) have the general form

$$F_1 \cdot F_2 \cdot F_3 \quad (\text{A-1.4})$$

Clearly, in the interval  $[-\tau_1, \tau_1]$ , the following general relation is valid

$$|F_1 \cdot F_2 \cdot F_3| \leq A^3,$$

hence

$$\chi_i''(\tau) \ll (3n-2) A^3 \equiv \alpha_2 \quad (i=1, \dots, n) \quad \tau \in [-\tau_1, \tau_1] \quad (A-1.5)$$

Since the second order derivative  $\chi_i''(\tau)$  ( $i=1, \dots, n$ ) contains  $(3n-2)$  products of the form (A-1.4), the third order derivative  $\chi_i^{(3)}(\tau)$  ( $i=1, \dots, n$ ) will contain  $(3n-2) \cdot 3$  products of the general form

$$F_1 \cdot F_2 \cdot F_3', \quad (A-1.6)$$

where  $F_3' \equiv dF_3/d\tau$  and the meaning of  $F_1, F_2, F_3$  is the same as above.

We define,

$\theta \equiv$  maximum number of products which appear in the right members of the relations (3.26),

$\mu \equiv$  maximum number of factors of these products.

From the equations (3.26), (A-1.3) and the definition of  $F_3$  it is evident that the derivative  $F_3'$  will be either zero or a sum of  $\theta$  products, at most, and every one of them will contain, at most,  $\mu$  factors.

It is obvious now that the function  $\chi_i^{(3)}(\tau)$  will be represented by a sum of  $(3n-2) \cdot 3 \cdot \theta$  products, at most, of the general form

$$F_1 \cdot F_2 \cdots F_v,$$

where  $v \leq \mu+2$ .

In the interval  $[-\tau_1, \tau_1]$  the relation

$$|F_1 \cdot F_2 \cdots F_v| \ll A^{\mu+2}$$

is valid, since  $v \leq \mu+2$ . Hence

$$|\chi_i^{(3)}(\tau)| \ll (3n-2) 3 \theta A^{\mu+2} \equiv \alpha_3 \quad (i=1, \dots, n) \quad \tau \in [-\tau_1, \tau_1].$$

Working as above we obtain the relations

$$|\chi_i^{(4)}(\tau)| \ll (3n-2) 3 \theta^2 (\mu+2) A^{2\mu+1} \equiv \alpha_4,$$

$$|\chi_i^{(5)}(\tau)| \ll (3n-2) 3 \theta^3 (\mu+2)(2\mu+1) A^{3\mu} \equiv \alpha_5,$$

(A-1.7)

$$|\chi_i^{(v)}(\tau)| \ll (3n-2) 3 \theta^{v-2} (\mu+2)(2\mu+1) \cdots (v(\mu-1)-3\mu+6) A^{v(\mu-1)-2\mu+5} \equiv \alpha_v,$$

( $i=1, \dots, n$ )  $\tau \in [-\tau_1, \tau_1]$ .

At the point  $\tau = 0$  we have  $\chi_{i0}^{(\nu)} \equiv \chi_{i0}^{(\nu)}$  ( $i=1, \dots, n$ )  $\nu \gg 0$ ,  
hence

$$|\chi_{i0}| \leq A,$$

$$|\chi'_{i0} \tau| \leq A |\tau|, \quad (\text{A-1.8})$$

$$\left| \chi''_{i0} \frac{\tau^2}{2!} \right| \leq (3n-2) A^3 \frac{|\tau^2|}{2!} \equiv \alpha_2 |\tau^2| / 2!,$$

$$\left| \chi^{(3)}_{i0} \frac{\tau^3}{3!} \right| \leq (3n-2) 3\theta A^{\mu+2} \frac{|\tau^3|}{3!} \equiv \alpha_3 |\tau^3| / 3!,$$

$$\left| \chi^{(\nu)}_{i0} \frac{\tau^\nu}{\nu!} \right| \leq (3n-2) 3\theta^{\nu-2} (\mu+2) \dots (\nu(\mu-1)-3\mu+6) A^{\nu(\mu-1)-2\mu+5} \equiv \alpha_\nu \frac{|\tau^\nu|}{\nu!},$$

$$(i=1, \dots, n) \quad \tau \in [-\tau_1, \tau_1].$$

We form the series

$$\sum_{\nu=2}^{\infty} \alpha_\nu \frac{|\tau^\nu|}{\nu!}, \quad (\text{A-1.9})$$

and we take the limit of the ratio of two successive terms of it

$$\lim_{\nu \rightarrow \infty} \frac{\alpha_{\nu+1} \frac{|\tau^{\nu+1}|}{(\nu+1)!}}{\alpha_\nu \frac{|\tau^\nu|}{\nu!}} = |\tau| \lim_{\nu \rightarrow \infty} \frac{\alpha_{\nu+1}}{\alpha_\nu (\nu+1)} =$$

$$= |\tau| \lim_{\nu \rightarrow \infty} \frac{(3n-2) 3\theta^{\nu-1} (\mu+2) (2\mu+1) \dots (\nu(\mu-1)-3\mu+6) (\nu(\mu-1)-2\mu+5) A^{\nu(\mu-1)-\mu+4}}{(\nu+1) (3n-2) 3\theta^{\nu-2} (\mu+2) (2\mu+1) \dots (\nu(\mu-1)-3\mu+6) A^{\nu(\mu-1)-2\mu+5}} =$$

$$= |\tau| \lim_{\nu \rightarrow \infty} \frac{\theta (\nu(\mu-1)-2\mu+5) A^{\mu-1}}{(\nu+1)} =$$

$$|\tau| \theta A^{\mu-1} \left[ \lim_{v \rightarrow \infty} \frac{v(\mu-1)}{v+1} + \lim_{v \rightarrow \infty} \frac{-2\mu+5}{v+1} \right] =$$

$$= |\tau| \theta A^{\mu-1} (\mu-1).$$

We can choose the interval  $[-\tau_1, \tau_1]$  such that

$$|\tau| \theta A^{\mu-1} (\mu-1) < 1.$$

In this interval the series (A-1.9) converges (ratio test). Hence the convergence of the series

$$\sum_{v=0}^{\infty} \left| \chi_{i0}^{(v)} \frac{\tau^v}{v!} \right| \quad (i=1, \dots, n) \quad \tau \in [-\tau_1, \tau_1], \quad (\text{A-1.10})$$

follows immediately from the relations (A-1.8). We interpret  $\chi_{i0}^{(0)}$  to mean  $\chi_{i0}$ .

The convergence of the series

$$\sum_{v=0}^{\infty} \chi_{i0}^{(v)} \frac{\tau^v}{v!} \quad (i=1, \dots, n), \quad (\text{A-1.11})$$

in the interval  $[-\tau_1, \tau_1]$  follows as a result of the convergence of the series (A-1.10)

With a similar process we can prove that the series

$$\sum_{v=0}^{\infty} y_{i0}^{(v)} \frac{\tau^v}{v!} \quad (i=1, \dots, n), \quad (\text{A-1.12})$$

$$\sum_{v=0}^{\infty} z_{i0}^{(v)} \frac{\tau^v}{v!} \quad (i=1, \dots, n), \quad (\text{A-1.13})$$

converge.

The common interval of convergence of the series (A-1.11), (A-1.12) and (A-1.13) is the interval of convergence of the series (3.37).

## APPENDIX A-2

### Determination of the mass of the asteroid

#### Use of the total energy of the system to test the accuracy of the numerical applications

The problem which arises in the numerical application of the power series method concerns the determination of the mass of the asteroid.

A first estimation can be obtained by using the relation

$$\log p = 5.94 - 2 \log R - 0.4 B(1,0)$$

where  $p$  is the albedo factor, with probable value 0.16,  $R$  the radius of the asteroid in Km and  $B(1,0)$  its absolute magnitude, given in the Ephemeris for the Minor Planets.

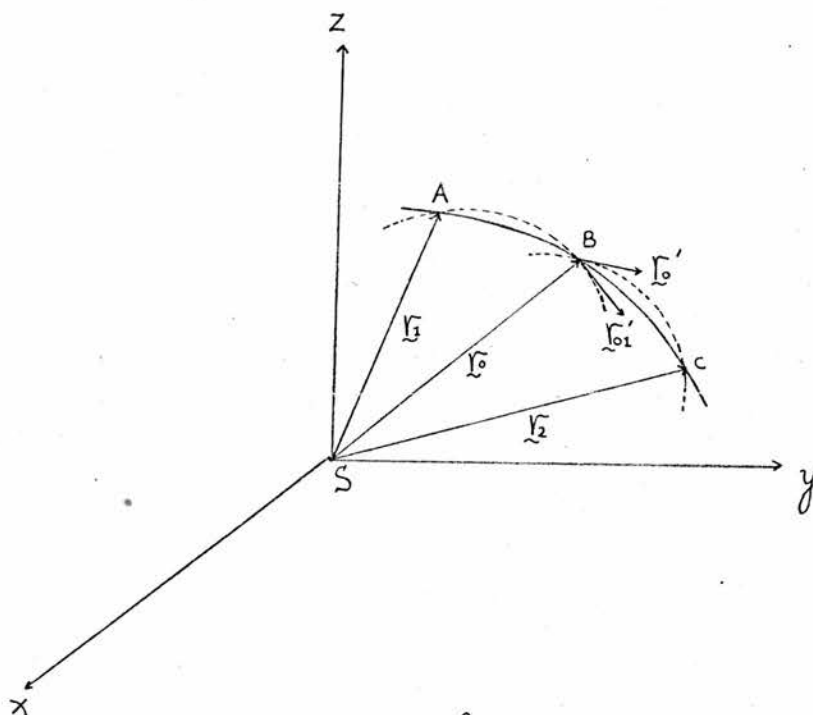
With probable density  $3,5 \text{ gr cm}^{-3}$ , and considering the shape of the asteroid as spherical, a value equal to  $0.97 \cdot 10^{-13}$  solar masses, is obtained for the mass of the asteroid.

Although this value is satisfactory, because the mass of the asteroid is very small compared with the masses of the planets, we calculated the mass of the asteroid as follows:

Consider three points on the real orbit of the asteroid A, B, C at three instants  $t_1, t_0, t_2$  and the position vectors  $\underline{r}_1, \underline{r}_0, \underline{r}_2$ . The use of the relation (3.44) twice for the values  $\underline{r}_1, \underline{r}_0, t_1, t_0$  and  $\underline{r}_0, \underline{r}_2, t_0, t_2$  gives two velocity vectors  $\underline{r}'_0$  and  $\underline{r}'_{01}$  at the point B, which must be the same.

The path of the asteroid in space depends on its mass, hence values of the mass different from the true value will give either a more curved or less curved path (fig. 1), hence the two velocity vectors  $\underline{r}'_0$  and  $\underline{r}'_{01}$  will not be the same.

The mass which gives the same values for the vectors at point B is the true mass of the asteroid.



(fig. 1)

This method gives a mass equal to  $1.10^{-13}$  solar masses.

Another problem which arises in the power series method concerns the checks during the calculation. Here, the total energy of the system was used as a check.

We notice that the velocity of the Sun (origin of the co-ordinate system) is very nearly constant since the centre of mass of the system is inside the Sun, hence the value of the total energy must be very nearly constant.

Another test of the accuracy of the calculations, used in the numerical application, is provided by the mass of the minor planet calculated from the solution of the equations of motion. This should, of course, be constant.



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